

SMALL DATA SCATTERING FOR CUBIC DIRAC EQUATION WITH HARTREE TYPE NONLINEARITY IN \mathbb{R}^{1+3*}

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Abstract. We prove that the initial value problem for the Dirac equation $(-i\gamma^\mu \partial_\mu + m)\psi = (\frac{e^{-|x|}}{|x|} * (\bar{\psi}\psi))\psi$ in \mathbb{R}^{1+3} is globally well-posed and the solution scatters to free waves asymptotically as $t \rightarrow \pm\infty$ if we start with initial data that are small in H^s for $s > 0$. This is an almost critical well-posedness result in the sense that L^2 is the critical space for the equation. The main ingredients in the proof are Strichartz estimates, space-time bilinear null-form estimates for free waves in L^2 , and an application of the U^p and V^p function spaces.

Key words. Dirac equation, Hartree nonlinearity, scattering

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1. Introduction.

1.1. Preliminary. We consider the initial value problem for the nonlinear Dirac equation with Hartree type nonlinearity,

$$(1.1) \quad \begin{cases} (-i\gamma^\mu \partial_\mu + m)\psi = (V * (\bar{\psi}\psi))\psi & \text{in } \mathbb{R}^{1+3}, \\ \psi(0, \cdot) = \psi_0 \in H^s(\mathbb{R}^3), \end{cases}$$

where the unknowns are a spinor field $\psi(t, x)$ regarded as a column vector in \mathbb{C}^4 ; $m \geq 0$ is a mass parameter; $V(x) = |x|^{-1}e^{-|x|}$ is the Yukawa potential; $\gamma^\mu \partial_\mu = \gamma^0 \partial_t + \sum_{j=1}^3 \gamma^j \partial_{x_j}$, where $\{\gamma^\mu\}_{\mu=0}^3$ are the 4×4 Dirac matrices, given in 2×2 block form by

$$\gamma^0 = \begin{pmatrix} I & 0 \\ 0 & -I \end{pmatrix}, \quad \gamma^j = \begin{pmatrix} 0 & \sigma^j \\ -\sigma^j & 0 \end{pmatrix},$$

where

$$\sigma^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

are the Pauli matrices; $\bar{\psi} = \psi^\dagger \gamma^0$, where ψ^\dagger denotes the conjugate transpose, hence,

$$\bar{\psi}\psi = \psi^\dagger \gamma^0 \psi = \langle \gamma^0 \psi, \psi \rangle \equiv |\psi_1|^2 + |\psi_2|^2 - |\psi_3|^2 - |\psi_4|^2,$$

where ψ_1, \dots, ψ_4 are the components of ψ . Finally, H^s is the Sobolev space of order s .

Equation (1.1) with a Coulomb potential, i.e., $V(x) = |x|^{-1}$, and a quadratic term $|\psi|^2$ replacing $\bar{\psi}\psi$ was derived by Chadam and Glassey [2] by uncoupling the Maxwell–Dirac equations under the assumption of vanishing magnetic field. They also conjectured in the same paper [2, pp. 507] that (1.1) with a Yukawa potential V

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can be derived by uncoupling the Dirac–Klein–Gordon equations:

$$(DKG) \quad \begin{cases} (-i\gamma^\mu \partial_\mu + m) \psi = \phi \psi, \\ (\partial_t^2 - \Delta + M^2) \phi = \bar{\psi} \psi. \end{cases}$$

Now if we assume that the scalar field ϕ is a standing wave of the form $\phi(t, x) = e^{ict} \varphi(x)$ with $|c| < M$ (see, e.g., [10, 23]), the Klein–Gordon part of (DKG) becomes

$$(-\Delta + (M^2 - c^2)) \phi = \bar{\psi} \psi,$$

whose solution is given by

$$\phi = V_{m_0} * (\bar{\psi} \psi),$$

where $V_{m_0} = (4\pi|x|)^{-1} e^{-m_0|x|}$ with $m_0 = \sqrt{M^2 - c^2} > 0$. Plugging $\phi = V_{m_0} * (\bar{\psi} \psi)$ back into the first equation in (DKG) yields (1.1) with V replaced by V_{m_0} . Nevertheless, the analysis of (1.1) with the Yukawa potential V or V_{m_0} is the same.

The L^2 -norm of the solution for (1.1) is conserved:

$$\int_{\mathbb{R}^3} |\psi(t, x)|^2 dx = \int_{\mathbb{R}^3} |\psi(0, x)|^2 dx.$$

In the massless case, $m = 0$, (1.1) is invariant under the scaling

$$u(t, x) \mapsto u_\lambda(t, x) = \lambda^{\frac{3}{2}} u(\lambda t, \lambda x)$$

for fixed $\lambda > 0$. This scaling symmetry leaves the L^2 -norm invariant, and so equation (1.1) is L^2 -critical.

A related equation that has been studied extensively is the boson star equation:

$$(1.2) \quad (-i\partial_t + \sqrt{m^2 - \Delta}) u = (V * |u|^2) u \quad \text{in } \mathbb{R}^{1+3}.$$

The first well-posedness result for this equation with both the Coulomb and Yukawa potential was obtained by Lenzmann [19] for data in H^s with $s \geq \frac{1}{2}$, and later this was improved to $s > 1/4$ by Herr and Lenzmann [14]. Concerning scattering theory Pusateri [21] established a modified scattering result in the case of a Coulomb potential (which is the most difficult case) for small initial data in some weighted Sobolev space. There are several well-posedness and scattering results for (1.2) with potentials of the form $V(x) = |x|^{-a}$ for $a \in (1, 3)$; see, e.g., [3, 4, 5, 6, 21].

Convolution with a Yukawa potential is (up to a multiplicative constant) the Fourier-multiplier $(1 - \Delta)^{-1}$ with Fourier symbol $(1 + |\xi|^2)^{-1}$ in \mathbb{R}^3 while convolution with a Coulomb potential is (up to a multiplicative constant) the Fourier-multiplier $(-\Delta)^{-1}$ with Fourier symbol $|\xi|^{-2}$ in \mathbb{R}^3 . Thus, both of these potentials are smoothing operators; however, the Yukawa potential has an advantage over the Coulomb potential (and also potentials of the form $V(x) = |x|^{-a}$ for $a \in (0, 3)$) since the latter one is singular near the origin.

Recently, Herr and the present author [16] proved small data scattering for (1.2) with $m > 0$ and $s > \frac{1}{2}$. Consequently, scattering is obtained for the nonlinear Dirac equation

$$(1.3) \quad (-i\gamma^\mu \partial_\mu + m) \psi = (V * |\psi|^2) \psi \quad \text{in } \mathbb{R}^{1+3}$$

with Yukawa potential, $m > 0$ and $s > \frac{1}{2}$ (see [16, Remark 1.2]).¹ Existence of a weak solution for (1.3) with a Yukawa potential in the massless case ($m = 0$) was proved earlier by Dias and Figueira [8, 9]. There is also a small data scattering result due to Machihara and Tsutaya [20] for (1.3) with a potential $V(x) = |x|^{-a}$ for $a \in (2, 3)$, $m > 0$, and $s > a/6 + 1/2$.

The key difference between (1.1) and (1.3) is the nonlinearity $(V * (\bar{\psi}\psi))\psi$ contains a hidden null structure while this structure is not present in $(V * |\psi|^2)\psi$. In the present paper, we exploit this null structure to obtain small data scattering for (1.1) for all $m \geq 0$ and $s > 0$. To establish this result we first prove L^2 -space-time bilinear null-form estimates for free waves and frequency localized quadrilinear estimates in U^p - and V^p -spaces. To the authors knowledge there is no prior well-posedness result for (1.1).

Our main result is as follows.

THEOREM 1. *Let $m \geq 0$, $s > 0$, and $\|\psi_0\|_{H^s} < \varepsilon$ for sufficiently small $\varepsilon > 0$. Then the initial value problem (1.1) is globally well-posed and the solution ψ scatters to free waves as $t \rightarrow \pm\infty$.*

Remark 1.

- (i) After the submission of this paper the author has learned that similar scattering results for (1.1) with a Yukawa potential and potentials of type $V(x) = |x|^{-a}$ was independently proved by Yang [23].
- (ii) The critical case $s = 0$ corresponds to initial data in $L^2(\mathbb{R}^3)$. The presence of the factor $\lambda_{\text{med}}^\delta$ ($\delta > 0$ small) in the dyadic quadrilinear estimate in Lemma 11 impedes us from performing the sum in Lemma 12 for $s = 0$. However, if one is able to prove the estimate with the factor $\lambda_{\text{med}}^{-\delta}$ or $(\lambda_{\text{med}}/\lambda_{\text{max}})^\delta$ replacing $\lambda_{\text{med}}^\delta$, then it is possible to do the sum for $s = 0$, and hence prove Theorem 1 for initial data in $L^2(\mathbb{R}^3)$. This may however require modifying the working spaces or proving more refined estimates. In this paper, we do not claim that the quadrilinear estimate in Lemma 11 is optimal.
- (iii) Recently, after the submission of this paper, the author established a scattering result for (1.1) in \mathbb{R}^{1+2} for $m > 0$ and $s > 0$ [22].

1.2. Reformulation of Theorem 1. We rewrite (1.1) in a slightly different form by multiplying the equation by $\beta = \gamma^0$:

$$(1.4) \quad \begin{cases} (-i\partial_t + \alpha \cdot D + m\beta)\psi = (V * \langle \beta\psi, \psi \rangle) \beta\psi & \text{in } \mathbb{R}^{1+3}, \\ \psi(0, \cdot) = \psi_0 \in H^s(\mathbb{R}^3), \end{cases}$$

where $D = -i\nabla$ and $\alpha = (\alpha^1, \alpha^2, \alpha^3)$ with $\alpha^j \equiv \gamma^0\gamma^j$. These matrices satisfy the following identities:

$$(1.5) \quad \begin{aligned} \beta^2 &= (\alpha^j)^2 = I, & \alpha^j\beta &= -\beta\alpha^j, \\ \alpha^j\alpha^k &= -\alpha^k\alpha^j + 2\delta^{jk}I, \end{aligned}$$

where $\delta^{jk} = 1$ if $j = k$ and $\delta^{jk} = 0$ if $j \neq k$. Moreover,

$$(1.6) \quad \alpha^j\alpha^k = \delta^{jk}I + i\epsilon^{jkl}S_l,$$

¹Global well-posedness and scattering of (1.1) for $m > 0$ and $s > 1/2$ will also follow from [16]. However, Theorem 1 improves this result to $m \geq 0$ and $s > 0$.

where $\epsilon^{jkl} = 1$ if (j, k, l) is an even permutation of $(1, 2, 3)$, $\epsilon^{jkl} = -1$ if (j, k, l) is an odd permutation of $(1, 2, 3)$, and $\epsilon^{jkl} = 0$ otherwise, and

$$S^l = \begin{pmatrix} \sigma^l & 0 \\ 0 & \sigma^l \end{pmatrix}.$$

Following [7, 1] we decompose the spinor ψ relative to a basis of the operator $\alpha \cdot D + m\beta$ whose symbol is $\alpha \cdot \xi + m\beta$. Since $(\alpha \cdot \xi + m\beta)^2 = (|\xi|^2 + m^2)I$, the eigenvalues are $\pm \langle \xi \rangle_m$, where

$$\langle \xi \rangle_m = \sqrt{m^2 + |\xi|^2}.$$

Now define the projections

$$\Pi_m^\pm(D) = \frac{1}{2} \left(I \pm \frac{1}{\langle D \rangle_m} [\alpha \cdot D + m\beta] \right).$$

Then we can decompose

$$(1.7) \quad \psi = \psi^+ + \psi^-, \quad \text{where } \psi^\pm = \Pi_m^\pm(D)\psi.$$

In view of the identities in (1.5)–(1.6) we have

$$(1.8) \quad \Pi_m^\pm(D)\Pi_m^\pm(D) = \Pi_m^\pm(D), \quad \Pi_m^\pm(D)\Pi_m^\mp(D) = 0$$

and

$$(1.9) \quad \beta\Pi_m^\pm(D) = \Pi_m^\mp(D)\beta \pm m\langle D \rangle_m^{-1}.$$

Applying $\Pi_m^\pm(D)$ to (1.4) and using (1.7)–(1.8) we obtain

$$(1.10) \quad \begin{cases} (-i\partial_t + \langle D \rangle_m)\psi^+ = \Pi_m^+(D) [(V * \langle \beta\psi, \psi \rangle)\beta\psi], \\ (-i\partial_t - \langle D \rangle_m)\psi^- = \Pi_m^-(D) [(V * \langle \beta\psi, \psi \rangle)\beta\psi] \end{cases}$$

with initial data

$$(1.11) \quad \psi^\pm(0, \cdot) = \psi_0^\pm \in H^s(\mathbb{R}^3),$$

where

$$\psi_0^\pm = \Pi_m^\pm(D)\psi_0.$$

We denote by $S_m(\pm t)$ the solution propagators to the free Dirac equation:

$$S_m(\pm t)f = e^{\mp it\langle D \rangle_m} f = \int_{\mathbb{R}^3} e^{\mp it\langle \xi \rangle_m} e^{ix \cdot \xi} \widehat{f}(\xi) d\xi.$$

Now Theorem 1 reduces to the following.

THEOREM 2. *Let $m \geq 0$, $s > 0$, and $\|\psi_0^\pm\|_{H^s} < \varepsilon$ for sufficiently small $\varepsilon > 0$. Then the IVP (1.10)–(1.11) is globally well-posed and the solutions ψ^\pm scatter to free waves as $t \rightarrow \pm\infty$, i.e., there exist $(f_\pm, g_\pm) \in H^s \times H^s$ such that*

$$\lim_{t \rightarrow \infty} \|\psi^\pm(t) - S_m(\pm t)f_\pm\|_{H^s} = 0$$

and

$$\lim_{t \rightarrow -\infty} \|\psi^\pm(t) - S_m(\pm t)g_\pm\|_{H^s} = 0.$$

The rest of the paper is organized as follows. In section 2 we give some notation, define the U^p - and V^p -spaces and collect their properties. In section 3, we collect some linear, convolution and bilinear estimates for free solutions of the Klein–Gordon equation. In section 4 we reveal the null structure in (1.10) and prove bilinear null-form estimates. In section 5 we give the proof for Theorem 2 after reducing it first to nonlinear estimates. The proof for these nonlinear estimates will be given in section 6. In sections 7 and 8 we prove the convolution and bilinear estimates for free waves stated in section 3.

2. Notation and function spaces.

2.1. Notation. In equations, estimates, and summations the Greek letters μ and λ are presumed to be dyadic with $\mu, \lambda > 0$, i.e., these variables range over numbers of the form 2^k for $k \in \mathbb{Z}$. In estimates we use $A \simeq B$ as shorthand for $A = CB$ and $A \lesssim B$ for $A \leq CB$ for some constant $C > 0$, whereas we use $A \ll B$ for $A \leq C^{-1}B$ for some constant $C \gg 1$; the constants are independent of dyadic numbers such as μ and λ ; $A \sim B$ means $B \lesssim A \lesssim B$; $A \approx B$ means either $A \ll B$ or $B \ll A$; $A \vee B$ and $A \wedge B$ denote the maximum and minimum of A and B , respectively; $\mathbb{1}_{\{\cdot\}}$ denotes the indicator function which is 1 if the condition in the bracket is satisfied and 0 otherwise; we write $a \pm := a \pm \varepsilon$ for sufficiently small $0 < \varepsilon \ll 1$. Finally, we use the notation

$$\|\cdot\| = \|\cdot\|_{L_{t,x}^2(\mathbb{R}^{1+3})} \quad \text{or} \quad \|\cdot\|_{L_x^2(\mathbb{R}^3)}$$

depending on the context.

