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Bridging Weather and Climate: Subseasonal-to-Seasonal (S2S) Prediction

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Key Points:
- High-top models have more skill in the stratosphere and the troposphere compared to low-top models
- Extreme stratospheric events are predictable at 1- to 2-week lead times in S2S models
- SSW events tend to be less predictable than strong vortex events or final warming events

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The Role of the Stratosphere in Subseasonal to Seasonal Prediction: 1. Predictability of the Stratosphere

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Abstract The stratosphere has been identified as an important source of predictability for a range of processes on subseasonal to seasonal (S2S) time scales. Knowledge about S2S predictability within the stratosphere is however still limited. This study evaluates to what extent predictability in the extratropical stratosphere exists in hindcasts of operational prediction systems in the S2S database. The stratosphere is found to exhibit extended predictability as compared to the troposphere. Prediction systems with higher stratospheric skill tend to also exhibit higher skill in the troposphere. The analysis also includes an assessment of the predictability for stratospheric events, including early and midwinter sudden stratospheric warming events, strong vortex events, and extreme heat flux events for the Northern Hemisphere and final warming events for both hemispheres. Strong vortex events and final warming events exhibit higher levels of predictability as compared to sudden stratospheric warming events. In general, skill is limited to the deterministic range of 1 to 2 weeks. High-top prediction systems overall exhibit higher stratospheric prediction skill as compared to their low-top counterparts, pointing to the important role of stratospheric representation in S2S prediction models.

1. Introduction

The winter stratosphere is dominated by strong westerly circumpolar winds in the extratropics of both hemispheres, which exhibit maximum variability from December-March in the Northern Hemisphere (NH) and from October-December in the Southern Hemisphere (SH) (Plumb, 1989; Thompson & Wallace, 2000). This variability, which is larger in the NH, is linked to dynamical extreme events. The most prominent events are so-called *major sudden stratospheric warming* (SSW) events. These occur in the polar NH on average every second winter (Butler et al., 2017; Charlton & Polvani, 2007) and are associated with a disruption of the polar vortex, reversing the climatological westerly winds to easterlies in midwinter. Temperatures at a height of 30 km can increase by around 50 °C within a few days during these events, and the troposphere tends to respond with an anomalously persistent negative signature of the Northern Annular Mode and the North Atlantic Oscillation (NAO) (Baldwin & Dunkerton, 2001; Charlton-Perez et al., 2018; Domeisen, 2019; Karpechko et al., 2017). In the SH, only one major SSW event has been observed to date, in September 2002 (e.g. Charlton et al., 2005; Newman & Nash, 2005; Taguchi, 2014). In addition, minor

stratospheric warming events in the SH can also significantly impact the Southern Annular Mode (SAM) and the associated surface climate (e.g. Lim et al., 2018).

In the NH, the polar vortex can also significantly weaken early in the season. *Early winter weak vortex events* occur before wind speeds peak in the stratosphere, are strongly influenced by the transient development of the vortex into winter, and can precondition the vortex for midwinter variability for both the NH (Albers & Birner, 2014; Ayarzagüena et al., 2011; Limpasuvan et al., 2004) and SH (Ivy et al., 2017). Early vortex weakening events can potentially influence early winter surface climate, for example, in NH winter 2016/2017 (Tyrrell et al., 2019), despite the fact that they generally do not meet the criteria for major midwinter SSWs. These events can exhibit zonal wind speeds of less than 10 ms^{-1} for more than a week at 60°N and 10 hPa and can exhibit easterly zonal mean winds at latitudes poleward of 60°N, which can lead to similar surface impacts as major SSWs (Butler & Gerber, 2018).

Occasionally, the vortex strengthens significantly in so-called *strong polar vortex* events (e.g. Limpasuvan et al., 2005) in boreal winter or austral spring. Strong polar vortex events occur when the winter polar vortex intensifies significantly above climatology, and these events generally have opposite impacts to midwinter SSWs on surface weather (i.e., in the NH [SH], the surface influence projects onto the positive phase of the NAO [SAM]). Strong vortex events have been found to increase surface predictability (Tripathi, Charlton-Perez, et al., 2015).

In addition, shorter-lived events, so-called *wave reflection* and *negative heat flux events* can also impact the entire atmospheric column and often precede strong vortex events (Dunn-Sigouin & Shaw, 2015; Perlwitz & Harnik, 2003). Extreme stratospheric wave 1 negative heat flux events are coupled with significant changes in the tropospheric circulation, in particular, they are followed by a poleward shift of the North Atlantic jet consistent with a positive phase of the NAO (Dunn-Sigouin & Shaw, 2015; Lubis et al., 2016; Shaw et al., 2014; Shaw & Perlwitz, 2013). The tropospheric response following negative heat flux events can be reproduced in dry dynamical core experiments if the stratosphere is nudged to the observed event evolution and the troposphere is freely evolving (Dunn-Sigouin & Shaw, 2018).

At the end of winter, the polar vortex collapses to easterlies in a *final stratospheric warming* event in spring (Black et al., 2006; Black & McDaniel, 2007). While final warmings are typically induced by the radiative relaxation of the equator-to-pole temperature gradient as sunlight returns to the pole, they can also be dynamically induced by wave breaking in a manner similar to midwinter SSWs (Hardiman et al., 2011; Hu, Ren, & Xu, 2014; Hu, Ren, Yu, & Xu, 2014). Final warmings can exhibit different surface impacts than midwinter SSWs in the NH (Ayarzagüena & Serrano, 2009; Hardiman et al., 2011). In the SH, the downward impact of the final warming tends to manifest in the tropospheric SAM (e.g., Gerber et al., 2010; Lim et al., 2018; Seviour et al., 2014; Son et al., 2013; Thompson & Solomon, 2005), which drives variations in surface climate throughout the SH (Bandoro et al., 2014; Lim et al., 2018). This indicates that a skillful prediction of the SH stratospheric polar vortex in spring can provide an early warning for the polarity of the surface SAM and associated SH climate in spring to summer, beyond the SAM's typical 2-week decorrelation time scale (Marshall et al., 2011).

The above described extreme events in the stratosphere remain difficult to predict deterministically despite significant progress in stratospheric representation, including higher model lids and increased stratospheric resolution (e.g. Butler et al., 2016). In idealized dynamical core models in ensemble mode, SSWs can on average be deterministically predicted 10 days in advance (Gerber et al., 2009). For more complex prediction systems, these predictive lead times are similar (Tripathi et al., 2016; Tripathi, Baldwin, et al., 2015) but can vary widely between different SSW events (Karpechko, 2018; Marshall & Scaife, 2010; Noguchi et al., 2016; Taguchi, 2016; Taguchi, 2018).

Given the influence of the stratosphere on surface weather during NH winter and SH spring and the implied added predictability on subseasonal to seasonal (S2S) time scales (e.g. Baldwin et al., 2003; Scaife et al., 2016), it is crucial to understand the dynamics and predictability of the stratosphere itself. Due to the different mechanisms for the above described events, there are reasons to expect different time scales of vortex evolution—and hence different predictability—for example, during weak versus strong vortex events (Limpasuvan et al., 2004; Limpasuvan et al., 2005) in addition to the different surface impacts previously mentioned. Only recently, via the World Climate Research Program and World Weather Research Program S2S project, an intercomparison of a large number of state-of-the-art operational S2S prediction

Table 1
Details of the Prediction Systems Considered in This Study, Based on the Data Available at the Time of Analysis

Prediction system	Initialization	Hindcast period	Ensemble size
BoM	ERA-interim/ALI	1981–2013	33
CMA	NCEP-NCAR R1	1994–2014	4
ECCC	ERA-interim	1995–2014	4
ECMWF$^{\times}$	ERA-interim	1997–2016	11
JMA$^{\times}$	JRA-55	1981–2010	5
CNRM-Meteo$^{\times}$	ERA-interim	1993–2014	15
CNR-ISAC	ERA-interim	1981–2010	1
NCEP$^{\times}$	CFSR	1999–2010	4
UKMO$^{\times}$	ERA-interim	1993–2015	2–7

Note. "×" indicates high-top models throughout this study, here referring to a top model level above 0.1 hPa and a stratospheric resolution with several levels above 1 hPa. ALI refers to the BoM data assimilation scheme. Differing numbers of ensemble members for UKMO were used in this study, depending on the members available at the time of data acquisition for each section.

systems with stratospheric output has been made possible. Here, we evaluate the predictability of the extratropical stratosphere of both hemispheres using this database, while the second part of this study (Domeisen et al., 2019, hereafter Part 2) investigates the influence of the stratosphere on the predictability of surface climate with a focus on the NH. Section 2 describes the S2S database and our methodology, including the definition of stratospheric extreme events (section 2.3). Section 3 evaluates the predictability of the winter stratosphere relative to the troposphere, while section 4 considers the predictability of stratospheric extreme events. Section 5 provides a summary and discussion of the results.

