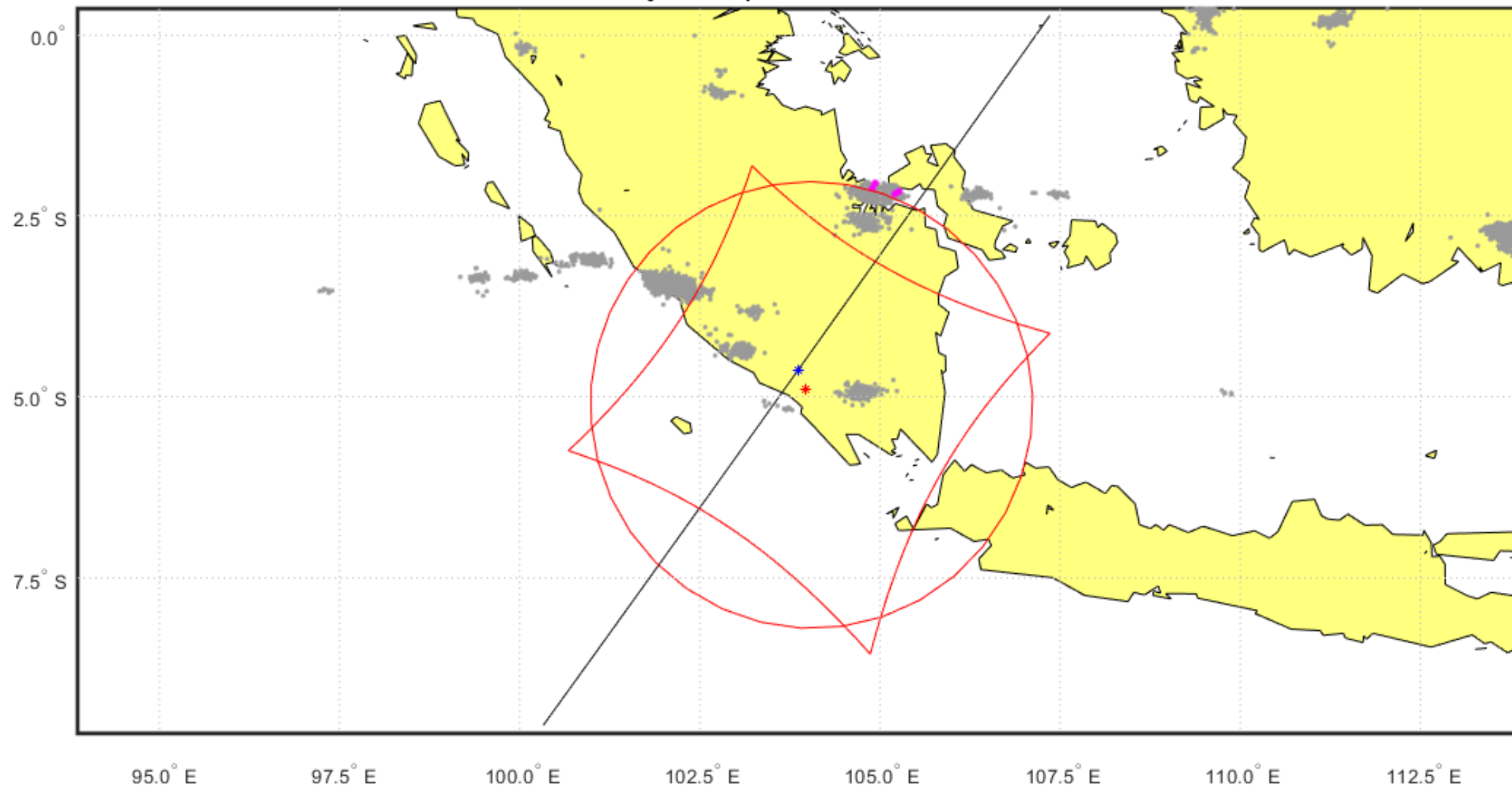


TGF-210510-12:51:32-31285
yaw = -4° pitch = -3° roll = 1.1°



TGF-210510-12:51:32-31285
yaw = -4° pitch = -3° roll = 1.1°