The Fourier transform in space and space time are given by

$$\begin{aligned} \mathcal{F}_x(f)(\xi) &= \widehat{f}(\xi) = \int_{\mathbb{R}^3} e^{-ix \cdot \xi} f(x) \, dx, \\ \mathcal{F}_{t,x}(u)(\tau, \xi) &= \widetilde{u}(\tau, \xi) = \int_{\mathbb{R}^{1+3}} e^{-i(t\tau + x \cdot \xi)} u(t, x) \, dt dx. \end{aligned}$$

Now consider an even function $\chi \in C_0^\infty((-2, 2))$ such that $\chi(s) = 1$ if $|s| \leq 1$. We define

$$\rho_\lambda(s) = \begin{cases} 0 & \text{if } 0 < \lambda < 1, \\ \chi(s) & \text{if } \lambda = 1, \\ \chi\left(\frac{s}{\lambda}\right) - \chi\left(\frac{2s}{\lambda}\right) & \text{if } \lambda > 1 \end{cases}$$

and

$$\sigma_\lambda(s) = \chi\left(\frac{s}{\lambda}\right) - \chi\left(\frac{2s}{\lambda}\right) \quad \text{for } \lambda > 0.$$

Thus, $\text{supp } \rho_1 = \{s \in \mathbb{R} : |s| < 2\}$ whereas $\text{supp } \rho_\lambda = \{s \in \mathbb{R} : \frac{\lambda}{2} < |s| < 2\lambda\}$ for $\lambda > 1$. Similarly, $\text{supp } \sigma_\lambda = \{s \in \mathbb{R} : \frac{\lambda}{2} < |s| < 2\lambda\}$ for all $\lambda > 0$. Then we define the frequency and modulation projections by

$$\begin{aligned} P_\lambda f &= \mathcal{F}_x^{-1}[\rho_\lambda(|\xi|)\widehat{f}(\xi)], \\ \Lambda_\lambda^\pm u &= \mathcal{F}_{t,x}^{-1}[\sigma_\lambda(|\tau \pm \langle \xi \rangle_m|)\widetilde{u}(\tau, \xi)]. \end{aligned}$$

Define also

$$\Lambda_{\geq \lambda}^\pm = \sum_{\mu \geq \lambda} \Lambda_\mu^\pm, \quad \Lambda_{< \lambda}^\pm = 1 - \Lambda_{\geq \lambda}^\pm.$$

2.2. Function spaces: U^p - and V^p -spaces. These function spaces were originally introduced in the unpublished work of Tataru on the wave map problem and then in Koch and Tataru [17] in the context of nonlinear spaces. The spaces have since been used to obtain critical results in different problems related to dispersive equations (see, e.g., [12, 13, 15]) and they serve as a useful replacement of $X^{s,b}$ -spaces in the limiting cases. For the convenience of the reader we list the definitions and some properties of these spaces.

Let \mathcal{Z} be the collection of finite partitions $-\infty < t_0 < \dots < t_K \leq \infty$ of \mathbb{R} . If $t_K = \infty$, we use the convention $u(t_K) := 0$ for all functions $u : \mathbb{R} \rightarrow L^2$.

DEFINITION 1. Let $1 \leq p < \infty$. A U^p atom is defined by a step function $a : \mathbb{R} \rightarrow L^2$ of the form

$$a(t) = \sum_{k=1}^K \mathbb{1}_{[t_{k-1}, t_k)}(t) \phi_{k-1},$$

where

$$\{t_k\}_{k=0}^K \in \mathcal{Z}, \quad \{\phi_k\}_{k=0}^{K-1} \subset L^2 \text{ with } \sum_{k=0}^{K-1} \|\phi_k\|_{L^2}^p = 1.$$

The atomic space $U^p(\mathbb{R}; L^2)$ is defined to be the collection of functions $u : \mathbb{R} \rightarrow L^2$ of the form

$$(2.1) \quad u = \sum_{j=1}^{\infty} \lambda_j a_j, \quad \text{where } a_j \text{'s are } U^p \text{ atoms and } \{\lambda_j\}_{j \in \mathbb{N}} \in \ell^1$$

with the norm

$$\|u\|_{U^p} := \inf_{\text{representation (2.1)}} \sum_{j=1}^{\infty} |\lambda_j|.$$

DEFINITION 2. Let $1 \leq p < \infty$.

(i) Define $V^p(\mathbb{R}, L^2)$ as the space of all functions $v : \mathbb{R} \rightarrow L^2$ for which the norm

$$(2.2) \quad \|v\|_{V^p} := \sup_{\{t_k\}_{k=0}^K \in \mathcal{Z}} \left(\sum_{k=1}^K \|v(t_k) - v(t_{k-1})\|_{L^2}^p \right)^{\frac{1}{p}}$$

is finite.

(ii) Likewise, let $V_-^p(\mathbb{R}, L^2)$ denote the normed space of all functions $v : \mathbb{R} \rightarrow L^2$ such that $\lim_{t \rightarrow -\infty} v(t) = 0$ and $\|v\|_{V^p} < \infty$, endowed with the norm (2.2).

(iii) We let $V_{rc}^p(\mathbb{R}, L^2)$ ($V_{-,rc}^p(\mathbb{R}, L^2)$) denote the closed subspace of all right-continuous $V^p(\mathbb{R}, L^2)$ functions ($V_-^p(\mathbb{R}, L^2)$ functions).

2.3. Properties of U^p - and V^p -spaces. We collect some useful properties of these spaces. For more details about the spaces and proofs we refer to [12, 13].

PROPOSITION 1. Let $1 \leq p < q < \infty$. Then we have the following:

- (i) $U^p(\mathbb{R}, L^2)$ is a Banach space.
- (ii) The embeddings $U^p(\mathbb{R}, L^2) \subset U^q(\mathbb{R}, L^2) \subset L^\infty(\mathbb{R}; L^2)$ are continuous.
- (iii) Every $u \in U^p(\mathbb{R}, L^2)$ is right continuous. Moreover, $\lim_{t \rightarrow -\infty} u(t) = 0$.

PROPOSITION 2. Let $1 \leq p < q < \infty$. Then we have the following:

- (i) The spaces $V^p(\mathbb{R}, L^2)$, $V_{rc}^p(\mathbb{R}, L^2)$, $V_-^p(\mathbb{R}, L^2)$, and $V_{-,rc}^p(\mathbb{R}, L^2)$ are Banach spaces.

- (ii) The embedding $U^p(\mathbb{R}, L^2) \subset V_{-,rc}^p(\mathbb{R}, L^2)$ is continuous.
- (iii) The embeddings $V^p(\mathbb{R}, L^2) \subset V^q(\mathbb{R}, L^2)$ and $V_-^p(\mathbb{R}, L^2) \subset V_-^q(\mathbb{R}, L^2)$ are continuous.
- (iv) The embedding $V_{-,rc}^p(\mathbb{R}, L^2) \subset U^q(\mathbb{R}, L^2)$ is continuous.

LEMMA 1 (see [18]). Let $p > 2$ and $v \in V^2(\mathbb{R}, L^2)$. There exists $L = L(p) > 0$ such that for all $N \geq 1$, there exist $w \in U^2(\mathbb{R}, L^2)$ and $z \in U^p(\mathbb{R}, L^2)$ with

$$v = w + z$$

and

$$\frac{L}{N} \|w\|_{U^2} + e^N \|z\|_{U^p} \lesssim \|v\|_{V^2}.$$

THEOREM 3. Let $1 < p < \infty$. Then

$$V^p = (U^p)^*$$

in the sense that there is a bilinear form B such that the mapping

$$T : V^p \rightarrow (U^p)^*, \quad T(v) := B(\cdot, v)$$

is an isometric isomorphism.

PROPOSITION 3. Let $1 < p < \infty$ and $u \in V_-^1$ be absolutely continuous on compact intervals and $v \in V^p$. Then

$$B(u, v) = - \int_{-\infty}^{\infty} \langle u'(t), v(t) \rangle dt.$$

2.4. U_{\pm}^p - and V_{\pm}^p -spaces and their properties. We now introduce U^p -, V^p -type spaces that are adapted to the linear propagators $S_m(\pm t) = e^{\mp it(D)}$.

DEFINITION 3. We define $U_{\pm}^p(\mathbb{R}, L^2)$ (and $V_{\pm}^p(\mathbb{R}, L^2)$, resp.) to be the spaces of all functions $u : \mathbb{R} \mapsto L^2(\mathbb{R}^3)$ such that $t \rightarrow S_m(\mp t)u$ is in $U^p(\mathbb{R}, L^2)$ (resp., $V^p(\mathbb{R}, L^2)$), with the respective norms

$$\begin{aligned} \|u\|_{U_{\pm}^p} &= \|S_m(\mp t)u\|_{U^p}, \\ \|u\|_{V_{\pm}^p} &= \|S_m(\mp t)u\|_{V^p}. \end{aligned}$$

We use $V_{rc,\pm}^p(\mathbb{R}, L^2)$ to denote the subspace of right-continuous functions in $V_{\pm}^p(\mathbb{R}, L^2)$.

Remark 2. Lemma 1 naturally extends to the spaces $U_{\pm}^p(\mathbb{R}, L^2)$ and $V_{\pm}^p(\mathbb{R}, L^2)$.

LEMMA 2 (interpolation). Let $p > 2$ and $u_j := P_{\lambda_j} u_j$ ($j = 1, \dots, 4$). For $u_j \in U_{\epsilon_j}^2$ and $u_4 \in V_{\epsilon_4}^2$, where $\epsilon_j \in \{+, -\}$, define

$$I(\lambda) := \left| \int V * \langle \beta u_1, u_2 \rangle \cdot \langle \beta u_3, u_4 \rangle dt dx \right|.$$

Assume that the following estimate holds:

$$(2.3) \quad I(\lambda) \lesssim \min \left(C_1(\lambda) \prod_{j=1}^3 \|u_j\|_{U_{\epsilon_j}^2} \|u_4\|_{U_{\epsilon_4}^2}, C_2(\lambda) \prod_{j=1}^3 \|u_j\|_{U_{\epsilon_j}^2} \|u_4\|_{U_{\epsilon_4}^p} \right).$$

Then

$$(2.4) \quad I(\lambda) \lesssim C_1(\lambda) [1 + \ln(C_2(\lambda))] \prod_{j=1}^3 \|u_j\|_{U_{\epsilon_j}^2} \|u_4\|_{V_{\epsilon_4}^2}.$$

Proof. Given $N \geq 1$, we use Lemma 1 to decompose $u_4 \in V_{\epsilon_4}^2$ into $u_4 = u + v$, where $u \in U_{\epsilon_4}^2$ and $v \in U_{\epsilon_4}^p$, such that

$$(2.5) \quad \begin{cases} \|u\|_{U_{\epsilon_4}^2} \lesssim \frac{N}{L} \|u_4\|_{V_{\epsilon_4}^2}, \\ \|v\|_{U_{\epsilon_4}^p} \lesssim e^{-N} \|u_4\|_{V_{\epsilon_4}^2}. \end{cases}$$

We now use (2.3) and (2.5) to obtain

$$\begin{aligned} I(\lambda) &\lesssim C_1(\lambda) \prod_{j=1}^3 \|u_j\|_{U_{\epsilon_j}^2} \|u\|_{U_{\epsilon_4}^2} + C_2(\lambda) \prod_{j=1}^3 \|u_j\|_{U_{\epsilon_j}^2} \|v\|_{U_{\epsilon_4}^p} \\ &\lesssim \left[\frac{N}{L} C_1(\lambda) + e^{-N} C_2(\lambda) \right] \prod_{j=1}^3 \|u_j\|_{U_{\epsilon_j}^2} \|u_4\|_{V_{\epsilon_4}^2}. \end{aligned}$$

This will imply the desired estimate (2.4) if we choose

$$N = 1 + \ln[C_2(\lambda)]. \quad \square$$

LEMMA 3 (modulation estimates; see [12]). *Let $\lambda \in 2^k$, where $k \in \mathbb{Z}$, and $p \geq 2$. Then*

$$(2.6) \quad \|\Lambda_{\lambda}^{\pm} u\|_{L^2} \lesssim \lambda^{-\frac{1}{2}} \|u\|_{V_{\pm}^2},$$

$$(2.7) \quad \|\Lambda_{\geq \lambda}^{\pm} u\|_{L^2} \lesssim \lambda^{-\frac{1}{2}} \|u\|_{V_{\pm}^2},$$

$$(2.8) \quad \|\Lambda_{< \lambda}^{\pm} u\|_{V_{\pm}^p} \lesssim \|u\|_{V_{\pm}^p}, \quad \|\Lambda_{\geq \lambda}^{\pm} u\|_{V_{\pm}^p} \lesssim \|u\|_{V_{\pm}^p},$$

$$(2.9) \quad \|\Lambda_{< \lambda}^{\pm} u\|_{U_{\pm}^p} \lesssim \|u\|_{U_{\pm}^p}, \quad \|\Lambda_{\geq \lambda}^{\pm} u\|_{U_{\pm}^p} \lesssim \|u\|_{U_{\pm}^p}.$$

LEMMA 4 (transfer principle). *Let*

$$T : L^2 \times \dots \times L^2 \rightarrow L_{loc}^1(\mathbb{R}^3; \mathbb{C})$$

be a multilinear operator and suppose that we have

$$\|T(S_m(\pm t)\phi_1, \dots, S_m(\pm t)\phi_k)\|_{L_t^p L_x^r(\mathbb{R} \times \mathbb{R}^3)} \lesssim \prod_{j=1}^k \|\phi_j\|_{L_x^2(\mathbb{R}^3)}$$

for some $1 \leq p, r \leq \infty$. Then

$$\|T(u_1, \dots, u_k)\|_{L_t^p L_x^r(\mathbb{R} \times \mathbb{R}^3)} \lesssim \prod_{j=1}^k \|u_j\|_{U_{\pm}^p}.$$

3. Linear and bilinear estimates for free waves.

3.1. Linear estimates. The following Strichartz estimate for wave-admissible pairs is well known.

LEMMA 5 (Wave-Strichartz). *Assume $m \geq 0$, $2 \leq r < \infty$, and $\frac{1}{q} + \frac{1}{r} = \frac{1}{2}$. Then*

$$\|S_m(\pm t)f\lambda\|_{L_t^q L_x^r} \lesssim \lambda^{\frac{2}{q}} \|f\lambda\|_{L^2}.$$

Moreover, for all $u_{\lambda} \in U_{\pm}^q$, we have (by the transfer principle)

$$\|u_{\lambda}\|_{L_t^q L_x^r} \lesssim \lambda^{\frac{2}{q}} \|u_{\lambda}\|_{U_{\pm}^q}.$$

3.2. Bilinear estimates. The following lemma contains estimates for the convolution of two free waves. This generalizes the result of Foschi and Klainerman for $m = 0$ [11, Lemmas 4.1 and 4.4] to $m \geq 0$. The proof is given in section 7.