2. Methodology

2.1. Data

The focus of this study will be the analysis of hindcasts from the S2S forecast project database (Vitart et al., 2017). The database is a repository of forecast and hindcast data from 11 different operational subseasonal forecast systems. The focus of this study is on the hindcast data, since it spans a broad range of different stratospheric states, at the expense of the large ensemble sizes characteristic of the real-time forecasts. Nine of the 11 systems are analyzed in detail in this study. Two models (KMA and HMCR) had to be excluded due to data issues. Table 1 lists the model systems included in our analysis along with specific details of each system and its output availability. The hindcast period differs substantially between different ensemble prediction systems due to their operational strategy. For the majority of the analysis in this study, the period 1996–2010, over which hindcasts are available for most prediction systems, is used. Not all analyses in this study are able to employ all prediction systems, for example, due to the differing length of the hindcasts or the different time periods for which hindcasts are available; hence, different sections may use a more limited set of models or a different hindcast period depending on the specific requirements of a particular analysis. An effort has been made to include as many models as possible into every analysis. Exceptions to the data listed in Table 1 will be noted.

There are several ways in which the design of the prediction systems is important to consider when thinking about their ability to forecast the stratosphere. Of primary importance are the vertical resolution of the atmospheric model component and the height of the model top level. Figure 1 shows the spacing of model levels for the nine systems considered. The prediction systems are divided into two broad groups, that is, high-top models (as defined in Table 1), which fully represent the stratosphere (ECMWF, UKMO, JMA, NCEP, and CNRM-Meteo), and low-top models (ECCC, CMA, CNR-ISAC, and BoM). Note that the prediction systems are initialized with different reanalysis products in the atmosphere, that is, JRA-55 (Kobayashi et al., 2015), ERA-Interim (Dee et al., 2011), NCEP-NCAR R1 (Kalnay et al., 1998), and CFSR (Saha et al., 2010) as indicated in Table 1. This may lead to differences in the models' performance in the stratosphere. The detailed performance of different reanalysis products in the stratosphere has been reviewed by the SPARC Reanalysis Intercomparison Project (e.g. Long et al., 2017). In this study, we verify all hindcasts against

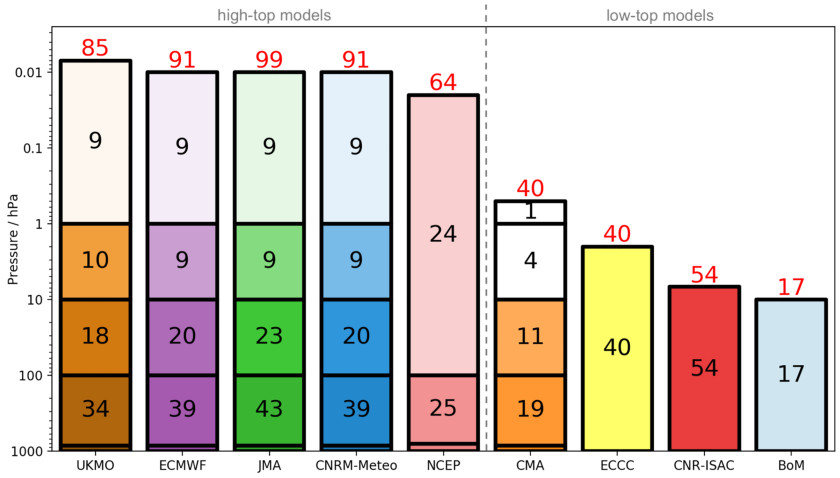

Figure 1. Schematic representation of model vertical resolution for all S2S prediction systems used in this study. Each block represents the pressure range indicated on the *y* axis. The number of model levels in each range is shown numerically. The shading in each box is proportional to the average level spacing (in kilometers) in that region of the atmosphere. The red number at the top of each bar shows the total number of levels in each model. The dashed line indicates the separation between high- and low-top models (see Table 1).

ERA-Interim reanalysis. While this could be biased against systems initialized with a different reanalysis, in most cases, sampling variability will be much larger than variability between reanalysis products (Gerber & Martineau, 2018).

2.2. Skill Measures

In this study, skill is evaluated according to a range of measures that are commonly used in the literature. One common metric is the *correlation coefficient r* given by

$$r = \frac{\sum_{t=1}^{T}(X_{\mathrm{mod}} - C_{\mathrm{mod}})(X_{\mathrm{obs}} - C_{\mathrm{obs}})}{\sqrt{\sum_{t=1}^{T}(X_{\mathrm{mod}} - C_{\mathrm{mod}})^2 \cdot \sum_{t=1}^{T}(X_{\mathrm{obs}} - C_{\mathrm{obs}})^2}}, \tag{1}$$

where X is a time-dependent variable and the subscripts mod and obs denote the model ensemble mean and the reanalysis data set, respectively. C_{mod} is the lead time-dependent model climatology, over the same period of time as the observed climatology C_{obs}. T is the number of events or time steps for which r is evaluated.

To evaluate the spatial skill of the anomaly pattern, we use the *anomaly correlation coefficient* (e.g., Table 2 and Figures 2 and 3):

$$ACC = \frac{\sum_{t=1}^{T}\sum_{s=1}^{S} w \cdot (X_{\mathrm{mod}} - C_{\mathrm{mod}})(X_{\mathrm{obs}} - C_{\mathrm{obs}})}{\sqrt{\sum_{t=1}^{T}\sum_{s=1}^{S} w \cdot (X_{\mathrm{mod}} - C_{\mathrm{mod}})^2 \cdot \sum_{t=1}^{T}\sum_{s=1}^{S} w \cdot (X_{\mathrm{obs}} - C_{\mathrm{obs}})^2}}. \tag{2}$$

Spatial weighting by the cosine of latitude w and spatial averaging over S grid spaces is applied as an additional summation over the covariance and variance terms separately. This formulation of the ACC allows an *a posteriori* removal of systematic errors in the model hindcasts. In this study, the ACC and r are computed for the ensemble mean for each prediction system as a function of forecast lead time. The multimodel mean is the averaged correlation from all prediction systems. A skill level of 0.6 is used as a threshold to compare the different models, consistent with other studies of seasonal and subseasonal predictability.

A further measure that has recently been introduced by Eade et al. (2014) is the *ratio of predictable components* (RPC), a property of ensemble hindcasts comparing the size of a predicted signal to that expected from their correlation coefficient:

$$RPC = \frac{r \cdot \sigma_{tot}}{\sigma_{mod}}, \tag{3}$$

with r as defined in equation (1). σ_{mod} is the standard deviation of the model ensemble mean, and σ_{tot} is the total variance in the ensemble, where σ_{tot} uses all ensemble members and start dates for each lead time.

