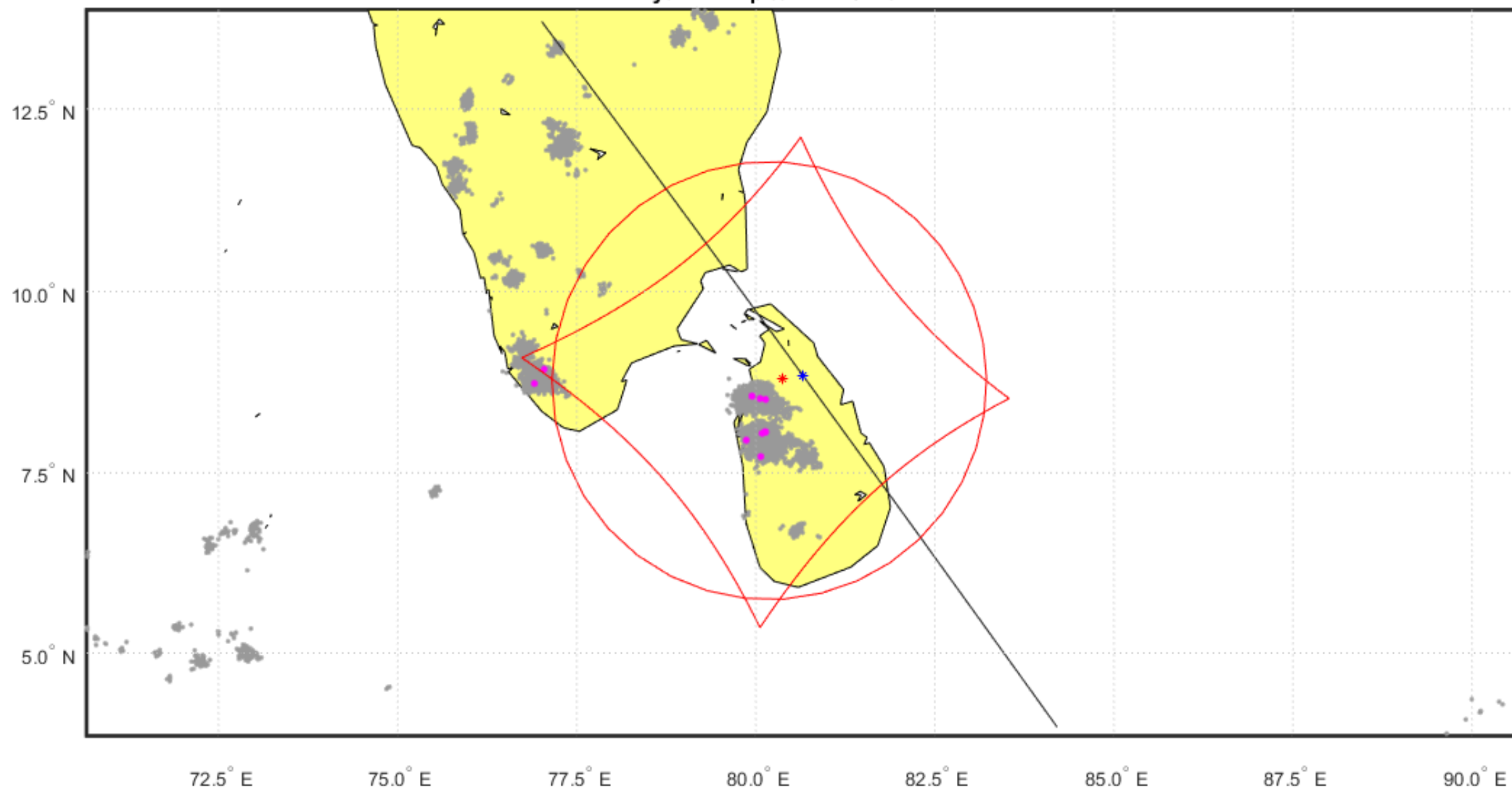


TGF-190418-12:15:18-31977
yaw = -4° pitch = -2.3° roll = 1°



TGF-190418-12:15:18-31977
yaw = -4° pitch = -2.3° roll = 1°