LEMMA 6 (convolution of free waves). For $m \geq 0$ define

$$I_+(f, g)(\tau, \xi) = \int_{\mathbb{R}^3} f(|\eta|)g(|\xi - \eta|)\delta(\tau - \langle \eta \rangle_m - \langle \xi - \eta \rangle_m) d\eta,$$

$$I_-(f, g)(\tau, \xi) = \int_{\mathbb{R}^3} f(|\eta|)g(|\xi - \eta|)\delta(\tau - \langle \eta \rangle_m + \langle \xi - \eta \rangle_m) d\eta.$$

Then the following hold:

(i) Estimate for I_+ :

$$(3.1) \quad I_+(f, g)(\tau, \xi) \simeq \frac{1}{|\xi|} \int_{a_-}^{a_+} r(\tau - r)f\left(\sqrt{r^2 - m^2}\right)g\left(\sqrt{(\tau - r)^2 - m^2}\right) dr,$$

where

$$a_{\pm} := a_{\pm}(\tau, \xi) = \frac{\tau}{2} \pm \frac{|\xi|}{2} \sqrt{\frac{\tau^2 - |\xi|^2 - 4m^2}{\tau^2 - |\xi|^2}}.$$

(ii) Estimate for I_- :

$$(3.2) \quad I_-(f, g)(\tau, \xi) \simeq \frac{1}{|\xi|} \int_{a_+}^{\infty} r(r - \tau)f\left(\sqrt{r^2 - m^2}\right)g\left(\sqrt{(r - \tau)^2 - m^2}\right) dr.$$

Lemma 6 is used to prove the key bilinear estimates in Lemma 7 below, which also generalizes the result of Foschi and Klainerman for $m = 0$ [11, Lemma 12.1] to $m \geq 0$. The proof is given in section 8.

LEMMA 7 (bilinear estimates for free waves). Let $m \geq 0$ and $\mu, \lambda_1, \lambda_2 \geq 1$. Then for all $f_{\lambda_1}, g_{\lambda_2} \in L_x^2$ we have the following:

(i) $(++)$ interaction:

$$\|P_{\mu}(S_m(t)f_{\lambda_1} \cdot S_m(t)g_{\lambda_2})\| \lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \lambda_1 \approx \lambda_2, \\ \mu \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases}$$

(ii) $(+-)$ interaction:

$$\|P_{\mu}(S_m(t)f_{\lambda_1} \cdot S_m(-t)g_{\lambda_2})\| \lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \lambda_1 \approx \lambda_2, \\ \mu^{\frac{1}{2}} \lambda_1^{\frac{1}{2}} \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases}$$

4. Null structure, null-form, and bilinear estimates.

4.1. Null structure. Here we reveal the null structure in the bilinear terms $\langle \beta\psi^+, \psi^{\pm} \rangle$. Taking the Fourier transform in space and then using the identities (1.7)–(1.9) we obtain

(4.1)

$$\begin{aligned} \mathcal{F}_x \langle \beta\Pi_m^+(D)\psi^+, \Pi_m^{\pm}(D)\psi^{\pm} \rangle(\xi) &= \iint_{\xi=\eta-\zeta} \langle \beta\Pi_m^+(\eta)\widehat{\psi}^+(\eta), \Pi_m^{\pm}(\zeta)\widehat{\psi}^{\pm}(\zeta) \rangle d\eta d\zeta \\ &= \iint_{\xi=\eta-\zeta} \langle \beta\widehat{\psi}^+(\eta), \Pi_m^-(\eta)\Pi_m^{\pm}(\zeta)\widehat{\psi}^{\pm}(\zeta) \rangle d\eta d\zeta \\ &\quad + m \iint_{\xi=\eta-\zeta} \langle \eta \rangle_m^{-1} \langle \widehat{\psi}^+(\eta), \widehat{\psi}^{\pm}(\zeta) \rangle d\eta d\zeta. \end{aligned}$$

We use the notation $\hat{\xi} = \langle \xi \rangle_m^{-1} \xi$. Now we compute.^{2,3}

$$\begin{aligned} 4\Pi_m^-(\eta)\Pi_m^\pm(\zeta) &= \left(I - \frac{1}{\langle \eta \rangle_m} [\boldsymbol{\alpha} \cdot \eta + m\beta] \right) \left(I \pm \frac{1}{\langle \zeta \rangle_m} [\boldsymbol{\alpha} \cdot \zeta + m\beta] \right) \\ &= I \mp (\boldsymbol{\alpha} \cdot \hat{\eta})(\boldsymbol{\alpha} \cdot \hat{\zeta}) - (\hat{\eta} \mp \hat{\zeta}) \cdot \boldsymbol{\alpha} + r^\pm(\eta, \zeta) \\ &= (1 \mp \hat{\eta} \cdot \hat{\zeta})I \mp i(\hat{\eta} \times \hat{\zeta}) \cdot S - (\hat{\eta} \mp \hat{\zeta}) \cdot \boldsymbol{\alpha} + r^\pm(\eta, \zeta), \end{aligned}$$

where

$$r^\pm(\eta, \zeta) = \mp \frac{[(\eta - \zeta) \cdot \boldsymbol{\alpha}]m\beta - (\langle \eta \rangle \mp \langle \zeta \rangle)m\beta + m^2 I}{\langle \eta \rangle_m \langle \zeta \rangle_m}.$$

We can write

$$\begin{aligned} (1 \mp \hat{\eta} \cdot \hat{\zeta})I &= q_1^\pm(\eta, \zeta) + b_1^\pm(\eta, \zeta), \\ -(\hat{\eta} \mp \hat{\zeta}) \cdot \boldsymbol{\alpha} &= q_2^\pm(\eta, \zeta) + b_2^\pm(\eta, \zeta), \end{aligned}$$

where

$$(4.2) \quad \begin{cases} q_1^\pm(\eta, \zeta) = (|\hat{\eta}||\hat{\zeta}| \mp \hat{\eta} \cdot \hat{\zeta})I, & q_2^\pm(\eta, \zeta) = -(\hat{\eta}|\hat{\zeta}| \mp \hat{\zeta}|\hat{\eta}|) \cdot \boldsymbol{\alpha}, \\ b_1^\pm(\eta, \zeta) = (1 - |\hat{\eta}||\hat{\zeta}|)I, & b_2^\pm(\eta, \zeta) = -\frac{[\eta(\langle \zeta \rangle_m - |\zeta|) \mp \zeta(\langle \eta \rangle_m - |\eta|)] \cdot \boldsymbol{\alpha}}{\langle \eta \rangle_m \langle \zeta \rangle_m}. \end{cases}$$

Setting

$$(4.3) \quad q_3^\pm(\eta, \zeta) := \mp i(\hat{\eta} \times \hat{\zeta}) \cdot S, \quad b_3^\pm(\eta, \zeta) := r^\pm(\eta, \zeta),$$

we can write

$$(4.4) \quad 4\Pi_m^-(\eta)\Pi_m^\pm(\zeta) = \sum_{j=1}^3 [q_j^\pm(\eta, \zeta) + b_j^\pm(\eta, \zeta)],$$

where q_j^\pm and b_j^\pm for $j = 1, 2, 3$ are given above.

Then in view of (4.1)–(4.4) we can write

$$(4.5) \quad \langle \beta \Pi_m^+(D)\psi^+, \Pi_m^\pm(D)\psi^\pm \rangle = \sum_{j=1}^3 Q_j(\psi^+, \psi^\pm) + \sum_{j=1}^4 B_j(\psi^+, \psi^\pm),$$

where

$$(4.6) \quad \begin{cases} Q_j(\psi^+, \psi^\pm) = \mathcal{F}_x^{-1} \iint_{\xi=\eta-\zeta} \langle \beta \hat{\psi}^+(\eta), q_j^\pm(\eta, \zeta) \hat{\psi}^\pm(\zeta) \rangle d\eta d\zeta, \\ B_j(\psi^+, \psi^\pm) = \mathcal{F}_x^{-1} \iint_{\xi=\eta-\zeta} \langle \beta \hat{\psi}^+(\eta), b_j^\pm(\eta, \zeta) \hat{\psi}^\pm(\zeta) \rangle d\eta d\zeta \end{cases}$$

²In view of (1.6) we have $I \mp (\boldsymbol{\alpha} \cdot \hat{\eta})(\boldsymbol{\alpha} \cdot \hat{\zeta}) = I \mp \boldsymbol{\alpha}^j \boldsymbol{\alpha}^k \hat{\eta}_j \hat{\zeta}_k = I \mp \delta^{jk} \hat{\eta}_j \hat{\zeta}_k I + i \hat{\eta}_j \hat{\zeta}_k \epsilon^{jkl} S_l = (1 \mp \hat{\eta} \cdot \hat{\zeta})I \mp i(\hat{\eta} \times \hat{\zeta}) \cdot S$.

³If $m = 0$, then $\hat{\eta} = |\eta|^{-1}\eta$, $\hat{\zeta} = |\zeta|^{-1}\zeta$ and $r^\pm(\eta, \zeta) = 0$. Hence, $4\Pi_0^-(\eta)\Pi_0^\pm(\zeta) = (1 \mp (|\eta||\zeta|)^{-1}\eta \cdot \zeta)I \mp i(|\eta||\zeta|)^{-1}(\eta \times \zeta) \cdot S - (|\eta|^{-1}\eta \mp |\zeta|^{-1}\zeta) \cdot \boldsymbol{\alpha}$ which coincides with the null structure found in [7, Lemma 2].

with

$$(4.7) \quad b_4^\pm(\eta, \zeta) = m\langle \eta \rangle_m^{-1} \beta.$$

As we show below the Q_j 's are all null forms. The B_j 's on the other hand, are not. Nevertheless, these terms are more regular than the Q_j 's with one full derivative; see the estimates in Lemma 10 below. Thus, we have decomposed $\langle \beta \Pi_m^+(D)\psi^+, \Pi_m^\pm(D)\psi^\pm \rangle$ into a sum of bilinear null forms and generic bilinear terms that are smoother. It is worth noting that if $m = 0$, then all the B_j 's are zero (see the footnote above), and hence we only have the null forms on the right-hand side of (4.5).

The null symbols q_j^\pm satisfy the following estimates.

LEMMA 8. *Let $a \in [0, \frac{1}{2}]$. Then for $j = 1, 2, 3$ we have*

$$(4.8) \quad \begin{cases} |q_j^+(\eta, \zeta)| \lesssim \left[\frac{|\eta - \zeta| (|\eta - \zeta| - \|\eta\| - \|\zeta\|)}{\langle \eta \rangle_m \langle \zeta \rangle_m} \right]^a, \\ |q_j^-(\eta, \zeta)| \lesssim \left[\frac{(|\eta| + \|\zeta\|) (|\eta| + \|\zeta\| - |\eta - \zeta|)}{\langle \eta \rangle_m \langle \zeta \rangle_m} \right]^a. \end{cases}$$

Proof. First note that

$$(4.9) \quad |q_j^\pm(\eta, \zeta)| \lesssim 1.$$

Moreover, for two vectors η and ζ we have the following estimates (see, e.g., [11, Lemma 13.2]):

$$(4.10) \quad \begin{cases} |q_1^+(\eta, \zeta)| \sim \frac{|\eta - \zeta| (|\eta - \zeta| - \|\eta\| - \|\zeta\|)}{\langle \eta \rangle_m \langle \zeta \rangle_m}, \\ |q_1^-(\eta, \zeta)| \sim \frac{(|\eta| + \|\zeta\|) (|\eta| + \|\zeta\| - |\eta - \zeta|)}{\langle \eta \rangle_m \langle \zeta \rangle_m}, \\ |q_j^+(\eta, \zeta)| \lesssim \left[\frac{|\eta - \zeta| (|\eta - \zeta| - \|\eta\| - \|\zeta\|)}{\langle \eta \rangle_m \langle \zeta \rangle_m} \right]^{\frac{1}{2}}, \\ |q_j^-(\eta, \zeta)| \lesssim \left[\frac{(|\eta| + \|\zeta\|) (|\eta| + \|\zeta\| - |\eta - \zeta|)}{\langle \eta \rangle_m \langle \zeta \rangle_m} \right]^{\frac{1}{2}}, \end{cases}$$

where $j = 2, 3$. Now interpolation between (4.9) and (4.10) gives the desired estimates in (4.8). \square

4.2. Null-form estimates. We now prove bilinear null-form estimates for two free solutions $S_m(t)f$ and $S_m(\pm t)g$ of the Dirac equation.

LEMMA 9 (null-form estimates for free waves). *Let $m \geq 0$ and $\mu, \lambda_1, \lambda_2 \geq 1$. Then we have the following null-form estimates:*

(i) *(++) interaction:*

$$\|P_\mu Q_j(S_m(t)f_{\lambda_1}, S_m(t)g_{\lambda_2})\| \lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \lambda_1 \approx \lambda_2, \\ \mu(\mu/\lambda_1)^{\frac{1}{2}} \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases}$$

(ii) *(+-) interaction:*

$$\|P_\mu Q_j(S_m(t)f_{\lambda_1}, S_m(-t)g_{\lambda_2})\| \lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \lambda_1 \approx \lambda_2, \\ \mu \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases}$$

Proof. By (4.6) we have

$$\begin{aligned} & \left| \mathcal{F}_{t,x}[Q_j(S_m(t)f_{\lambda_1}, S_m(\pm t)g_{\lambda_2})](\tau, \xi) \right| \\ &= \left| \iint_{\xi=\eta-\zeta} \rho_\mu(|\eta-\zeta|) \langle \beta \widehat{f_{\lambda_1}}(\eta), q_j^\pm(\eta, \zeta) \widehat{g_{\lambda_2}}(\zeta) \rangle \delta(\tau + \langle \eta \rangle_m \mp \langle \zeta \rangle_m) d\eta d\zeta \right| \\ &\lesssim \iint_{\xi=\eta-\zeta} \rho_\mu(|\eta-\zeta|) |q_j^\pm(\eta, \zeta)| |\widehat{f_{\lambda_1}}(\eta)| |\widehat{g_{\lambda_2}}(\zeta)| \delta(\tau + \langle \eta \rangle_m \mp \langle \zeta \rangle_m) d\eta d\zeta, \end{aligned}$$

where on the second line the sign change to \mp in the delta function is because of the complex conjugation in $\langle \cdot, \cdot \rangle$.