Thereby, the RPC is the ratio of the correlation coefficient multiplied by the standard deviation across all years and ensemble members (the variability we would expect the ensemble mean to contain given the correlation) to the standard deviation of the year-to-year variations in the ensemble mean (the variability we actually obtain from the system). RPC = 1 indicates that a forecast system perfectly reflects the predictability of the observed system. Eade et al. (2014) showed that we expect an ensemble prediction system that is overconfident to have RPC < 1 and one that is underconfident to have RPC > 1. For RPC > 1, the system has less ensemble mean amplitude than expected by the correlation of the ensemble mean with the observations (i.e., the ACC). This is found for many prediction systems on seasonal time scales and likely reveals deficiencies in the model (e.g., O'Reilly et al., 2018).

2.3. Classification of Stratospheric Events

We investigate the predictability of extreme events in the polar stratosphere in section 4. Here we briefly describe how we classify these stratospheric events.

Early winter weak vortex event. Weak (i.e., less than -1σ from the ERA-interim daily climatological mean) zonal mean zonal winds at 60°N and 10 hPa that persist for at least a week beginning in the month of November. There are four of these events in the 1996–2010 period in ERA-interim.

Strong polar vortex event. Strong polar vortex events are defined as periods when zonal mean zonal winds at 60°N and 10 hPa exceed a threshold value. Following Tripathi, Baldwin, et al. (2015), we use the 80th percentile of ERA-Interim November to March winds over the 1980–2012 period, which is 41.2 m/s. We define the start of the event as the date when the winds exceed the threshold for the first time. This condition is set to ensure that the forecasts are not initiated during a strong polar vortex. An event must last for at least 2 days, and events must be separated by at least 30 days. During the period 1996–2010, there are 12 strong polar vortex events.

Midwinter SSW event. Though there are several possible definitions for a SSW event (Butler et al., 2015), here we base our analysis on zonal mean zonal wind reversals at 60°N and 10 hPa (Charlton & Polvani, 2007), as listed in Table 2 of Butler et al. (2017) for ERA-Interim (December-February [DJF] events only). During the 1996–2010 period, there are 11 midwinter SSW events.

Negative heat flux events. Negative heat flux events are defined by extreme values of the daily zonal mean wave 1 meridional heat flux ($\overline{v'T'}_{k=1}$, where k denotes the zonal wave number) computed from daily mean values of the meridional wind v and temperature T and averaged from 60–90°N at 50 hPa during January-March, as in Dunn-Sigouin and Shaw (2015). Negative events are identified when the 5-day running mean high latitude heat flux drops below the fifth percentile of the climatological distribution from reanalysis (-13.5 K ms^{-1}). The central date of the events is defined at the day of minimum high latitude heat flux, and events must be separated by a minimum of 15 days. Ten events are identified from 1996–2010 (Table 1 in Dunn-Sigouin and Shaw, 2015).

Final stratospheric warming events. The final warming is defined as the last date prior to 30 June (31 December) of each year when the ERA-Interim daily mean zonal mean zonal winds at 10 hPa and 60° latitude in the NH (SH) turn easterly and do not return to westerly for more than 10 consecutive days (Butler & Gerber, 2018). The final warming typically occurs around mid-April in the NH and mid-November in the SH at the 10 hPa level. This same definition is used for model runs initialized between 1 February (1 September for the SH) and the date of the observed final warming. Note that if the zonal wind reverses less than 10 days from the end of the forecast, it is counted as a predicted final warming, although the criterion of not returning to westerlies cannot be evaluated in this case. Because there is a final warming every spring, there are 14 observed events from 1997–2010. The climatological mean final warming date from ERA-Interim (over the longer 1981–2016 period) is 15 April in the NH and 20 November in the SH.

3. Evaluation of the Baseline Prediction Skill in the Stratosphere and the Troposphere

The main purpose of this study is to investigate how well the prediction systems in the database simulate the predictability in the stratosphere and troposphere on subseasonal time scales. As a first step, we characterize the baseline skill present in the prediction systems in the stratosphere and troposphere.

The stratosphere and the troposphere have different characteristics when it comes to persistence and predictability. Large-scale variability in the stratosphere has significantly longer decorrelation time scales than the troposphere (Baldwin et al., 2003; Gerber et al., 2008, 2010; Simpson et al., 2011). The extent to which the decorrelation time scale is determined primarily by radiative time scales or a combination of radiative and dynamical processes is uncertain (Charlton-Perez & O'Neill, 2010; Hitchcock et al., 2013). The longer decorrelation time scales in the stratosphere result in enhanced prediction skill at subseasonal time scales in the stratosphere compared to the skill in the troposphere (Zhang et al., 2013).

Table 2 and Figure 2 show the prediction skill (equation (2)) at 50 and 500 hPa (defined here by the ACC, see equation (2)), characterizing the model predictability in the middle stratosphere and the middle troposphere, respectively. The ACC decreases more slowly in the stratosphere than in the troposphere. All the prediction systems, even those with a poor stratospheric representation, are able to capture the enhanced prediction skill in the stratosphere compared to the troposphere. The predictability limit is defined as the day when the ACC drops below 0.6. In the troposphere, the daily ACC drops below 0.6 typically at lead times of 6–8 days in both hemispheres regardless of the season. In the stratosphere of both hemispheres, the predictability limit extends to 12 days or longer in DJF. Although the stratospheric predictability limit is shorter in boreal summer, it is still longer than tropospheric predictive time scales. The only exception is BoM in boreal summer, which shows comparable prediction skills for the stratosphere and the troposphere. This is likely caused by an unrealistic stratosphere in this prediction system (Lim et al., 2019). There is notable variation in the stratospheric prediction skill among the prediction systems, with those with little stratospheric variation such as BoM and CMA having reduced prediction skill as compared to the multimodel average. In particular, the average of the high-top models (indicated by ×) for DJF in the NH is 18 days, while it is 13.6 days for the low-top models. While evaluating these results, it has to be kept in mind that the hemispheres are not fully symmetric. The enhanced persistence of stratospheric and tropospheric variability that can arise due to stratospheric events occurs during midwinter (December to February) and spring (March to May) in the NH and during spring to early summer (October to December) for the SH (Lim et al., 2018; Simpson et al., 2011). The SH stratosphere in DJF tends to be more predictable than its NH counterpart in June-August (JJA), likely due to the later breakup of the polar vortex in the SH, leading to enhanced predictability in the SH. On the other hand, the NH stratosphere in DJF is more predictable than its SH counterpart in JJA. One possible reason for this is the stronger remote influences in the NH winter that affect the stratosphere in winter. For the stratosphere, models also often show strongly enhanced predictability for periods of weeks to months after extreme stratospheric events such as SSW events, which are absent in the SH stratosphere in JJA.

It is further found that the stratospheric prediction skill is highly correlated with tropospheric prediction skill. Figure 3 shows a scatter plot for the prediction skill shown in Figure 2 and Table 2. A significant linear relationship across nine prediction systems is found, indicating that the models with a better prediction skill in the stratosphere also exhibit a better tropospheric prediction skill. From this analysis, it is however not possible to infer any causality. In particular, the available model data do not allow us to distinguish if the better tropospheric prediction of high-top models is indeed due to a better resolved stratosphere, which might improve tropospheric predictability, or if prediction systems with a higher stratospheric resolution also exhibit better tropospheric predictions due to a better representation of processes unrelated to the stratosphere or a combination of both.