By (4.8) we have

$$(4.11) \quad |q_j^+(\eta, \zeta)| \lesssim \left(\frac{\mu(\mu \wedge \lambda_1 \wedge \lambda_2)}{\lambda_1 \lambda_2} \right)^{\frac{1}{2}} \quad \text{and} \quad |q_j^-(\eta, \zeta)| \lesssim 1,$$

where for the estimate on q_j^+ we used

$$|\eta - \zeta| - \|\eta\| - \|\zeta\| \lesssim \mu \wedge \lambda_1 \wedge \lambda_2.$$

Indeed, this is obvious if $\mu \lesssim \lambda_1 \sim \lambda_2$. Now assume $\lambda_2 \ll \lambda_1 \sim \mu$. Then

$$|\eta - \zeta| - \|\eta\| - \|\zeta\| = \frac{|\eta - \zeta|^2 - (\|\eta\| - \|\zeta\|)^2}{|\eta - \zeta| + \|\eta\| - \|\zeta\|} = \frac{2\|\eta\|\|\zeta\| - 2\eta \cdot \zeta}{|\eta - \zeta| + \|\eta\| - \|\zeta\|} \lesssim \lambda_2.$$

The case $\lambda_1 \ll \lambda_2 \sim \mu$ also follows by symmetry.

Now using the estimate for q_j^+ in (4.11) we have for the $(++)$ interaction

$$\begin{aligned} & \left| \mathcal{F}_{t,x}[P_\mu Q_j(S_m(t)f_{\lambda_1}, S_m(t)g_{\lambda_2})](\tau, \xi) \right| \\ &\lesssim \left(\frac{\mu(\mu \wedge \lambda_1 \wedge \lambda_2)}{\lambda_1 \lambda_2} \right)^{\frac{1}{2}} \iint_{\xi=\eta-\zeta} \rho_\mu(|\eta-\zeta|) |\widehat{f_{\lambda_1}}(\eta)| |\widehat{g_{\lambda_2}}(\zeta)| \delta(\tau + \langle \eta \rangle_m - \langle \zeta \rangle_m) d\eta d\zeta \\ &= \left(\frac{\mu(\mu \wedge \lambda_1 \wedge \lambda_2)}{\lambda_1 \lambda_2} \right)^{\frac{1}{2}} \mathcal{F}_{t,x} \left[P_\mu \left(S(t) \mathcal{F}_x^{-1}(|\widehat{f_{\lambda_1}}|) \cdot S(-t) \mathcal{F}_x^{-1}(|\widehat{g_{\lambda_2}}|) \right) \right] (\tau, \xi). \end{aligned}$$

By Plancherel and Lemma 7(ii) we obtain

$$\begin{aligned} & \|P_\mu Q_j(S_m(t)f_{\lambda_1}, S_m(t)g_{\lambda_2})\| \\ &\lesssim \left(\frac{\mu(\mu \wedge \lambda_1 \wedge \lambda_2)}{\lambda_1 \lambda_2} \right)^{\frac{1}{2}} \left\| P_\mu \left(S_m(t) \mathcal{F}_x^{-1}(|\widehat{f_{\lambda_1}}|) \cdot S_m(-t) \mathcal{F}_x^{-1}(|\widehat{g_{\lambda_2}}|) \right) \right\| \\ &\lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \lambda_1 \approx \lambda_2, \\ \mu(\mu/\lambda_1)^{\frac{1}{2}} \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases} \end{aligned}$$

Similarly, we use the estimate for q_j^- in (4.11) to estimate the $(+-)$ interaction as

$$\begin{aligned} & \left| \mathcal{F}_{t,x}[P_\mu Q_j(S(t)f_{\lambda_1}, S(-t)g_{\lambda_2})](\tau, \xi) \right| \\ &\lesssim \iint_{\xi=\eta-\zeta} \rho_\mu(|\eta-\zeta|) |q_j^-(\eta, \zeta)| |\widehat{f_{\lambda_1}}(\eta)| |\widehat{g_{\lambda_2}}(\zeta)| \delta(\tau + \langle \eta \rangle_m + \langle \zeta \rangle_m) d\eta \\ &= \mathcal{F}_{t,x} \left[P_\mu \left(S_m(t) \mathcal{F}_x^{-1}(|\widehat{f_{\lambda_1}}|) \cdot S_m(t) \mathcal{F}_x^{-1}(|\widehat{g_{\lambda_2}}|) \right) \right] (\tau, \xi). \end{aligned}$$

By Plancherel and Lemma 7(i) we obtain

$$\begin{aligned} \|P_\mu Q_j(S_m(t)f_{\lambda_1}, S_m(-t)g_{\lambda_2})\| &\lesssim \left\| P_\mu \left(S_m(t)\mathcal{F}_x^{-1}(|\widehat{f_{\lambda_1}}|) \cdot S_m(t)\mathcal{F}_x^{-1}(|\widehat{g_{\lambda_2}}|) \right) \right\| \\ &\lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \lambda_1 \approx \lambda_2, \\ \mu \|f_{\lambda_1}\| \|g_{\lambda_2}\| & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases} \quad \square \end{aligned}$$

Applying Lemma 4 (the transfer principle) to Lemma 9 we obtain the following.

COROLLARY 1 (null-form estimates in the U^2 -space). *Let $m \geq 0$ and $\mu, \lambda_1, \lambda_2 \geq 1$.*

(i) $(++)$ interaction: *For all $u_{\lambda_1}, v_{\lambda_2} \in U_+^2$ we have*

$$\|P_\mu Q_j(u_{\lambda_1}, v_{\lambda_2})\| \lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|u_{\lambda_1}\|_{U_+^2} \|v_{\lambda_2}\|_{U_+^2} & \text{if } \lambda_1 \approx \lambda_2, \\ \mu(\mu/\lambda_1)^{\frac{1}{2}} \|u_{\lambda_1}\|_{U_+^2} \|v_{\lambda_2}\|_{U_+^2} & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases}$$

(ii) $(+-)$ interaction: *For all $u_{\lambda_1} \in U_+^2$ and $v_{\lambda_2} \in U_-^2$ we have*

$$\|P_\mu Q_j(u_{\lambda_1}, v_{\lambda_2})\| \lesssim \begin{cases} (\lambda_1 \wedge \lambda_2) \|u_{\lambda_1}\|_{U_+^2} \|v_{\lambda_2}\|_{U_-^2} & \text{if } \lambda_1 \approx \lambda_2, \\ \mu \|u_{\lambda_1}\|_{U_+^2} \|v_{\lambda_2}\|_{U_-^2} & \text{if } \mu \lesssim \lambda_1 \sim \lambda_2. \end{cases}$$

4.3. Bilinear estimates. In this section we express the bilinear terms in (4.6), Q_j and B_j , in physical space. We then apply Cauchy–Schwarz and Strichartz estimates to derive bilinear estimates for Q_j and B_j .

LEMMA 10. *Let Q denote any one of the Q_j ’s ($j = 1, \dots, 3$) and B denote any one of the B_j ’s ($j = 1, \dots, 4$). For $\lambda_1, \lambda_2 \geq 1$ assume that $u_{\lambda_1} \in V_\pm^2$ and $v_{\lambda_2} \in V_{\pm'}^2$, where \pm and \pm' are two independent signs. Then*

$$(4.12) \quad \|P_\mu Q(u_{\lambda_1}, v_{\lambda_2})\| \lesssim (\lambda_1 \lambda_2)^{\frac{1}{2}} \|u_{\lambda_1}\|_{U_\pm^4} \|v_{\lambda_2}\|_{U_{\pm'}^4},$$

$$(4.13) \quad \|P_\mu Q(u_{\lambda_1}, v_{\lambda_2})\| \lesssim (\lambda_1 \lambda_2)^{\frac{1}{2}} \|u_{\lambda_1}\|_{V_\pm^2} \|v_{\lambda_2}\|_{V_{\pm'}^2},$$

$$(4.14) \quad \|P_\mu B(u_{\lambda_1}, v_{\lambda_2})\| \lesssim \frac{(\lambda_1 \lambda_2)^{\frac{1}{2}}}{(\lambda_1 \wedge \lambda_2)} \|u_{\lambda_1}\|_{V_\pm^2} \|v_{\lambda_2}\|_{V_{\pm'}^2}.$$

Proof. By Proposition 2(ii), the estimate (4.13) follows from (4.12). Thus, we only need to prove (4.12) and (4.14).

The null forms $Q_j(u, v)$ in (4.6) can be written in physical space as follows:

$$(4.15) \quad \begin{aligned} Q_1(u, v) &= \langle \beta R u, R v \rangle \mp \langle \beta R_j u, R^j v \rangle, \\ Q_2(u, v) &= \langle \beta R_j u, \alpha^j R v \rangle \pm \langle \beta R u, \alpha^j R_j v \rangle, \\ Q_3(u, v) &= \langle \beta R_1 u, \gamma R_2 v \rangle \pm \langle \beta R_2 u, \gamma R_1 v \rangle, \end{aligned}$$

where

$$R_j = \frac{\partial_j}{\langle D \rangle_m} \quad \text{and} \quad R = \frac{|D|}{\langle D \rangle_m}$$

are Riesz operators. These operators are bounded in L^p for $1 < p < \infty$, i.e.,

$$(4.16) \quad \|R_j f_\lambda\|_{L^p} \lesssim \|f_\lambda\|_{L^p} \quad \text{and} \quad \|R f_\lambda\|_{L^p} \lesssim \|f_\lambda\|_{L^p}.$$

Now by Hölder, (4.16) and Lemma 5 we have

$$\begin{aligned} \|P_\mu Q_j(u_{\lambda_1}, v_{\lambda_2})\| &\lesssim \|u_{\lambda_1}\|_{L_{t,x}^4} \|v_{\lambda_2}\|_{L_{t,x}^4} \\ &\lesssim (\lambda_1 \lambda_2)^{\frac{1}{2}} \|u_{\lambda_1}\|_{U_\pm^4} \|v_{\lambda_2}\|_{U_\pm^4}. \end{aligned}$$

Next we prove (4.14). The bilinear terms $B_j(u, v)$ in (4.6) can be written in physical space as follows:

$$\begin{aligned} B_1(u, v) &= \langle \beta(1-R)u, v \rangle + \langle \beta R u, (1-R)v \rangle, \\ B_2(u, v) &= -\langle \beta R_j u, \alpha^j (1-R)v \rangle \pm \langle (1-R)\beta u, \alpha^j R_j v \rangle, \\ (4.17) \quad B_3(u, v) &= \mp \langle u, \langle D \rangle_m^{-1} v \rangle + \langle \langle D \rangle_m^{-1} u, v \rangle \mp \langle R_j u, \alpha^j \langle D \rangle^{-1} v \rangle \\ &\quad \mp \langle \langle D \rangle_m^{-1} u, \alpha^j R_j v \rangle \mp \langle \beta \langle D \rangle_m^{-1} u, \langle D \rangle_m^{-1} v \rangle, \\ B_4(u, v) &= -\langle \langle D \rangle_m^{-1} u, v \rangle. \end{aligned}$$

Note that

$$(4.18) \quad \|\langle D \rangle_m^{-1} f\|_{L^2} \lesssim \langle \lambda \rangle_m^{-1} \|f\|_{L^2}$$

and

$$(4.19) \quad \|(1-R)f\|_{L^2} \lesssim \langle \lambda \rangle_m^{-2} \|f\|_{L^2},$$

where in the latter case we used Plancherel and the fact that

$$1 - \frac{|\xi|}{\langle \xi \rangle_m} = \frac{\langle \xi \rangle_m - |\xi|}{\langle \xi \rangle_m} = \frac{m^2}{\langle \xi \rangle_m (\langle \xi \rangle_m + |\xi|)} \sim m^2 \langle \xi \rangle_m^{-2}.$$

Now using Hölder, Lemma 5, Proposition 2(ii), and (4.16)–(4.19) we obtain

$$\begin{aligned} \|P_\mu B_1(u_{\lambda_1}, v_{\lambda_2})\| &\lesssim \|(1-R)u_{\lambda_1}\|_{L_{t,x}^4} \|v_{\lambda_2}\|_{L_{t,x}^4} + \|u_{\lambda_1}\|_{L_{t,x}^4} \|(1-R)v_{\lambda_2}\|_{L_{t,x}^4} \\ &\lesssim (\lambda_1 \lambda_2)^{\frac{1}{2}} \left\{ \|(1-R)u_{\lambda_1}\|_{U_\pm^4} \|v_{\lambda_2}\|_{U_\pm^4} + \|u_{\lambda_1}\|_{U_\pm^4} \|(1-R)v_{\lambda_2}\|_{U_\pm^4} \right\} \\ &\lesssim (\lambda_1 \lambda_2)^{\frac{1}{2}} \left\{ \|(1-R)u_{\lambda_1}\|_{V_\pm^2} \|v_{\lambda_2}\|_{V_\pm^2} + \|u_{\lambda_1}\|_{V_\pm^2} \|(1-R)v_{\lambda_2}\|_{V_\pm^2} \right\} \\ &\lesssim \frac{(\lambda_1 \lambda_2)^{\frac{1}{2}}}{(\lambda_1 \wedge \lambda_2)^2} \|u_{\lambda_1}\|_{V_\pm^2} \|v_{\lambda_2}\|_{V_\pm^2}. \end{aligned}$$

Similarly,

$$\|P_\mu B_2(u_{\lambda_1}, v_{\lambda_2})\| \lesssim \frac{(\lambda_1 \lambda_2)^{\frac{1}{2}}}{(\lambda_1 \wedge \lambda_2)^2} \|u_{\lambda_1}\|_{V_\pm^2} \|v_{\lambda_2}\|_{V_\pm^2},$$

and for $j = 3, 4$

$$\|P_\mu B_j(u_{\lambda_1}, v_{\lambda_2})\| \lesssim \frac{(\lambda_1 \lambda_2)^{\frac{1}{2}}}{(\lambda_1 \wedge \lambda_2)} \|u_{\lambda_1}\|_{V_\pm^2} \|v_{\lambda_2}\|_{V_\pm^2}, \quad \square$$

5. Reduction of Theorem 2 to nonlinear estimates. Let $I = [0, \infty)$. We define X_{\pm}^s to be the complete space of all functions $u : I \rightarrow L^2$ such that $P_{\mu}u \in U_{\pm}^2(I, L^2)$ for all $\mu \geq 1$, with the norm

$$\|u\|_{X_{\pm}^s} = \left(\sum_{\mu \geq 1} \mu^{2s} \|\mathbb{1}_I P_{\mu}u\|_{U_{\pm}^2}^2 \right)^{\frac{1}{2}} < \infty,$$

where

$$\|f\|_{U_{\pm}^2} = \|S_m(\mp t)f\|_{U^2}.$$

The Duhamel representation of (1.10)–(1.11) is given by

$$(5.1) \quad \psi^{\pm}(t) = S_m(\pm t)\psi_0^{\pm} + J_{m,\pm}(\psi)(t),$$

where

$$(5.2) \quad J_{m,\pm}(\psi)(t) = \Pi_m^{\pm}(D) \int_0^t S_m(\pm(t-t')) [(V * \langle \beta\psi, \psi \rangle)\beta\psi](t') dt'.$$

The linear part of (5.1) satisfies the following estimate:

$$(5.3) \quad \begin{aligned} \|S_m(\pm t)\psi_0^{\pm}\|_{X_{\pm}^s}^2 &= \sum_{\mu \geq 1} \mu^{2s} \|\mathbb{1}_I S_m(\pm t)P_{\mu}\psi_0^{\pm}\|_{U_{\pm}^2}^2 \\ &= \sum_{\mu \geq 1} \mu^{2s} \|\mathbb{1}_I P_{\mu}\psi_0^{\pm}\|_{U^2}^2 \\ &\sim \|\psi_0^{\pm}\|_{H^s}^2. \end{aligned}$$

So it remains to estimate $J_{m,\pm}(\psi)(t)$. To this end we let $\epsilon = (\epsilon_1, \epsilon_2, \epsilon_3)$, where $\epsilon_j \in \{+, -\}$. Since $\psi = \psi^+ + \psi^-$, where $\psi^{\pm} = \Pi_m^{\pm}(D)\psi$, we can write

$$J_{m,\pm}(\psi)(t) = \sum_{\epsilon_j \in \{+,-\}} J_{\pm}^{\epsilon}(\psi)(t),$$

where

$$(5.4) \quad J_{m,\pm}^{\epsilon}(\psi)(t) = i\Pi_m^{\pm}(D) \int_0^t S_m(\pm(t-t')) [(V * \langle \beta\psi^{\epsilon_1}, \psi^{\epsilon_2} \rangle)\beta\psi^{\epsilon_3}](t') dt'.$$

Theorem 2 will follow by a contraction argument from (5.3) and the following cubic estimates for $J_{m,\pm}(\psi)(t)$ (see subsection 5.3 below).

PROPOSITION 4. *Let $m \geq 0$ and $s > 0$. For all $\psi^{\pm} \in X_{\pm}^s$, we have*

$$\|J_{m,\pm}^{\epsilon}(\psi)\|_{X_{\pm}^s} \lesssim \prod_{j=1}^3 \|\psi^{\epsilon_j}\|_{X_{\pm}^s}.$$

5.1. Reduction of Proposition 4 to dyadic quadrilinear estimates. Due to time reversibility, we may assume that $\psi^{\pm}(t) = 0$ for $t < 0$. Let

$$\Psi^{\epsilon} = V * \langle \beta\psi^{\epsilon_1}, \psi^{\epsilon_2} \rangle \beta\psi^{\epsilon_3}.$$

By definition of U_{\pm}^2 , (5.4), Theorem 3, and Proposition 3, we have

$$\begin{aligned}
 (5.5) \quad & \|P_{\lambda} J_{m,\pm}^{\epsilon}(\psi)\|_{U_{\pm}^2} = \|S_m(\mp t) P_{\lambda} J_{m,\pm}^{\epsilon}(\psi)\|_{U^2} \\
 & = \left\| \Pi_m^{\pm}(D) P_{\lambda} \int_0^t S_m(\mp t') \Psi^{\epsilon}(t') dt' \right\|_{U^2} \\
 & = \sup_{\|\phi_{\lambda}\|_{V^2}=1} \left| B \left(\Pi_m^{\pm}(D) P_{\lambda} \int_0^t S_m(\mp t') \Psi^{\epsilon}(t') dt', \phi \right) \right| \\
 & = \sup_{\|\phi_{\lambda}\|_{V^2}=1} \left| \int_{\mathbb{R}^4} \langle \Psi^{\epsilon}, S_m(\pm t) P_{\lambda} \phi^{\pm} \rangle dt dx \right| \\
 & = \sup_{\|\phi_{\lambda}^{\pm}\|_{V_{\pm}^2}=1} \left| \int_{\mathbb{R}^4} V * \langle \beta \psi^{\epsilon_1}, \psi^{\epsilon_2} \rangle \langle \beta \psi^{\epsilon_3}, \phi_{\lambda}^{\pm} \rangle dt dx \right|,
 \end{aligned}$$

where Theorem 3 and Proposition 3 are used to obtain the third and fourth equality. Hence

$$\begin{aligned}
 (5.6) \quad & \|J_{m,\pm}^{\epsilon}(\psi)\|_{X_{\pm}^s}^2 \\
 & = \sum_{\lambda_4 \geq 1} \lambda_4^{2s} \|P_{\lambda_4} J_{m,\pm}^{\epsilon}(\psi)\|_{U_{\pm}^2}^2 \\
 & = \sum_{\lambda_4 \geq 1} \lambda_4^{2s} \sup_{\|\phi_{\lambda_4}^{\pm}\|_{V_{\pm}^2}=1} \left| \int_{\mathbb{R}^4} V * \langle \beta \psi^{\epsilon_1}, \psi^{\epsilon_2} \rangle \langle \beta \psi^{\epsilon_3}, \phi_{\lambda_4}^{\pm} \rangle dt dx \right|^2 \\
 & \lesssim \sum_{\lambda_4 \geq 1} \lambda_4^{2s} \sup_{\|\phi_{\lambda_4}^{\pm}\|_{V_{\pm}^2}=1} \left(\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \left| \int_{\mathbb{R}^4} V * \langle \beta \psi_{\lambda_1}^{\epsilon_1}, \psi_{\lambda_2}^{\epsilon_2} \rangle \langle \beta \psi_{\lambda_3}^{\epsilon_3}, \phi_{\lambda_4}^{\pm} \rangle dt dx \right| \right)^2.
 \end{aligned}$$

Set $\epsilon_4 := \pm$ and

$$I_m^{\epsilon}(\lambda) := \left| \int_{\mathbb{R}^4} V * \langle \beta \psi_{\lambda_1}^{\epsilon_1}, \psi_{\lambda_2}^{\epsilon_2} \rangle \langle \beta \psi_{\lambda_3}^{\epsilon_3}, \phi_{\lambda_4}^{\epsilon_4} \rangle dt dx \right|.$$

Observe that if ξ_j and ξ_4 are the spatial Fourier variables for the functions $\psi_{\lambda_j}^{\epsilon_j}$ and $\phi_{\lambda_4}^{\epsilon_4}$ one can see using Plancherel that the integral on the right vanishes unless

$$\xi_1 - \xi_2 + \xi_3 - \xi_4 = 0.$$

Consequently, for each $j = 1, \dots, 4$ it follows from the triangle inequality that the following conditions must be satisfied:

$$(5.7) \quad \lambda_j \leq 3 \max\{\lambda_k : k \neq j, k = 1, \dots, 4\}.$$

Moreover, if ξ_0 is the frequency variable for $\langle \beta \psi_{\lambda_1}^{\epsilon_1}, \psi_{\lambda_2}^{\epsilon_2} \rangle$ we have

$$\xi_0 = \xi_1 - \xi_2 = -\xi_3 + \xi_4.$$

Thus, if ξ_0 has dyadic size μ it follows from the triangle inequality that the following conditions must be satisfied:

$$(5.8) \quad \begin{cases} \mu \ll \lambda_1 \sim \lambda_2 & \text{or } \mu \sim \lambda_1 \vee \lambda_2, \\ \mu \ll \lambda_3 \sim \lambda_4 & \text{or } \mu \sim \lambda_4 \vee \lambda_3. \end{cases}$$

We denote the minimum, median, and maximum of $(\lambda_1, \lambda_2, \lambda_3)$ by λ_{\min} , λ_{med} , and λ_{\max} , respectively.

LEMMA 11. Assume $\lambda_j \geq 1$ and $\delta > 0$. Then for all $\psi_{\lambda_j}^\pm \in U_\pm^2$ and $\phi_{\lambda_4}^\pm \in V_\pm^2$ we have

$$I_m^\epsilon(\lambda) \lesssim \lambda_{\text{med}}^\delta \prod_{j=1}^3 \left\| \psi_{\lambda_j}^{\epsilon_j} \right\|_{U_{\epsilon_j}^2} \left\| \phi_{\lambda_4}^{\epsilon_4} \right\|_{V_{\epsilon_4}^2}.$$

The proof of Lemma 11 is given in section 6. Now if we set $c_{j,\lambda_j} := \|\psi_{\lambda_j}^{\epsilon_j}\|_{U_{\epsilon_j}^2}$, by definition

$$\|\lambda_j^s c_{j,\lambda_j}\|_{l_{\lambda_j}^2} = \|\psi^{\epsilon_j}\|_{X_{\epsilon_j}^s}.$$

Consequently, Proposition 4 follows from (5.6), Lemma 11, and the following lemma.

LEMMA 12. Let $s > \delta > 0$. Then for all $c_{j,\lambda_j} \in l_{\lambda_j}^2$ we have

$$\begin{aligned} S &:= \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \lambda_4^s \lambda_{\text{med}}^\delta \cdot c_{1,\lambda_1} c_{2,\lambda_2} c_{3,\lambda_3} \right]^2 \\ &\lesssim \prod_{j=1}^3 \|\lambda_j^s c_{j,\lambda_j}\|_{l_{\lambda_j}^2}^2. \end{aligned}$$

5.2. Proof of Lemma 12. Without loss of generality one could assume $\lambda_1 \leq \lambda_2 \leq \lambda_3$. We deal with the cases $\lambda_4 \sim \lambda_3$, $\lambda_4 \gg \lambda_3$ and $\lambda_4 \ll \lambda_3$, separately.

5.2.1. Case 1: $\lambda_4 \sim \lambda_3$. In this case we have

$$\begin{aligned} S &\lesssim \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \lambda_4^s (\lambda_1 \lambda_2)^\delta \cdot c_{1,\lambda_1} c_{2,\lambda_2} c_{3,\lambda_3} \right]^2 \\ &\lesssim \|\lambda_1^s c_{1,\lambda_1}\|_{l_{\lambda_1}^2}^2 \|\lambda_2^s c_{2,\lambda_2}\|_{l_{\lambda_2}^2}^2 \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_3 \sim \lambda_4} \lambda_4^s c_{3,\lambda_3} \right]^2 \\ &\lesssim \prod_{j=1}^3 \|\lambda_j^s c_{j,\lambda_j}\|_{l_{\lambda_j}^2}^2, \end{aligned}$$

where to obtain the second inequality, we used Cauchy–Schwarz in λ_1 and in λ_2 , and the fact that $\sum_{\lambda_j \geq 1} \lambda_j^{-2(s-\delta)} \lesssim 1$, since $s > \delta$.

5.2.2. Case 2: $\lambda_4 \gg \lambda_3$. We further divide this case into $\lambda_1 \ll \lambda_2$ and $\lambda_1 \sim \lambda_2$. Assume first $\lambda_1 \ll \lambda_2$. Then in view of (5.7) we have $\lambda_4 \sim \lambda_2$. Now we can use

Cauchy–Schwarz in λ_1 and in λ_3 to obtain

$$\begin{aligned} S &\lesssim \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \lambda_4^s (\lambda_1 \lambda_3)^\delta \cdot c_{1, \lambda_1} c_{2, \lambda_2} c_{3, \lambda_3} \right]^2 \\ &\lesssim \|\lambda_1^s c_{1, \lambda_1}\|_{l_{\lambda_1}^2}^2 \|\lambda_2^s c_{3, \lambda_3}\|_{l_{\lambda_3}^2}^2 \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_2 \sim \lambda_4} \lambda_4^s c_{2, \lambda_2} \right]^2 \\ &\lesssim \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2. \end{aligned}$$

Next assume $\lambda_1 \sim \lambda_2$. In view of (5.7) we have $\lambda_4 \lesssim \lambda_2$. Then we apply Cauchy–Schwarz in $\lambda_1 \sim \lambda_2$ and in λ_3 to obtain

$$\begin{aligned} S &\lesssim \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \lambda_4^s (\lambda_1 \lambda_3)^\delta \cdot c_{1, \lambda_1} c_{2, \lambda_2} c_{3, \lambda_3} \right]^2 \\ &\lesssim \left[\sum_{\lambda_4 \geq 1} \lambda_4^{2s} \lambda_4^{2(\delta-2s)} \right] \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2 \\ &\lesssim \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2. \end{aligned}$$

5.2.3. Case 3: $\lambda_4 \ll \lambda_3$. As above we further divide this case into $\lambda_1 \ll \lambda_2$ and $\lambda_1 \sim \lambda_2$. Assume first $\lambda_1 \ll \lambda_2$. In view of (5.7) we have $\lambda_2 \sim \lambda_3$. Then applying Cauchy–Schwarz first in λ_1 and then in $\lambda_2 \sim \lambda_3$ we obtain

$$\begin{aligned} S &\lesssim \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \lambda_4^s (\lambda_1 \lambda_2)^\delta \cdot c_{1, \lambda_1} c_{2, \lambda_2} c_{3, \lambda_3} \right]^2 \\ &\lesssim \left[\sum_{\lambda_4 \geq 1} \lambda_4^{2s} \lambda_4^{2(\delta-2s)} \right] \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2 \\ &\lesssim \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2. \end{aligned}$$

Assume next $\lambda_1 \sim \lambda_2$. By (5.7) we have $\lambda_3 \lesssim \lambda_2$. Applying Cauchy–Schwarz first in $\lambda_1 \sim \lambda_2$ and then in λ_3 we obtain

$$\begin{aligned} S &\lesssim \sum_{\lambda_4 \geq 1} \left[\sum_{\lambda_1, \lambda_2, \lambda_3 \geq 1} \lambda_4^s (\lambda_1 \lambda_3)^\delta \cdot c_{1, \lambda_1} c_{2, \lambda_2} c_{3, \lambda_3} \right]^2 \\ &\lesssim \left[\sum_{\lambda_4 \geq 1} \lambda_4^{2s} \lambda_4^{2(\delta-2s)} \right] \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2 \\ &\lesssim \prod_{j=1}^3 \|\lambda_j^s c_{j, \lambda_j}\|_{l_{\lambda_j}^2}^2. \end{aligned}$$

5.3. Proof of Theorem 2. We solve the integral equation (5.1) by contraction mapping techniques as follows. Define the mapping

$$(5.9) \quad \psi^\pm(t) = \mathcal{T}(\psi^\pm)(t) := S_m(\pm t)\psi_0^\pm + iJ_{m,\pm}(\psi)(t).$$

We look for the solution in the set

$$D_\delta = \left\{ \psi^\pm \in X_\pm^s : \|\psi^\pm\|_{X_\pm^s} \leq \delta \right\}.$$

For $\psi^\pm \in D_\delta$ and initial data of size $\|\psi_0^\pm\|_{H^s} \leq \varepsilon \ll \delta$, we have by Proposition 4

$$\|\mathcal{T}(\psi^\pm)\|_{X_\pm^s} \lesssim \varepsilon + \delta^3 \leq \delta$$

for small enough δ . Moreover, for solutions ψ^\pm and ϕ^\pm with the same data, one can show the difference estimate

$$\begin{aligned} \|\mathcal{T}(\psi^\pm) - \mathcal{T}(\phi^\pm)\|_{X_\pm^s} &\lesssim \left(\|\psi^\pm\|_{X_\pm^s} + \|\phi^\pm\|_{X_\pm^s} \right)^2 \|\psi^\pm - \phi^\pm\|_{X_\pm^s} \\ &\lesssim \delta^2 \|\psi^\pm - \phi^\pm\|_{X_\pm^s} \end{aligned}$$

whenever $\psi^\pm, \phi^\pm \in D_\delta$. Hence \mathcal{T} is a contraction on D_δ when $\delta \ll 1$, which implies the existence of a unique fixed point in D_δ solving the integral equation (5.9).