While many prediction systems show appreciable skill in simulating large-scale NH winter stratospheric anomalies, they do so with a small signal-to-noise ratio (the so-called 'signal-to-noise paradox' (Scaife & Smith, 2018)). For the subseasonal prediction systems in the S2S database, there is evidence that the same problem is also present, at least at lags beyond the limit of predictability in the troposphere. To diagnose signal-to-noise problems in the prediction systems, we examine the RPC diagnostic (section 2.2 and equation 3) and its behavior as a function of lead time and pressure level for the NH winter stratosphere (Figure 4). For all systems, the RPC starts close to 1.0, indicating, as expected, no initial signal-to-noise problem, but the RPC then subsequently grows larger than 1.0, indicating underconfident forecasts and a signal-to-noise issue. In the troposphere, the speed of this growth and the ultimate level of RPC vary between the systems, but an onset at around 10–20 days is typical, leading to the RPC reaching values of about 1.5–3.0. Note this is similar to the level found at the seasonal time scale, and the positive values indicate underconfidence of the prediction systems (i.e., the prediction systems underestimate the predictability of the observations). In the stratosphere, the RPC is found to grow more slowly than in the troposphere.

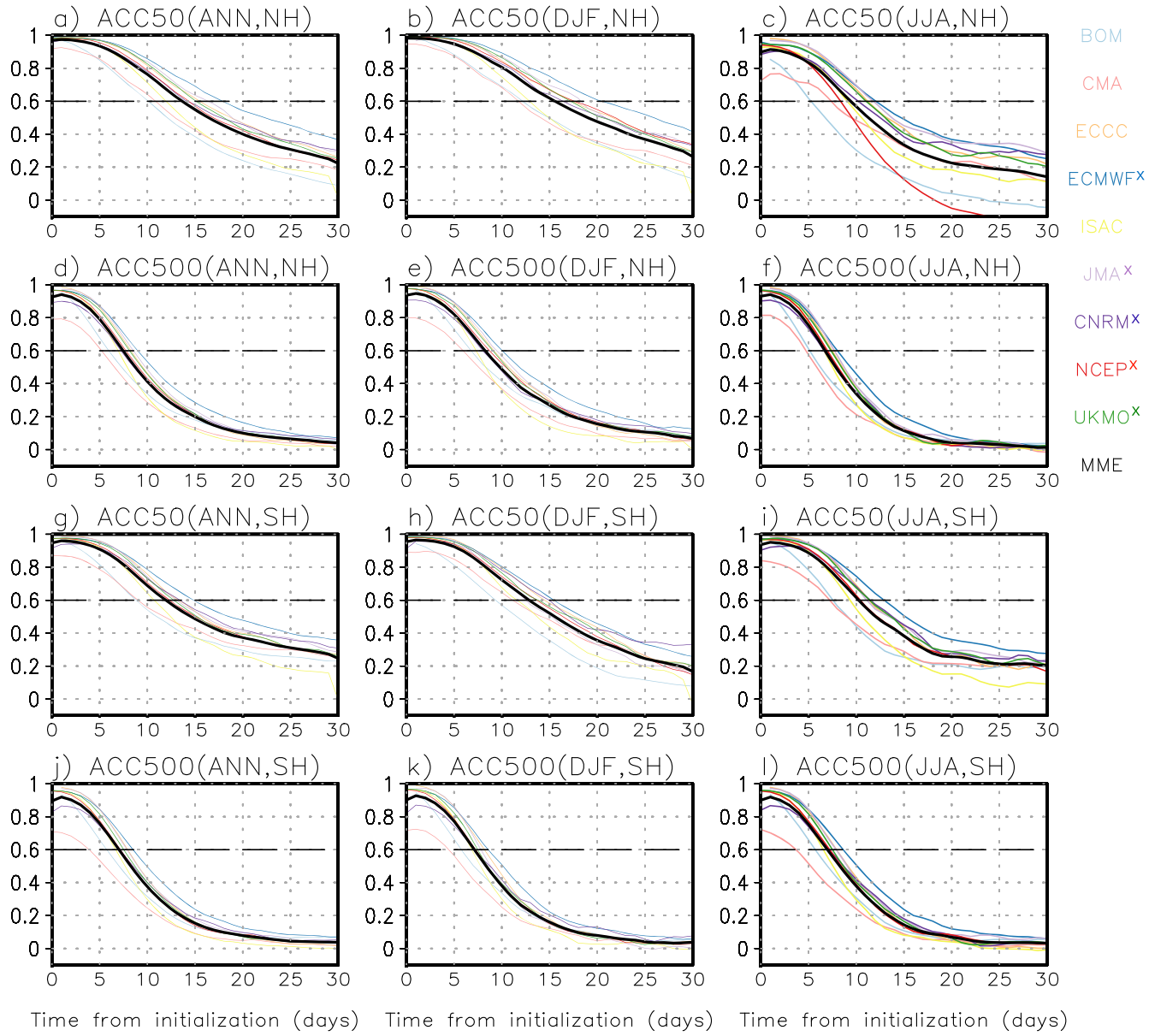

Figure 2. ACC for geopotential height for the area (a–f) north of 30°N and (g–l) south of 30°S. For both hemispheres, the ACC is examined at 50(a–c, g–i) and 500 hPa (d–f, j–l) as a function of lead time (days). The results for JJA and DJF are plotted separately for the period common to all prediction systems. Different colors denote individual prediction systems and the black bold line indicates the multimodel mean, which is computed by averaging the ACC values of all prediction systems. "×" indicates high-top models.

This is consistent with, but not obviously a result of, the higher predictive skill in the stratosphere. Despite the slower onset, the eventual values of the RPC attained in the stratosphere still tend to be large, in many systems equaling (e.g., CMA and NCEP) or exceeding (e.g., BoM) those reached in the troposphere. Other systems do not appear to be integrated sufficiently long for the signal-to-noise paradox to develop in the stratosphere, for example, JMA.

Overall, the results show that all systems in the S2S project possess the signal-to-noise paradox as a feature of their predictions. Note that the skill derived in this section is possibly dependent on the ensemble size of the forecasting systems. This has, for example, been shown to yield a difference for the tropospheric winter circulation on seasonal time scales (Athanasiadis et al., 2017).

Table 2
Maximum Forecast Lead Time (i.e., Predictability Limit in Days) Determined by the Lead Time When the ACC Drops Below 0.6, Based on the Period 1999–2010 for 30–90°N and S

	NH						SH					
	Annual		DJF		JJA		Annual		DJF		JJA	
Model	50 hPa	500 hPa	50 hPa	500 hPa	50 hPa	500 hPa	50 hPa	500 hPa	50 hPa	500 hPa	50 hPa	500 hPa
BoM	*10.1*	*6.0*	*12.2*	*6.8*	*5.3*	*5.1*	*8.8*	5.7	*9.4*	*5.8*	*7.6*	5.7
CMA	*10.9*	*5.2*	*11.7*	*6.0*	7.4	*4.7*	*9.0*	*3.9*	11.1	*4.4*	*7.2*	*3.7*
ECCC	15.5	8.3	17.4	9.2	11.2	7.5	13.3	7.9	14.5	8.2	11.4	7.9
ECMWF×	**17.9**	**9.0**	**20.5**	**10.1**	**12.1**	**8.0**	**14.8**	**8.5**	**15.5**	**8.6**	**12.9**	**8.6**
CNR-ISAC	12.0	6.9	*12.9*	7.3	9.1	6.6	10.7	6.7	11.6	6.8	9.4	6.6
JMA×	16.4	8.5	18.3	9.5	11.8	7.7	13.1	7.9	12.5	7.8	11.1	7.9
CNRM-Meteo×	14.2	7.3	16.4	8.0	10.2	6.6	13.4	7.1	**15.0**	7.2	11.5	7.2
NCEP×	14.3	7.8	17.6	8.7	8.4	7.0	12.3	7.2	13.7	7.3	10.4	7.2
UKMO×	15.1	8.1	17.2	9.0	11.0	7.4	12.8	7.5	13.8	7.5	11.4	7.5
MMM	14.0 ± 2.4	7.5 ± 1.2	16.0 ± 2.9	8.3 ± 1.3	9.6 ± 2.2	6.7 ± 1.1	12.0 ± 1.9	6.9 ± 1.3	13.0 ± 1.9	7.1 ± 1.2	10.3 ± 1.8	6.9 ± 1.4

Note. Values that fall below one standard deviation of the MMM are italicized; values that fall above one standard deviation of the MMM are bolded. × indicates high-top models.

4. Predicting Stratospheric Events

We now turn to prediction on S2S time scales in the extratropical stratosphere. In particular, this section analyzes the predictability of stratospheric extreme events that can subsequently influence surface climate on S2S time scales, as discussed in Part 2 of this study.

Polar vortex events that influence surface climate include early and major midwinter SSW events, strong vortex events, negative heat flux events, and final warming events. These extreme events, which are defined in section 2.3, have different characteristics and potentially different predictability. For example, for SSW events, anomalously large wave breaking is followed by strongly nonlinear wave-mean flow interaction that can lead to quickly developing changes in the circulation. For strong vortex events, anomalously weak wave breaking gives way to slow radiative processes that slowly drive the circulation towards radiative equilibrium and hence a strong vortex. Negative heat flux events are associated with reflection (a reversible process), which is different from wave breaking (an irreversible process), and hence, different predictability time scales could be expected.

Here we compare the predictability of these events during a common period 1996–2010. Five prediction systems (CMA, ECCC, ECMWF, JMA, and UKMO) were used in the analysis of all types of events for the NH to form the multimodel mean (black line in Figure 5); additional modeling systems (BoM, CNR-ISAC, and CNRM-Meteo) were considered in some cases where data were available but are not included in the multimodel mean. NCEP is not considered for this analysis as its period of hindcasts begins in 1999. Note that only two ensemble members from UKMO were available for some initialization dates at the time of data acquisition for this section. The data are first bias corrected by removing the model climatology (leaving the year to be corrected out) and then adding back ERA-interim climatology. The bias correction had the strongest influence on the detection of strong vortex and negative heat flux events at long leads (not shown). In particular, after bias correction, a smaller percentage of members across prediction systems detected strong vortex events at long lead times (suggesting an overestimation of these events in the model climatology) and a greater percentage of detected negative heat flux events at long lead times (suggesting an underestimation of these events in model climatology, in agreement with results from the Coupled Model Intercomparison Project Phase 5 models; Shaw et al., 2014, Fig. 5).

Figure 5 shows the percentage of ensemble members for each prediction system that detects the observed event within ±3 days of its actual date, for lead times averaged over 5-day periods prior to the event, which occurs on Day 0. The bin length is chosen as a balance between having sufficient hindcasts in each bin for each event while resolving the lead times before each event. The "false alarm rate" is the percentage of

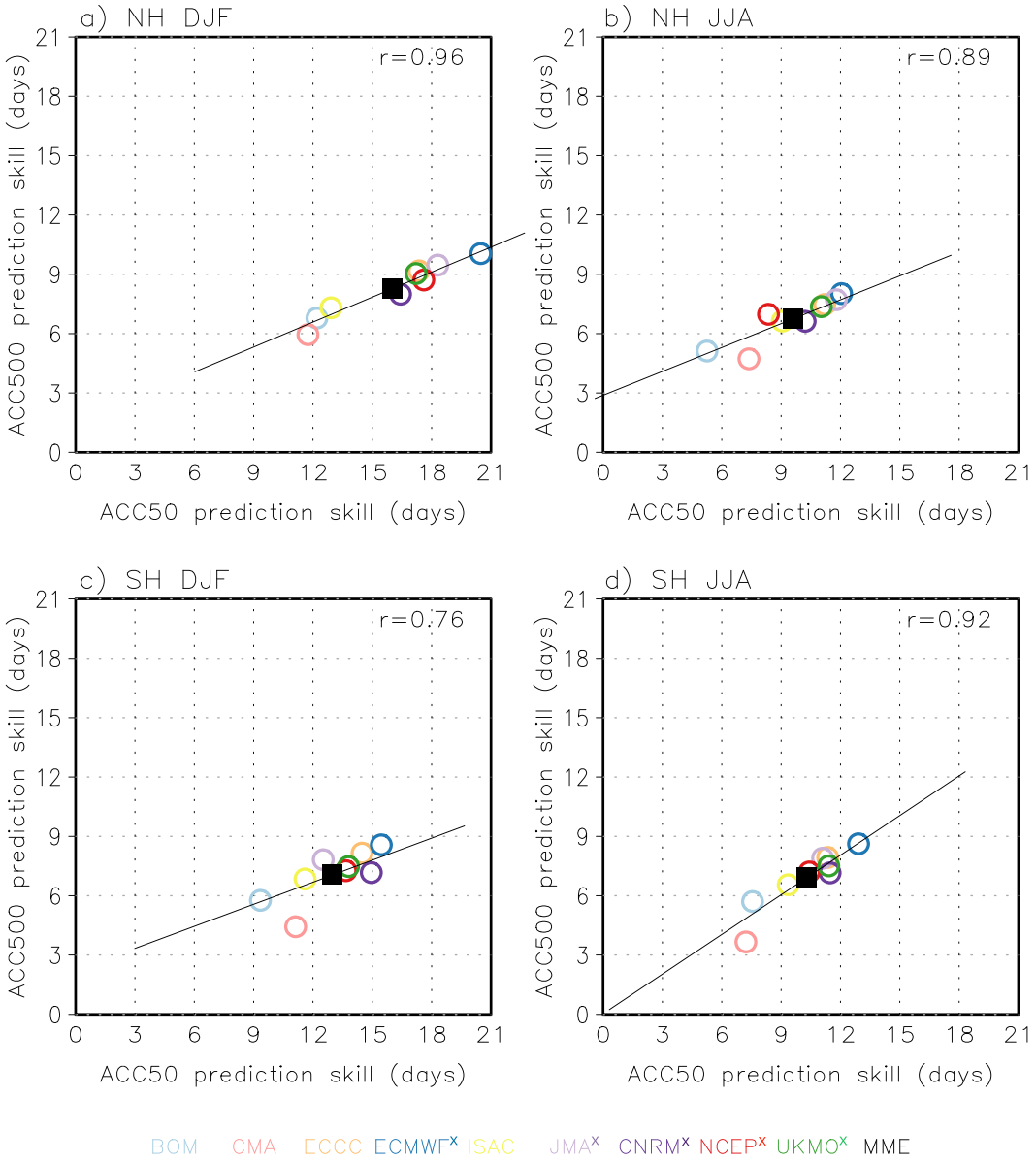

Figure 3. Scatter plot showing the predictability limit (the day for which the ACC crosses 0.6) of geopotential height (a,b) north of 30°N and (c,d) south of 30°S for each model at 50 hPa versus 500 hPa for DJF (left) and JJA (right). The average for all prediction systems is shown as the black square. A linear fit to the data points is shown as the solid line. The correlation coefficient between the prediction skill at 50 hPa and 500 hPa is indicated in the upper-right corner of each panel. "×" indicates high-top models.

members that predict an event to occur within a 1- to 30-day lead time when no event was observed. The comparison of the hit rate with the false alarm rate in Figure 5 provides a measure of the predictive skill.