It thus remains to show scattering of a solution of (5.9) to a free solution as $t \rightarrow \infty$. By Propositions 2 and 4, we have for each μ

$$S_m(\mp t)P_\mu J_{m,\pm}(\psi) \in V_{-,rc}^2$$

and hence the limit as $t \rightarrow \infty$ exists for each μ . Combining this with

$$\sum_{\mu \geq 1} \mu^{2s} \|P_\mu J_{m,\pm}(\psi)\|_{V^2}^2 \lesssim 1$$

gives

$$\lim_{t \rightarrow \infty} S_m(\mp t)P_\mu J_{m,\pm}(\psi) := f_\pm \in H^s.$$

Hence for the solution ψ^\pm we have

$$\|S_m(\pm t)f_\pm - \psi^\pm(t)\|_{H^s} \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

6. Proof of Lemma 11. We use the notation

$$\psi_1 := \psi_{\lambda_1}^{\epsilon_1}, \quad \psi_2 := \psi_{\lambda_2}^{\epsilon_2}, \quad \psi_3 := \psi_{\lambda_3}^{\epsilon_3}, \quad \psi_4 := \psi_{\lambda_4}^{\epsilon_4}.$$

By symmetry we may set $\epsilon_1 = \epsilon_3 = +$ in the integral for I_m^ϵ , and thus we need to estimate

$$I(\lambda) := I_m^\epsilon(\lambda) = \left| \int_{\mathbb{R}^4} V * \langle \beta\psi_1, \psi_2 \rangle \cdot \langle \beta\psi_3, \psi_4 \rangle dt dx \right|$$

with $\epsilon_1 = \epsilon_3 = +$.

Let Q denote any one of the Q_l 's for $l = 1, \dots, 3$ and B denote any one of the B_l 's for $l = 1, \dots, 4$. In view of (4.5)–(4.6), it suffices to show for $\epsilon_1 = \epsilon_3 = +$ the estimates

$$(6.1) \quad I_k(\lambda) \lesssim \lambda_{\text{med}}^\delta \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2} \quad (k = 1, \dots, 4),$$

where

$$\begin{aligned} I_1(\lambda) &= \left| \int_{\mathbb{R}^4} V * Q(\psi_1, \psi_2) \cdot Q(\psi_3, \psi_4) \, dt dx \right|, \\ I_2(\lambda) &= \left| \int_{\mathbb{R}^4} V * B(\psi_1, \psi_2) \cdot Q(\psi_3, \psi_4) \, dt dx \right|, \\ I_3(\lambda) &= \left| \int_{\mathbb{R}^4} V * Q(\psi_1, \psi_2) \cdot B(\psi_3, \psi_4) \, dt dx \right|, \\ I_4(\lambda) &= \left| \int_{\mathbb{R}^4} V * B(\psi_1, \psi_2) \cdot B(\psi_3, \psi_4) \, dt dx \right|. \end{aligned}$$

In the arguments that follow we repeatedly use the following facts (see Propositions 1 and 2):

$$(6.2) \quad U_{\pm}^2 \subset U_{\pm}^p, \quad V_{\pm}^2 \subset U_{\pm}^p \quad \text{for } p > 2.$$

We shall also use the conditions in (5.8). We remark that in \mathbb{R}^3 , convolution with $V(x) = e^{-|x|}/|x|$ is (up to a multiplicative constant) the Fourier multiplier $\langle D \rangle^{-2}$ with symbol $\langle \xi \rangle^{-2}$.

6.1. Estimate for $I_4(\lambda)$. By the symmetry of our argument we may assume $\lambda_1 \leq \lambda_2$ and $\lambda_3 \leq \lambda_4$. Using Littlewood–Paley decomposition, Hölder, and the bilinear estimate (4.14), we obtain

$$\begin{aligned} I_4(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_{\mu} B(\psi_1, \psi_2)\| \|P_{\mu} B(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} (\lambda_1 \lambda_3)^{-\frac{1}{2}} (\lambda_2 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^4 \|\psi_j\|_{V_{\epsilon_j}^2} \\ &\lesssim \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}, \end{aligned}$$

where to sum up the third line we considered the following cases: $\lambda_1 \sim \lambda_2$ or $\lambda_1 \ll \lambda_2 \sim \mu$ and $\lambda_3 \sim \lambda_4$ or $\lambda_3 \ll \lambda_4 \sim \mu$.

6.2. Estimate for $I_3(\lambda)$. As in the previous subsection we may assume $\lambda_3 \leq \lambda_4$. Then using Littlewood–Paley decomposition, Hölder, the null-form estimates in Corollary 1, and the bilinear estimate (4.14), we obtain

$$\begin{aligned} I_3(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_{\mu} Q(\psi_1, \psi_2)\| \|P_{\mu} B(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \mu \lambda_3^{-\frac{1}{2}} \lambda_4^{\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{U_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{V_{\epsilon_j}^2} \\ &\lesssim \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}, \end{aligned}$$

where to sum up the second line we considered the cases $\lambda_3 \sim \lambda_4$ or $\lambda_3 \ll \lambda_4 \sim \mu$.

6.3. Estimate for $I_2(\lambda)$. By the symmetry of our argument we may assume $\lambda_1 \leq \lambda_2$ and $\lambda_3 \leq \lambda_4$.

6.3.1. Case $\lambda_3 \ll \lambda_4 \sim \mu$. As in the preceding subsections we use Hölder and the bilinear estimates (4.13) and (4.14) to obtain

$$\begin{aligned} I_2(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu B(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \lambda_1^{-\frac{1}{2}} (\lambda_2 \lambda_3 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^4 \|\psi_j\|_{V_{\epsilon_j}^2} \\ &\lesssim \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}, \end{aligned}$$

where to sum up the second line we considered the cases $\lambda_1 \sim \lambda_2$ or $\lambda_1 \ll \lambda_2 \sim \mu$.

6.3.2. Case $\lambda_3 \sim \lambda_4$.

Subcase 1: $\lambda_2 \gtrsim \lambda_3 \sim \lambda_4$. Then by Hölder, the bilinear estimate (4.14), and the null-form estimates in Corollary 1 we obtain

$$\begin{aligned} I_2(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu B(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \mu \lambda_1^{-\frac{1}{2}} \lambda_2^{\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \\ &\lesssim \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^2}, \end{aligned}$$

where we used $\lambda_1 \sim \lambda_2$ or $\lambda_1 \ll \lambda_2 \sim \mu$ to sum up the second line.

On the other hand, applying Hölder and the bilinear estimates (4.12) and (4.14) we obtain

$$\begin{aligned} I_2(\lambda) &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \lambda_1^{-\frac{1}{2}} (\lambda_2 \lambda_3 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^4} \\ &\lesssim \lambda_3 \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^4}, \end{aligned}$$

where we used $\lambda_1 \sim \lambda_2$ or $\lambda_1 \ll \lambda_2 \sim \mu$ to sum up the first line.

Now we use Lemma 2 to interpolate between the two estimates for $I_2(\lambda)$ above and obtain

$$I_2(\lambda) \lesssim \lambda_3^\delta \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}.$$

Subcase 2: $\lambda_2 \ll \lambda_3 \sim \lambda_4$. Since by assumption $\lambda_1 \leq \lambda_2$ we have $\mu \ll \lambda_3 \sim \lambda_4$. We separate this subcase further into (i) $\epsilon_4 = +$ and (ii) $\epsilon_4 = -$. Recall that $\epsilon_3 = +$.

(i) $\epsilon_4 = +$. By Hölder, the bilinear estimate (4.14) and the null-form estimate in Corollary 1(i) we obtain

$$\begin{aligned} I_2(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu B(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \lambda_1^{-\frac{1}{2}} \lambda_2^{\frac{1}{2}} \cdot \mu^{\frac{3}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \\ &\lesssim \lambda_3^{-\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^2}, \end{aligned}$$

where we used $\lambda_1 \sim \lambda_2$ or $\lambda_1 \ll \lambda_2 \sim \mu$ to sum up the second line.

On the other hand, similarly as in subcase 1 above we have

$$I_2(\lambda) \lesssim \lambda_3 \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^4}.$$

Then we use Lemma 2 to interpolate between the two estimates for I_2 above and obtain

$$I_2(\lambda) \lesssim \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}.$$

(ii) $\epsilon_4 = -$. This case is contained in Lemma 13 below.

6.4. Estimate for $I_1(\lambda)$. By the symmetry of our argument we may assume $\lambda_1 \leq \lambda_2$ and $\lambda_3 \leq \lambda_4$.

6.4.1. Case $\lambda_3 \ll \lambda_4 \sim \mu$. By Hölder, (4.14), and the null-form estimates in Corollary 1 we obtain

$$\begin{aligned} I_1(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu Q(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \sim \lambda} \langle \mu \rangle^{-2} \mu \lambda_3^{\frac{1}{2}} \lambda_4^{\frac{1}{2}} \prod_{j=1}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \prod_{j=4}^3 \|\psi_j\|_{V_{\epsilon_j}^2} \\ &\lesssim \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}. \end{aligned}$$

6.4.2. Case $\lambda_3 \sim \lambda_4 \gtrsim \mu$.

Subcase 1: $\lambda_2 \gtrsim \lambda_3 \sim \lambda_4$. By Hölder and the null-form estimates in Corollary 1 we obtain

$$\begin{aligned} I_1(\lambda) &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \|P_\mu Q(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{1 \leq \mu \lesssim \lambda_3} \langle \mu \rangle^{-2} \mu^2 \prod_{j=1}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \\ &\lesssim \ln(\lambda_3) \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^2}. \end{aligned}$$

On the other hand, by Hölder, (4.12), and the null-form estimates in Corollary 1 we have

$$\begin{aligned} I_1(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu Q(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \mu (\lambda_3 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{U_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^4} \\ &\lesssim \lambda_3 \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^4}. \end{aligned}$$

Then we interpolate the two estimates for $I_1(\lambda)$ above, using Lemma 2, and obtain

$$I_1(\lambda) \lesssim \lambda_3^\delta \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}.$$

Subcase 2: $\lambda_2 \ll \lambda_3 \sim \lambda_4$. Since by assumption $\lambda_1 \leq \lambda_2$ we have $\mu \ll \lambda_3 \sim \lambda_4$. We separate this subcase further into (i) $\epsilon_4 = +$ and (ii) $\epsilon_4 = -$. Recall that $\epsilon_3 = +$.
 (i) $\epsilon_4 = +$. By Hölder and the null-form estimates in Corollary 1

$$\begin{aligned} I_1(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu Q(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{1 \leq \mu \lesssim \lambda_2} \langle \mu \rangle^{-2} \mu^{\frac{5}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \\ &\lesssim \lambda_2^{\frac{1}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^2}. \end{aligned}$$

On the other hand, by Hölder and (4.12) we have

$$\begin{aligned} I_1(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu Q(\psi_1, \psi_2)\| \|P_\mu Q(\psi_3, \psi_4)\| \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} (\lambda_1 \lambda_2 \lambda_3 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^4 \|\psi_j\|_{U_{\epsilon_j}^4} \\ &\lesssim \lambda_2 \lambda_3 \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^4}. \end{aligned}$$

We then use Lemma 2 to interpolate between the two estimates for $I_1(\lambda)$ above and obtain

$$I_1(\lambda) \lesssim \lambda_2^\delta \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}.$$

(ii) $\epsilon_4 = -$. This case is contained in Lemma 13 below.

6.5. A modulation lemma. Recall

$$\psi_1 = \psi_{\lambda_1}^{\epsilon_1}, \quad \psi_2 = \psi_{\lambda_2}^{\epsilon_2}, \quad \psi_3 = \psi_{\lambda_3}^{\epsilon_3}, \quad \psi_4 = \psi_{\lambda_4}^{\epsilon_4},$$

where $\epsilon_j \in \{+, -\}$ and $\epsilon_1 = \epsilon_3 = +$.

In the case $\epsilon_4 = -$ and $\lambda_1 \leq \lambda_2 \ll \lambda_3 \sim \lambda_4$ we exploit the nonresonance structure in the integral for $I_k(\lambda)$ to establish the required estimates for $I_1(\lambda)$ and $I_2(\lambda)$ (see subsections 6.3.2(ii) and 6.4.2(ii) above). This is contained in the following lemma.

LEMMA 13. *Let*

$$J(\lambda) = \left| \int_{\mathbb{R}^4} V * A(\psi_1, \psi_2) \cdot Q(\psi_3, \psi_4) dt dx \right|,$$

where A is either Q or B . Assume $\epsilon_1 = \epsilon_3 = +$, $\epsilon_4 = -$, and $\lambda_1 \leq \lambda_2 \ll \lambda_3 \sim \lambda_4$. Then

$$(6.3) \quad J(\lambda) \lesssim \lambda_2^\delta \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{V_{\epsilon_4}^2}.$$

Proof. Decompose the functions ψ_j into a low and high modulation part, i.e., $\psi_j = \psi_j^l + \psi_j^h$, where

$$\psi_j^h := \Lambda_{\geq \lambda_3/8}^{\epsilon_j} \psi_j, \quad \psi_j^l := \Lambda_{< \lambda_3/8}^{\epsilon_j} \psi_j.$$

We claim that

$$\int_{\mathbb{R}^4} V * A(\psi_1^l, \psi_2^l) \cdot Q(\psi_3^l, \psi_4^l) dt dx = 0.$$

Indeed, let (τ_j, ξ_j) be the space-time Fourier variables of the functions ψ_j^l . Clearly, the integral vanishes unless $\tau_1 - \tau_2 + \tau_3 - \tau_4 = 0$ and $\xi_1 - \xi_2 + \xi_3 - \xi_4 = 0$. By assumption and definition of low modulation, the contributing set must then satisfy

$$\begin{aligned} 4 \cdot \frac{\lambda_3}{8} = \frac{\lambda}{2} &> |(\tau_1 + \langle \xi_1 \rangle_m) - (\tau_2 + \epsilon_2 \langle \xi_2 \rangle_m) + (\tau_3 + \langle \xi_3 \rangle_m) - (\tau_4 - \langle \xi_4 \rangle_m)| \\ &= \langle \xi_1 \rangle_m - \epsilon_2 \langle \xi_2 \rangle_m + \langle \xi_3 \rangle_m + \langle \xi_4 \rangle_m \geq \frac{\lambda_3}{2}, \end{aligned}$$

which is a contradiction, and hence the integral vanishes. Thus, we always have at least one function on high modulation in the integral for J . There are 15 cases of which at least one of the four functions has high modulation but we consider only 4 cases where one of the functions is on high modulation and the other functions are on high or low modulation.

Case 1: $\psi_1 = \psi_1^h$ or $\psi_2 = \psi_2^h$. We only consider the case $\psi_1 = \psi_1^h$ since the case $\psi_2 = \psi_2^h$ can be handled in a similar way.

Subcase (i): $A = Q$. By Hölder, Sobolev, Lemma 5, Corollary 1(ii), and (2.7) we obtain

$$\begin{aligned} J(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu Q(\psi_1^h, \psi_2)\|_{L_t^2 L_x^1} \|P_\mu Q(\psi_3, \psi_4)\|_{L_t^2 L_x^\infty} \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \mu^{\frac{3}{2}} \|\psi_1^h\|_{L_{t,x}^2} \|\psi_2\|_{L_t^\infty L_x^2} \|P_\mu Q(\psi_3, \psi_4)\|_{L_{t,x}^2} \\ &\lesssim \sum_{1 \leq \mu \lesssim \lambda_2} \langle \mu \rangle^{-2} \mu^{\frac{5}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \\ &\lesssim \lambda_2^{\frac{1}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^2}, \end{aligned}$$

where we used the physical space representation of the term $Q(\psi_1^h, \psi_2)$ found in (4.15). On the other hand, applying 4.12 to the norm $\|P_\mu Q(\psi_3, \psi_4)\|_{L_{t,x}^2}$ we obtain

$$\begin{aligned} J(\lambda) &\lesssim \sum_{1 \leq \mu \lesssim \lambda_2} \langle \mu \rangle^{-2} \mu^{\frac{3}{2}} \lambda_3^{-\frac{1}{2}} (\lambda_3 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^4} \\ &\lesssim \lambda_3^{\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^4}. \end{aligned}$$

Now we use Lemma 2 to interpolate between the two estimates for $J(\lambda)$ above to obtain the desired estimate (6.3).

Subcase (ii): $A = B$. By Hölder, Sobolev, Lemma 5, Corollary 1(ii), and (2.7) we obtain

$$\begin{aligned} J(\lambda) &\lesssim \sum_{\mu \geq 1} \|\langle D \rangle^{-2} P_\mu B(\psi_1^h, \psi_2)\|_{L_t^2 L_x^1} \|P_\mu Q(\psi_3, \psi_4)\|_{L_t^2 L_x^\infty} \\ &\lesssim \sum_{\mu \geq 1} \langle \mu \rangle^{-2} \mu^{\frac{3}{2}} \lambda_1^{-1} \|\psi_1^h\|_{L_{t,x}^2} \|\psi_2\|_{L_t^\infty L_x^2} \|P_\mu Q(\psi_3, \psi_4)\|_{L_{t,x}^2} \\ &\lesssim \sum_{1 \leq \mu \lesssim \lambda_2} \langle \mu \rangle^{-2} \mu^{\frac{5}{2}} \lambda_1^{-1} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^2} \\ &\lesssim \lambda_2^{\frac{1}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^2}, \end{aligned}$$

where the Hölder inequality is applied on the physical space representation of $B(\psi_1^h, \psi_2)$ found in (4.17). On the other hand, applying 4.12 to the norm $\|P_\mu Q(\psi_3, \psi_4)\|_{L_{t,x}^2}$ we obtain

$$\begin{aligned} J(\lambda) &\lesssim \sum_{1 \leq \mu \lesssim \lambda_2} \langle \mu \rangle^{-2} \mu^{\frac{3}{2}} \lambda_1^{-1} \lambda_3^{-\frac{1}{2}} (\lambda_3 \lambda_4)^{\frac{1}{2}} \prod_{j=1}^2 \|\psi_j\|_{V_{\epsilon_j}^2} \prod_{j=3}^4 \|\psi_j\|_{U_{\epsilon_j}^4} \\ &\lesssim \lambda_3^{\frac{1}{2}} \prod_{j=1}^3 \|\psi_j\|_{U_{\epsilon_j}^2} \|\psi_4\|_{U_{\epsilon_4}^4}. \end{aligned}$$

Interpolating between the two estimates for $J(\lambda)$ above and using Lemma 2, we obtain the desired estimate (6.3).

Case 2: $\psi_3 = \psi_3^h$ or $\psi_4 = \psi_4^h$. We only consider the case $\psi_4 = \psi_4^h$ since the case $\psi_3 = \psi_3^h$ can be handled in a similar way.

Subcase (i): $A = Q$. By Hölder, Sobolev, Lemma 5, Lemma 1, and (2.7) we have

$$\begin{aligned} J(\lambda) &\lesssim \sum_{\mu \geq 1} \| \langle D \rangle^{-2} P_\mu Q(\psi_1, \psi_2) \|_{L_t^2 L_x^\infty} \| P_\mu Q(\psi_3, \psi_4^h) \|_{L_t^2 L_x^1} \\ &\lesssim \sum_{\mu \geq 1} \mu^{-\frac{1}{2}} \| P_\mu Q(\psi_1, \psi_2) \| \| \psi_3 \|_{L_t^\infty L_x^2} \| \psi_4^h \|_{L^2} \\ &\lesssim \sum_{1 \leq \mu \lesssim \lambda_3} \mu^{\frac{1}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^2 \| \psi_j \|_{U_{\epsilon_j}^2} \prod_{j=3}^4 \| \psi_j \|_{V_{\epsilon_j}^2} \lesssim \prod_{j=1}^3 \| \psi_j \|_{U_{\epsilon_j}^2} \| \psi_4 \|_{V_{\epsilon_4}^2}. \end{aligned}$$

Subcase (ii): $A = B$. By Hölder, Sobolev, (4.14), and (2.7) we have

$$\begin{aligned} J(\lambda) &\lesssim \sum_{\mu \geq 1} \| \langle D \rangle^{-2} P_\mu B(\psi_1, \psi_2) \|_{L_t^2 L_x^\infty} \| P_\mu Q(\psi_3, \psi_4^h) \|_{L_t^2 L_x^1} \\ &\lesssim \sum_{\mu \geq 1} \mu^{-\frac{1}{2}} \| P_\mu B(\psi_1, \psi_2) \| \| P_\mu Q(\psi_3, \psi_4^h) \|_{L_t^2 L_x^1} \\ &\lesssim \sum_{\mu \geq 1} \mu^{-\frac{1}{2}} \lambda_1^{-1} (\lambda_1 \lambda_2)^{\frac{1}{2}} \| \psi_1 \|_{V_{\epsilon_1}^2} \| \psi_2 \|_{V_{\epsilon_2}^2} \| \psi_3 \|_{L_t^\infty L_x^2} \| \psi_4^h \|_{L_{t,x}^2} \\ &\lesssim \sum_{\mu \geq 1} \mu^{-\frac{1}{2}} \lambda_1^{-\frac{1}{2}} \lambda_2^{\frac{1}{2}} \lambda_3^{-\frac{1}{2}} \prod_{j=1}^4 \| \psi_j \|_{V_{\epsilon_j}^2} \lesssim \prod_{j=1}^3 \| \psi_j \|_{U_{\epsilon_j}^2} \| \psi_4 \|_{V_{\epsilon_4}^2}, \end{aligned}$$

since $\lambda_1 \leq \lambda_2 \ll \lambda_3 \sim \lambda_4$. □

7. Proof of Lemma 6. To prove the estimates in Lemma 6 we closely follow the argument of Foschi and Klainerman for $m = 0$ [11, Lemmas 4.1 and 4.4].

For a smooth function φ , define the hypersurface $S = \{x \in \mathbb{R}^3 : \varphi(x) = 0\}$. If $\nabla \varphi \neq 0$ for $x \in S \cap \text{supp}(\Phi)$, then

$$(7.1) \quad \int_{\mathbb{R}^3} \Phi(x) \delta(\varphi(x)) dx = \int_S \frac{\Phi(x)}{|\nabla \varphi(x)|} dS_x.$$

For a nonnegative smooth function h which does not vanish on S , (7.1) also implies

$$(7.2) \quad \delta(\varphi(x)) = h(x) \delta(h(x)\varphi(x)).$$

7.1. Proof of Lemma 6(i). First note that the integral $I_+(f, g)$ is supported on the set

$$(7.3) \quad \mathcal{E}(\tau, \xi) = \{\eta \in \mathbb{R}^3 : \langle \eta \rangle_m + \langle \xi - \eta \rangle_m = \tau\}.$$

Thus for $\eta \in \mathcal{E}(\tau, \xi)$ we have

$$\begin{aligned} (7.4) \quad \tau^2 - |\xi|^2 - 4m^2 &= (\langle \eta \rangle_m + \langle \xi - \eta \rangle_m)^2 - |\xi|^2 - 4m^2 \\ &= 2\langle \eta \rangle_m \langle \xi - \eta \rangle_m - 2(|\eta||\xi - \eta| + m^2) + 2(|\eta||\xi - \eta| - \eta \cdot (\xi - \eta)) \\ &\geq 0. \end{aligned}$$

Now we use (7.2) to write

$$(7.5) \quad \begin{cases} \delta(\tau - \langle \eta \rangle_m - \langle \xi - \eta \rangle_m) \\ = [(\tau - \langle \eta \rangle_m) + \langle \xi - \eta \rangle_m] \delta((\tau - \langle \eta \rangle_m)^2 - \langle \xi - \eta \rangle_m^2) \\ = 2(\tau - \langle \eta \rangle_m) \delta(\tau^2 - |\xi|^2 - 2\tau \langle \eta \rangle_m + 2\xi \cdot \eta), \end{cases}$$

where in the first line we multiplied the argument of the delta function on the left by $(\tau - \langle \eta \rangle_m) + \langle \xi - \eta \rangle_m$.

Introduce polar coordinate $\eta = \sigma\omega$, where $\omega \in \mathbb{S}^2$:

$$|\eta| = \sigma, \quad d\eta = \sigma^2 dS_\omega d\sigma.$$

Then using (7.5) and (7.2) we obtain

$$\begin{aligned} I_+(f, g)(\tau, \xi) &= 2 \int_{\mathbb{R}^3} (\tau - \langle \eta \rangle_m) f(|\eta|) g(|\xi - \eta|) \delta(\tau^2 - |\xi|^2 - 2\tau \langle \eta \rangle_m + 2\xi \cdot \eta) d\eta \\ &\simeq \int_0^{\sqrt{\tau^2 - m^2}} \int_{\omega \in \mathbb{S}^2} \sigma^2 (\tau - \langle \sigma \rangle_m) f(\sigma) g\left(\sqrt{(\tau - \langle \sigma \rangle_m)^2 - m^2}\right) \\ &\quad \times \delta(\tau^2 - |\xi|^2 - 2\tau \langle \sigma \rangle_m + 2\sigma \xi \cdot \omega) dS_\omega d\sigma \\ &\simeq \frac{1}{|\xi|} \int_0^{\sqrt{\tau^2 - m^2}} \int_{\omega \in \mathbb{S}^2} \sigma (\tau - \langle \sigma \rangle_m) f(\sigma) g\left(\sqrt{(\tau - \langle \sigma \rangle_m)^2 - m^2}\right) \\ &\quad \times \delta\left(\frac{\tau^2 - |\xi|^2 - 2\tau \langle \sigma \rangle_m}{2|\xi|\sigma} + \frac{\xi \cdot \omega}{|\xi|}\right) dS_\omega d\sigma, \end{aligned}$$

where in the second inequality we used the fact that

$$\tau - \langle \eta \rangle_m = \langle \xi - \eta \rangle_m \Rightarrow |\xi - \eta| = \sqrt{(\tau - \langle \sigma \rangle_m)^2 - m^2}.$$

Changing the variable

$$s = \frac{\omega \cdot \xi}{|\xi|} \Rightarrow dS_\omega = dS_{\omega'} ds, \quad \text{where } \omega' \in \mathbb{S}^1,$$

we have

$$\begin{aligned} I_+(f, g)(\tau, \xi) &\simeq \frac{1}{|\xi|} \int_0^{\sqrt{\tau^2 - m^2}} \int_{-1}^1 \sigma (\tau - \langle \sigma \rangle_m) f(\sigma) g\left(\sqrt{(\tau - \langle \sigma \rangle_m)^2 - m^2}\right) \\ &\quad \times \delta\left(\frac{\tau^2 - |\xi|^2 - 2\tau \langle \sigma \rangle_m}{2|\xi|\sigma} + s\right) ds d\sigma \end{aligned}$$

Again, changing the variable

$$r = \langle \sigma \rangle_m \Rightarrow r dr = \sigma d\sigma$$

we obtain

$$\begin{aligned} I_+(f, g)(\tau, \xi) &\simeq \frac{1}{|\xi|} \int_m^\tau \int_{-1}^1 r(\tau - r) f\left(\sqrt{r^2 - m^2}\right) g\left(\sqrt{(\tau - r)^2 - m^2}\right) \\ &\quad \times \delta\left(\frac{\tau^2 - |\xi|^2 - 2\tau r}{2|\xi|\sqrt{r^2 - m^2}} + s\right) ds dr \\ &\simeq \frac{1}{|\xi|} \int_0^\infty r(\tau - r) \mathbb{1}_{\mathcal{D}_+}(r) f\left(\sqrt{r^2 - m^2}\right) g\left(\sqrt{(\tau - r)^2 - m^2}\right) dr, \end{aligned}$$

where

$$\mathcal{D}_+ := \mathcal{D}_+(\tau, \xi) = [m, \tau] \cap \left\{ r \in \mathbb{R} : -1 \leq \frac{\tau^2 - |\xi|^2 - 2\tau r}{2|\xi|\sqrt{r^2 - m^2}} \leq 1 \right\}.$$

So $r \in \mathcal{D}_+$ if and only if $r \in [m, \tau]$ and

$$(\tau^2 - |\xi|^2 - 2\tau r)^2 - 4|\xi|^2 r^2 + 4m^2 |\xi|^2 \leq 0.$$

The latter condition is equivalent to

$$(r - a_+)(r - a_-) \leq 0,$$

where

$$a_{\pm} = \frac{\tau}{2} \pm \frac{|\xi|}{2} \sqrt{\frac{\tau^2 - |\xi|^2 - 4m^2}{\tau^2 - |\xi|^2}}.$$

Thus $r \in [a_-, a_+]$ and, hence, $\mathcal{D}_+ = [m, \tau] \cap [a_-, a_+]$. We claim that $[a_-, a_+] \subseteq [m, \tau]$. Clearly, $a_+ \leq \tau$ since $|\xi| < \tau$ and $1 - \frac{4m^2}{\tau^2 - |\xi|^2} \leq 1$ by (7.4). The condition $a_- \geq m$ is equivalent to

$$\tau - 2m \geq |\xi| \sqrt{\frac{\tau^2 - |\xi|^2 - 4m^2}{\tau^2 - |\xi|^2}}$$

which can be squared to obtain

$$\tau^4 - 4m\tau^3 + 4m^2\tau^2 - 2|\xi|^2\tau^2 + 4m\tau|\xi|^2 + |\xi|^4 \geq 0.$$

The expression on the left-hand side can be written as

$$((\tau - m)^2 - m^2)^2 - 2|\xi|^2((\tau - m)^2 - m^2) + |\xi|^4 = ((\tau - m)^2 - m^2) - |\xi|^2)^2$$

which is ≥ 0 .