Below, we describe the differences in the predictability between the different types of polar vortex events. The results should be prefaced by a number of caveats: (1) Not all prediction systems produce a hindcast in each time bin for each event; (2) the number of ensemble members varies across prediction systems; (3) the number of events is generally small, due to the short period covered by the hindcasts; (4) hindcast data from different model versions of a given model are sometimes used; (5) the ±3-day window is an arbitrary choice which could matter for the accuracy in the detection of the events shown here; (6) the false alarm rates are used as a baseline for skill, but the prediction systems could overestimate or underestimate these events, even after bias correction; and (7) the percentage of ensemble members forecasting an event is only one metric for the assessment of predictability and may be less reliable for models with a small number

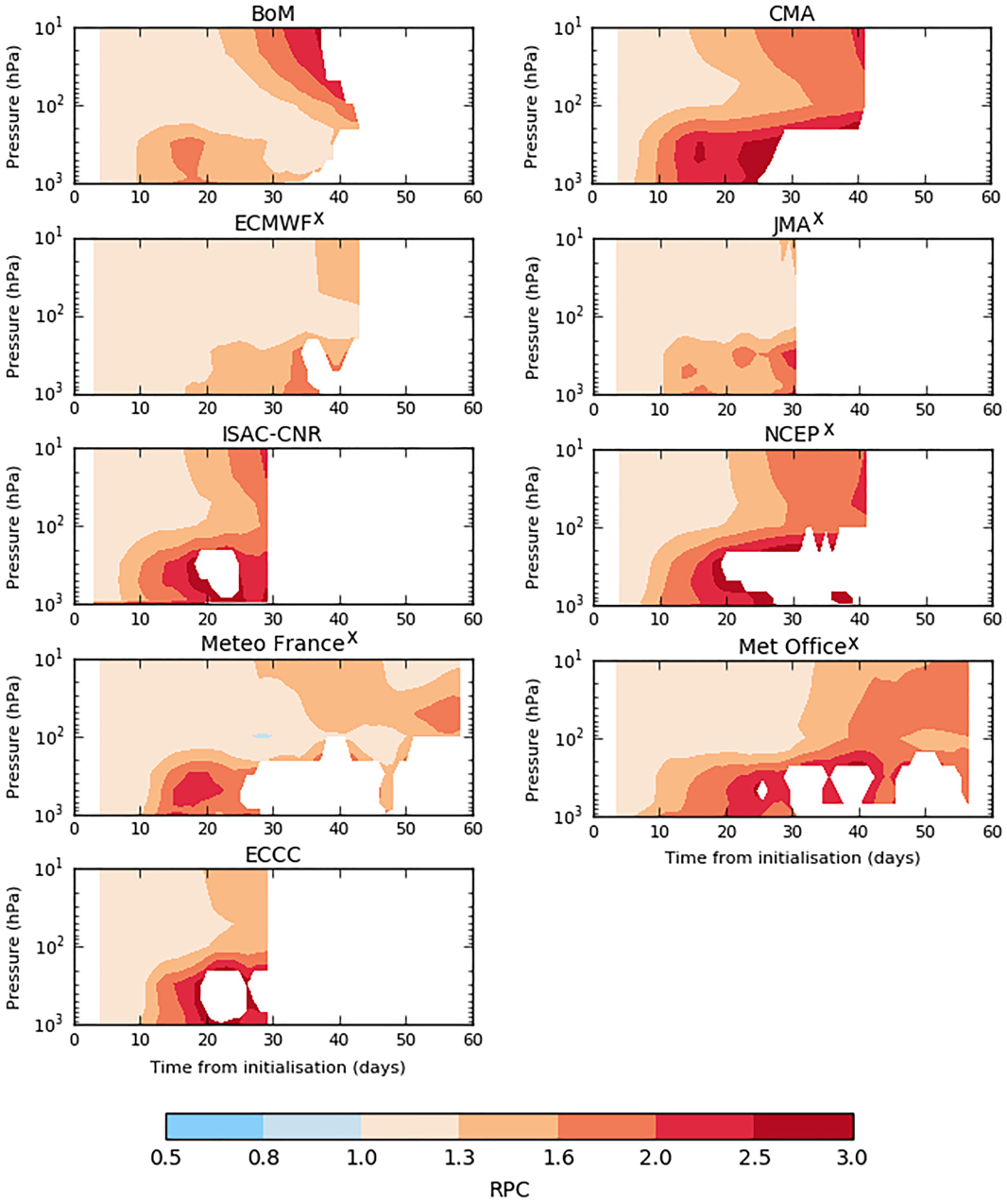

Figure 4. RPC (equation 3) for each prediction system as a function of lead time and height for DJF. Below 100 hPa, the RPC is calculated for the zonal means of zonal wind at 60°N for the North Atlantic-European sector between 90°W and 60°E. Above 100 hPa, the same diagnostic calculated for the entire latitude circle is used. Before calculating the RPC, the data are aggregated into 7-day running means. These two aspects are necessary so that a reliable RPC can be obtained. As the correlation r and the ensemble mean become small, the RPC becomes ill defined, resulting in very noisy estimates. To avoid potentially misleading noise, the plot is masked where the correlation with observations is less than 0.2. For full zonal means at daily resolution, the tropospheric correlation is always less than 0.2 after about 20 days, making it impossible to trace the growth of the RPC. "×" indicates high-top models.

of ensemble members at a given lead time. Other skill evaluation techniques (such as in Karpechko et al. (2018)) return similar but not identical results.

Four early winter weak vortex events (one each in 1996, 2000, 2005, and 2009) are evaluated in the common S2S period. Each of these instances is associated with at least one ensemble member from the S2S hindcasts forecasting a major SSW in November, while other ensemble members miss the event entirely by forecasting vortex intensification. We find that fewer than 50% of ensemble members accurately detect early warming

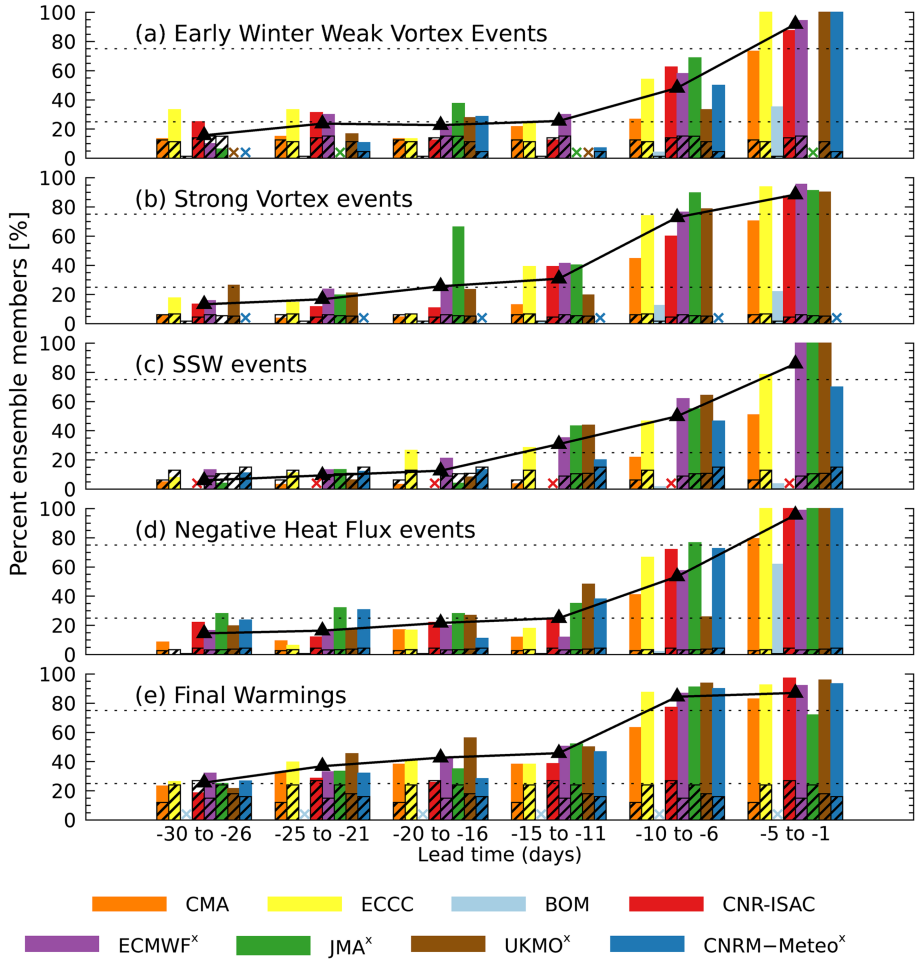

Figure 5. The average across all events of the percentage of ensemble members as a function of lead time (days) that detect the event within ±3 days of the observed event for (a) early stratospheric warming events, (b) strong polar vortex events, (c) SSW events, (d) negative heat flux events, and (e) final warming events. The black line shows the multimodel mean based on five prediction systems (CMA, ECCC, ECMWF, JMA, and UKMO). Dotted lines show where 25% and 75% of ensemble members detect the event. "×" marks the high-top models in the legend. Where a prediction system was not used for the analysis or where there were not enough available ensemble members (at least 10 members were required for a given lead time range) is marked by an × in the color of the prediction system. Patterned black bars give the "false alarm rate" (events that were predicted but not detected at the given lead times).

events prior to 6–10 days from the observed event, but almost all capture the event within 5 days (Figure 5a). The multimodel mean rises above the false alarm rate at lags up to 25 days from the event, suggesting some skill at longer leads. Two low-top systems, BoM and CMA, have difficulty predicting early winter weak vortex events even 5 days ahead of time, but two other low-top systems, ECCC and CNR-ISAC, perform similarly to high-top models at most lead times (and even slightly better at long lead times).

Accurate detection of strong polar vortex events (Figure 5b) becomes highly probable (i.e., greater than 75%) up to 10 days before the event. Two exceptions are BoM and CMA. CMA has, on average, relatively low probability (about 70%) of detection even at lead times less than 5 days before the events. BoM clearly has problems with forecasting a strong polar vortex event, which is likely due to a lack of stratospheric resolution in this model. JMA indicates the most skill at 6- to 20-day leads, but overall, all systems (with the exception of BoM and CMA) perform similarly. At lead times longer than 15 days, the forecasted probability of detecting an event is between 5% and 60%, which typically exceeds the averaged 30-day lead time false alarm rates. The enhanced detection of the event relative to the false alarm rate may indicate some skill even at lead times of 30 days.

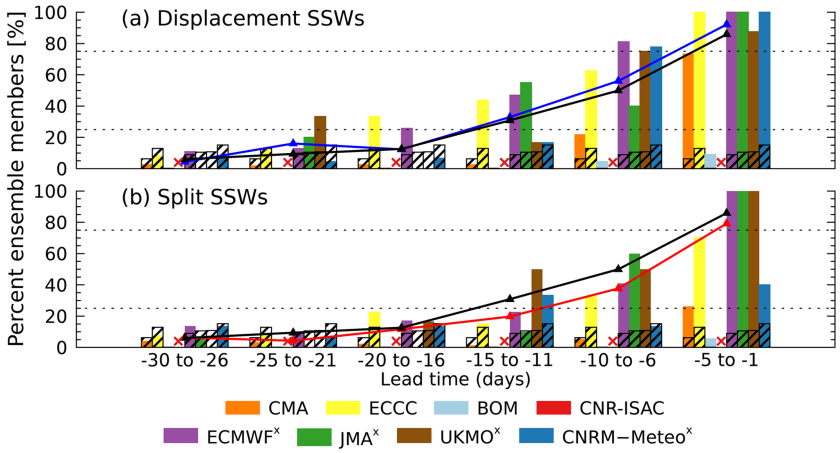

Figure 6. Same as Figure 5c but for SSW events separated into (a) displacement and (b) split events. The black line corresponds to the multimodel mean from Figure 5c; the blue/red lines indicate the multimodel mean for the displayed events only. A student *t* test of the differences between the detection of splits and displacements gives the following *p* values for lead times from left to right: [0.6948, 0.0279, 0.7550, 0.357, 0.0925, 0.3740]. The false alarm rates shown by the black patterned bars are for all SSW events, as in Figure 5c.

Previous studies (e.g., Gerber et al., 2009; Karpechko, 2018; Karpechko et al., 2018) have found predictability limits for major midwinter SSWs of around 10–20 days. Here we find similar results for the S2S prediction systems (Figure 5c). While the percentage of ensemble members detecting an event does exceed false alarm rates at lead times of up to 15 days for most prediction systems, less than 10% of members detect SSW events at long leads (greater than 25 days), and predictions do not exceed 50% of members until lead times of 10 days or less. Even at lead times of 5 days, a few of the prediction systems (CMA, BoM, and CNRM-Meteo) show 80% or less of members detecting the observed SSW. These results generally agree with previous estimates of SSW deterministic predictability (Karpechko, 2018; Tripathi, Baldwin, et al., 2015) and indicate that predictability of such a major nonlinear transition can be limited by both the predictability of Rossby wave propagation and their interaction with the stratospheric mean state (Plumb, 1981).

One more interesting implication of midwinter SSW events is the *type* of SSW that occurs. In a common classification, there are two major types of midwinter SSW events: (1) "split" events, for which the polar vortex splits into two separate vortices, and (2) "displacement" events, for which the polar vortex is distorted and displaced off the pole (e.g., Charlton & Polvani, 2007). Taguchi (2018) provides an analysis of the predictability in the S2S hindcasts of five SSW events (December 1998, December 2001, January 2009, January 2013 in the NH, and September 2002 in the SH), showing that the vortex split SSWs (i.e., 2002, 2009, and 2013) were more difficult to forecast than the displacements (1998 and 2001). Here, we extend that analysis by considering the predictability of 11 NH midwinter SSW events in ERA-Interim during the 1996–2010 period. A separate analysis separating split and displacement events for this larger number of events, that is, six displacements and five split events (Figure 6), confirms the results from Taguchi (2018), that is, that displacement events tend to be more predictable than split events, especially at lead times of 1–2 weeks, though given the limited number of events this difference has limited statistical significance. While this points to potentially different mechanisms in the precursors and causes of these events (e.g. Domeisen et al., 2018; Esler & Matthewman, 2011; Martius et al., 2009; Matthewman & Esler, 2011), it will have to be further investigated if this difference is indeed robust and what the reasons for these differences are.

Next, we consider the predictability of negative eddy heat flux events (Figure 5d). Mukougawa et al. (2017) used an ensemble forecast model to show that the predictive lead time of a March 2007 negative heat flux event was 1 week. Extending the analysis to multiple extreme negative stratospheric heat flux events, here we find that the multimodel mean exhibits predictive skill at lead times of up to 30 days. The performance again varies between prediction systems, with JMA and CNRM-Meteo showing the highest skill at long leads and BOM and CMA showing weaker skill at most leads.

Finally, we find that the predictability of final warmings is higher for longer lead times compared to other events (Figure 5e). However, the false alarm rate is also larger than for other events since the prediction

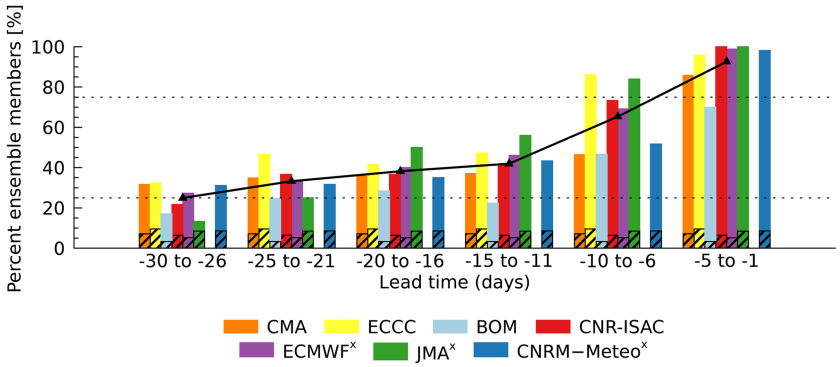

Figure 7. Same as Figure 5e but for final warming events in the Southern Hemisphere. The false alarm rates are shown by the black patterned bars. The black line shows the multimodel average over all prediction systems displayed here.

systems climatologically must predict a final warming every year. The detection rate rises above the false alarm rate at lead times of up to 25 days. Note also that this particular period (1996–2010) comprises 10 "late" (i.e., after 15 April) final warmings and only four "early" (i.e., before 15 April) final warmings. This is relevant since late final warmings are more predictable at longer lead times than early, dynamically driven final warmings, which show predictability more similar to midwinter SSW events (Butler et al., 2019).

We now perform the same analysis for the SH to obtain the model skill for predicting the timing of the final stratospheric warming events in the SH using the same approach as for the NH discussed above. In the SH, the maximum variability of the polar vortex is found in spring in the upper stratosphere when the stratospheric polar night jet seasonally weakens and becomes more susceptible to wave forcing from the troposphere (Byrne & Shepherd, 2018; Graversen & Christiansen, 2003; Kuroda & Kodera, 1998; Lim et al., 2018; Randel, 1988; Sheshadri & Plumb, 2016; Shiotani & Hirota, 1985; Thompson & Wallace, 2000). Anomalous weakening and warming (strengthening and cooling) of the SH spring polar vortex generally leads to an earlier (later) final warming event (Byrne & Shepherd, 2018; Shiotani et al., 1993).

Figure 7 assesses the skill of the subseasonal forecasting systems in predicting final warming events in the SH. All models show skill (relative to the false alarm rate at these leads, given in black bars), even out to lead times of 30 days. As for the NH, the high-top models tend to show the highest skill, though it is notable that several low-top models such as CNR-ISAC and ECCC show significant skill for all lead times. In comparison to the NH final warmings, the false alarm rates tend to be smaller in the SH, and predictability (the percentage of ensemble members predicting the correct date in comparison to the false alarm rate) can be found for longer lead times: While in the NH, the prediction rate falls below the false alarm rate as early as at lead times of 16 to 20 days before the event for several models, this is not the case for any model in the SH out to 30 days before the final warming event. The multimodel mean predictability is similar to the NH, though it decays faster for lead times of 6 to 10 days, while it remains high for these lead times in the NH. Overall, this indicates a higher predictability of the final warming events at short lead times for the NH but higher predictability for long lead times of 3–4 weeks for the SH. The predictability at longer lead times in the SH might arise due to the smaller variability in the timing of the SH final warming compared to the NH, despite the observed trend in the timing of the final warming due to ozone variability and trends (Black & McDaniel, 2007; Sheshadri & Plumb, 2016; Thompson et al., 2011). Given that almost all models use noninteractive or climatological ozone, this demonstrated forecast skill to predict the timing of the SH final warming indicates that dynamical processes are the dominant drivers of predictability for the final warming, but there is scope for further improvement of forecast skill by including prognostic ozone (e.g. Seviour et al., 2014).

While it is difficult to directly compare the predictability of different types of events, given the differences in the number of events and their time of occurrence in each case, in general, we can conclude the following:

(a) Models with poorer stratospheric resolution or a low model top such as, for example, CMA and BoM, show a weaker performance in predicting stratospheric events. Note that BoM's top level below the model lid is at 10 hPa, so using metrics based on 10 hPa, output may not be physically meaningful for this prediction system because of strong damping of wave-driven processes by the deep sponge layer. However, ECCC,

despite its low model top (see Figure 1), has a predictability of stratospheric events that is comparable to models with a well-resolved stratosphere.

(b) The probability of accurately detecting the observed event increases as lead time decreases and becomes large (greater than 75%) at lead times of up to 10 days before the events. The probability of accurately detecting the observed event has less dependence on lead time between 30 and 15 days before the event. For these lead times, forecast probability is between 5% and 50%, with some types of events exhibiting longer-lead predictability than others. Strong vortex events and final warmings appear somewhat more predictable at longer leads than SSW events, which hints at the different mechanisms causing these events. The lower predictability of SSW events is likely linked to their more dynamical and wave-driven nature, while more gradual and/or radiatively driven processes, for example, strong vortex or late final warming events, tend to be more predictable (Butler et al., 2019). While we here provide a first look at the overall predictability of these events in the S2S database, more work will have to be done to fully understand the factors that drive some events to be more predictable than others.

5. Discussion and Outlook

In this study, we have examined the predictability in the stratosphere using the subseasonal prediction systems from the S2S database (Vitart et al., 2017). These systems provide important operational guidance for prediction on S2S time scales, so it is important to understand the processes that give rise to predictability, including those that involve the stratosphere. This study focuses on evaluating the predictability of the stratosphere itself, as extreme events in the stratosphere can have significant impacts on the predictability of surface weather, which is investigated in Part 2 of this study (Domeisen et al., 2019).

Overall, the stratosphere exhibits longer predictability time scales as compared to the troposphere, as exemplified by the slower decrease in the prediction skill in comparison to the troposphere. For most models, predictability beyond 2 weeks is typical in the stratosphere. In addition, the stratosphere exhibits a slower growth of the signal-to-noise problem as compared to the troposphere. The stratosphere also exhibits a range of extreme events; however, stratospheric extreme events themselves tend not to be predictable beyond deterministic time scales and exhibit similar predictability to tropospheric weather. This is in particular the case for SSW events, which are predicted by up to 50% of the ensemble members in all models out to only about a week. Events that are less abrupt in nature, such as late final warming events and strong vortex events, tend to be more predictable, with up to 50% of the ensemble members predicting the occurrence of the event 2 weeks in advance (see also: Butler et al., 2019). Final warming events in the SH tend to be more predictable than those in the NH.

Due to the limited representation of ozone on the S2S models, it is not possible to assess the role of ozone on predictability using the current set of models. Given the possible influence of ozone on the dynamical evolution of the stratosphere in both hemispheres (Ivy et al., 2016, 2017; Keeble et al., 2014; Rieder et al., 2019; Seviour et al., 2014; Solomon et al., 2014), an improved representation of stratospheric ozone might further increase the predictability of the stratosphere on subseasonal and longer time scales. Significant differences can be found in the predictability of stratospheric events between high-top and low-top models, with the high-top models exhibiting significantly higher predictability of stratospheric extreme events as compared to low-top models. Note that here, high top refers to models with both a high model top and an improved stratospheric resolution.

It should be noted that the estimates of skill in the prediction of various parameters in this study are dependent on the frequency and ensemble size of the hindcasts in the S2S database. Ensemble size has been shown to have a marked influence on the skill of ensemble forecasting of the midlatitude winter circulation (e.g. Athanasiadis et al., 2017), with larger ensembles tending to be more skillful. Operational requirements within the centers contributing to the S2S data set frequently mean that hindcast ensemble sizes are considerably smaller than those of operational forecasts. As a result, when the same systems are used to produce forecasts in real time, they may have levels of skill that exceed those shown here. It might be reasonable to assume, therefore, that the skill shown here is a lower limit for the skill of real-time operational forecasts. In a similar way, our results cannot be used to infer the relative performance of the underlying models within the prediction systems, as any differences in skill may be a result of differences in their ensemble size and initialization strategy rather than the model itself.

Overall, this study shows a clear dependence of S2S prediction skill on the season and the type of extreme event in the stratosphere for all models. In addition, a clear difference in predictability between high-top and low-top models can be observed, with a significantly better prediction of stratospheric extreme events in high-top models. While this study provides an overview of the prediction skill available in the S2S database, further detailed studies of S2S prediction skill for the stratosphere will be necessary in order to assess the full range of stratospheric predictability, especially with further stratospheric data becoming available in future versions of the S2S database.

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