Thus $\mathcal{D}_+ = [a_-, a_+]$ and, hence,

$$I_+(f, g)(\tau, \xi) \simeq \frac{1}{|\xi|} \int_{a_-}^{a_+} r(\tau - r) f\left(\sqrt{r^2 - m^2}\right) g\left(\sqrt{(\tau - r)^2 - m^2}\right) dr.$$

7.2. Proof of Lemma 6(ii). First note that the integral $I_-(f, g)$ is supported on the set

$$(7.6) \quad \mathcal{H}(\tau, \xi) = \{\eta \in \mathbb{R}^3 : \langle \eta \rangle_m - \langle \xi - \eta \rangle_m = \tau\}.$$

Thus for $\eta \in \mathcal{H}(\tau, \xi)$ we have

$$(7.7) \quad \begin{aligned} |\xi|^2 - \tau^2 &= |\xi|^2 - (\langle \eta \rangle_m - \langle \xi - \eta \rangle_m)^2 \\ &= 2\langle \eta \rangle_m \langle \xi - \eta \rangle_m - 2m^2 + 2\eta \cdot (\xi - \eta) \geq 0, \end{aligned}$$

where in the last inequality we used the fact

$$2\langle \eta \rangle_m \langle \xi - \eta \rangle_m \geq 2|\eta||\xi - \eta| + 2m^2.$$

Since the expression on the second line is ≥ 0 , we conclude

$$(7.8) \quad \tau^2 - |\xi|^2 \geq 4m^2.$$

By (7.2) we have

$$\begin{aligned} \delta(\tau - \langle \eta \rangle_m + \langle \xi - \eta \rangle_m) &= [-\langle \tau - \langle \eta \rangle_m \rangle + \langle \xi - \eta \rangle_m] \delta(-\langle \tau - \langle \eta \rangle_m \rangle^2 + \langle \xi - \eta \rangle_m^2) \\ &= -2\langle \tau - \langle \eta \rangle_m \rangle \delta(|\xi|^2 - \tau^2 + 2\tau \langle \eta \rangle_m - 2\xi \cdot \eta), \end{aligned}$$

where in the first line we multiplied the argument of the delta function on the left by $-\langle \tau - \langle \eta \rangle_m \rangle + \langle \xi - \eta \rangle_m$.

Now introduce polar coordinate $\eta = \sigma\omega$, where $\omega \in \mathbb{S}^2$. Proceeding similarly as in the above subsection we obtain

$$\begin{aligned} I_-(f, g)(\tau, \xi) &\simeq \frac{1}{|\xi|} \int_0^\infty \int_{-1}^1 \sigma \langle \sigma \rangle_m - \tau f(\sigma) g\left(\sqrt{\langle \sigma \rangle_m^2 - \tau^2 - m^2}\right) \\ &\quad \times \delta\left(\frac{|\xi|^2 - \tau^2 + 2\tau \langle \sigma \rangle_m}{2|\xi|\sigma} - s\right) ds d\sigma \\ &= \frac{1}{|\xi|} \int_0^\infty r(r - \tau) \mathbb{1}_{\mathcal{D}_-}(r) f\left(\sqrt{r^2 - m^2}\right) g\left(\sqrt{(r - \tau)^2 - m^2}\right) dr, \end{aligned}$$

where

$$\mathcal{D}_- := \mathcal{D}_-(\tau, \xi) = [m, \infty) \cap \left\{ r \in \mathbb{R} : -1 \leq \frac{|\xi|^2 - \tau^2 + 2\tau r}{2|\xi|\sqrt{r^2 - m^2}} \leq 1 \right\}.$$

So $r \in \mathcal{D}_-$ if and only if $r \in [m, \infty)$ and

$$(|\xi|^2 - \tau^2 + 2\tau r)^2 - 4|\xi|^2 r^2 + 4m^2 |\xi|^2 \leq 0.$$

The latter condition is equivalent to

$$(r - a_+)(r - a_-) \geq 0,$$

where a_\pm is given above. Thus $r \leq a_-$ or $r \geq a_+$ and, hence,

$$\mathcal{D}_- = [m, \infty) \cap \{(-\infty, a_-] \cup [a_+, \infty)\}.$$

We claim that $a_- < m$ and $a_+ \geq m$. These would imply $\mathcal{D}_- = [a_+, \infty)$ and, hence,

$$I_-(f, g)(\tau, \xi) \simeq \frac{1}{|\xi|} \int_{b_+}^\infty r(r - \tau) f\left(\sqrt{r^2 - m^2}\right) g\left(\sqrt{(r - \tau)^2 - m^2}\right) dr.$$

It remains to prove the claim. By (7.7) we have $-|\xi| \leq \tau \leq |\xi|$. So clearly,

$$a_- \leq \frac{|\xi|}{2} \left(1 - \sqrt{1 + \frac{4m^2}{|\xi|^2 - \tau^2}} \right) \leq 0 \leq m.$$

Next we show that $a_+ \geq m$. If $0 \leq \tau \leq |\xi|$ we have

$$a_+ \geq \frac{\tau}{2} + \frac{|\xi|}{2} \cdot \sqrt{\frac{4m^2}{|\xi|^2}} = \frac{\tau}{2} + m \geq m.$$

Now assume $-|\xi| \leq \tau < 0$. Then $a_+ > m$ if and only if

$$|\xi| \sqrt{\frac{|\xi|^2 - \tau^2 + 4m^2}{|\xi|^2 - \tau^2}} \geq 2m - \tau.$$

Since $\tau < 0$, we can square both sides to obtain the condition

$$\tau^4 - 4m\tau^3 + 4m^2\tau^2 - 2|\xi|^2\tau^2 + 4m\tau|\xi|^2 + |\xi|^4 \geq 0.$$

The expression on the left-hand side can be written as

$$((\tau - m)^2 - m^2)^2 - 2|\xi|^2((\tau - m)^2 - m^2) + |\xi|^4 = ((\tau - m)^2 - m^2) - |\xi|^2)^2$$

which is ≥ 0 .

8. Proof of Lemma 7. By symmetry we may assume $\lambda_1 \leq \lambda_2$. Thus, we are reduced to the following cases:

(a) $\lambda_1 \lesssim \lambda_2 \sim \mu$,

(b) $\mu \ll \lambda_1 \sim \lambda_2$.

8.1. Case (a) $\lambda_1 \lesssim \lambda_2 \sim \mu$. First assume $\mu = 1$ and, hence, $\lambda_2 \sim \mu = 1$. In this case we simply apply Hölder and Lemma 5 to obtain

$$(8.1) \quad \begin{aligned} \|P_\mu(S_m(t)f_{\lambda_1}S_m(\pm t)g_{\lambda_2})\|_{L^2_{t,x}} &\lesssim \|S_m(t)f_{\lambda_1}\|_{L^4_{t,x}} \|S_m(\pm t)g_{\lambda_2}\|_{L^4_{t,x}} \\ &\lesssim \|f_{\lambda_1}\|_{L^2_x(\mathbb{R}^3)} \|g_{\lambda_2}\|_{L^2_x(\mathbb{R}^3)}. \end{aligned}$$

Thus, we may from now on assume $\mu > 1$. Taking the space-time Fourier transform we have

$$\begin{aligned} \mathcal{F}_{t,x} [P_\mu(S_m(t)f_{\lambda_1}S_m(t)g_{\lambda_2})] (\tau, \xi) &= \rho_\mu(|\xi|) \int_{\mathbb{R}^3} \widehat{f_{\lambda_1}}(\eta) \widehat{g_{\lambda_2}}(\xi - \eta) \delta(\tau - \langle \eta \rangle_m - \langle \xi - \eta \rangle_m) d\eta, \\ \mathcal{F}_{t,x} [P_\mu(S_m(t)f_{\lambda_1}S_m(-t)g_{\lambda_2})] (\tau, \xi) &= \rho_\mu(|\xi|) \int_{\mathbb{R}^3} \widehat{f_{\lambda_1}}(\eta) \widehat{g_{\lambda_2}}(\xi - \eta) \delta(\tau - \langle \eta \rangle_m + \langle \xi - \eta \rangle_m) d\eta. \end{aligned}$$

By Cauchy–Schwarz

$$\begin{aligned} |\mathcal{F}_{t,x} [P_\mu(S_m(t)f_{\lambda_1}S_m(\pm t)g_{\lambda_2})] (\tau, \xi)|^2 &\leq I_\pm(\tau, \xi) \cdot \int_{\mathbb{R}^3} |\widehat{f_{\lambda_1}}(\eta)|^2 |\widehat{g_{\lambda_2}}(\xi - \eta)|^2 \delta(\tau - \langle \eta \rangle_m \mp \langle \xi - \eta \rangle_m) d\eta, \end{aligned}$$

where

$$I_\pm(\tau, \xi) = \rho_\mu(|\xi|) \int_{\mathbb{R}^3} \rho_{\lambda_1}(|\eta|) \rho_{\lambda_2}(|\xi - \eta|) \delta(\tau - \langle \eta \rangle_m \mp \langle \xi - \eta \rangle_m) d\eta.$$

Now we claim that

$$(8.2) \quad \sup_{(\tau, \xi) \in \mathbb{R}^{1+3}} I_\pm(\tau, \xi) \lesssim \lambda_1^2 \quad \text{if } \lambda_1 \lesssim \lambda_2 \sim \mu.$$

Assume for the moment that this claim holds. Then integration with respect to τ and ξ gives the following:

$$\begin{aligned} &\|P_\mu(S_m(t)f_{\lambda_1}S_m(\pm t)g_{\lambda_2})\|^2 \\ &= \int_{\mathbb{R}^{1+3}} |\mathcal{F}_{t,x} [P_\mu(S_m(t)f_{\lambda_1}S_m(\pm t)g_{\lambda_2})] (\tau, \xi)|^2 d\tau d\xi \\ &\lesssim \lambda_1^2 \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} |\widehat{f_{\lambda_1}}(\eta)|^2 |\widehat{g_{\lambda_2}}(\xi - \eta)|^2 \left(\int_{\mathbb{R}^3} \delta(\tau - \langle \eta \rangle_m \pm \langle \xi - \eta \rangle_m) d\tau \right) d\eta d\xi \\ &= \lambda_1^2 \|f_{\lambda_1}\|^2 \|g_{\lambda_2}\|^2, \end{aligned}$$

where we used the fact $\int_{\mathbb{R}} \delta(\tau - \langle \eta \rangle_m \mp \langle \xi - \eta \rangle_m) d\tau = 1$. This estimate together with (8.1) establishes Lemma 7(i) and 7(ii) in the case $\lambda_1 \lesssim \lambda_2 \sim \mu$.

Thus, it remains to prove (8.2). By Lemma 7 we have

$$I_+(\tau, \xi) \simeq \frac{\rho_\mu(|\xi|)}{|\xi|} \int_{a_-}^{a_+} r(\tau - r)\rho_{\lambda_1}(\sqrt{r^2 - m^2})\rho_{\lambda_2}(\sqrt{(\tau - r)^2 - m^2}) dr,$$

$$I_-(\tau, \xi) \simeq \frac{\rho_\mu(|\xi|)}{|\xi|} \int_{a_+}^{\infty} r(r - \tau)\rho_{\lambda_1}(\sqrt{r^2 - m^2})\rho_{\lambda_2}(\sqrt{(r - \tau)^2 - m^2}) dr.$$

By the support assumption in the integral for I_+ we have $r \sim \langle \lambda_1 \rangle_m$ and $\tau - r \sim \langle \lambda_2 \rangle_m$. Since $\mu > 1$ and $\lambda_1 \lesssim \lambda_2 \sim \mu$ we have

$$\sup_{(\tau, \xi) \in \mathbb{R}^{1+3}} I_+(\tau, \xi) \lesssim \frac{\langle \lambda_1 \rangle_m \langle \lambda_2 \rangle_m}{\mu} \int_{r \sim \langle \lambda_1 \rangle_m} dr \sim \lambda_1^2.$$

Similarly, by the support assumption in the integral for I_- we have $r \sim \langle \lambda_1 \rangle_m$ and $r - \tau \sim \langle \lambda_2 \rangle_m$. Since $\mu > 1$ and $\lambda_1 \lesssim \lambda_2 \sim \mu$ we have

$$\sup_{(\tau, \xi) \in \mathbb{R}^{1+3}} I_-(\tau, \xi) \lesssim \frac{\langle \lambda_1 \rangle_m \langle \lambda_2 \rangle_m}{\mu} \int_{r \sim \langle \lambda_1 \rangle_m} dr \sim \lambda_1^2.$$

8.2. Case (b) $\mu \ll \lambda_1 \sim \lambda_2$. In this case we follow the argument of Foschi and Klainerman for $m = 0$ [11, Lemma 12.1] and introduce a collection of cubes $C_z = \mu z + [0, \mu]^3$, $z \in \mathbb{Z}^3$, which induce a disjoint covering of \mathbb{R}^3 . By the triangle inequality

$$(8.3) \quad \|P_\mu(S(t)f_{\lambda_1}S_m(\pm t)g_{\lambda_2})\| \lesssim \sum_{z, z' \in \mathbb{Z}^3} \|P_\mu(S_m(t)P_{C_z}f_{\lambda_1} \cdot S_m(\pm t)P_{C_{z'}}g_{\lambda_2})\|,$$

where P_{C_z} is the frequency projection onto C_z . Let

$$f_{\lambda_1, z} := P_{C_z}f_\lambda \quad \text{and} \quad g_{\lambda_2, z'} := P_{C_{z'}}g_{\lambda_2}.$$

Taking the Fourier transform we have

$$(8.4) \quad \mathcal{F}_{t,x} [P_\mu(S_m(t)f_{\lambda_1, z} \cdot S_m(\pm t)g_{\lambda_2, z'})](\tau, \xi) = \rho_\mu(|\xi|) \int_{\mathbb{R}^3} \widehat{f_{\lambda_1, z}}(\eta) \widehat{g_{\lambda_2, z'}}(\xi - \eta) \delta(\tau - \langle \eta \rangle_m \mp \langle \xi - \eta \rangle_m) d\eta.$$

Since $\mu \ll \lambda_1 \sim \lambda_2$ and $\eta \in C_z$, $\xi - \eta \in C_{z'}$, the integral in (8.4) yields a nontrivial contribution if C_z and $C_{z'}$ are almost opposite, i.e., if $\angle(\eta, \xi - \eta) \sim 1$. In other words, for each $z \in \mathbb{Z}^3$, only those $z' \in \mathbb{Z}^3$ with $|z + z'| \lesssim 1$ yield a nontrivial contribution to the sum (8.3). We use these observations and apply Lemma 14(i)–14(ii) below to (8.3), and use Cauchy–Schwarz to obtain

$$\begin{aligned} \|P_\mu(S_m(t)f_{\lambda_1}S_m(t)g_{\lambda_2})\| &\lesssim \mu \sum_{|z+z'| \lesssim 1} \|f_{z, \lambda_1}\| \|g_{z', \lambda_2}\| \\ &\lesssim \mu \left(\sum_{z \in \mathbb{Z}^3} \|f_{z, \lambda_1}\|^2 \right)^{\frac{1}{2}} \left(\sum_{z' \in \mathbb{Z}^3} \|g_{z', \lambda_2}\|^2 \right)^{\frac{1}{2}} \\ &\sim \mu \|f_{\lambda_1}\| \|g_{\lambda_2}\| \end{aligned}$$

and

$$\begin{aligned} \|P_\mu(S_m(t)f_{\lambda_1}S_m(-t)g_{\lambda_2})\| &\lesssim (\mu\lambda_1)^{\frac{1}{2}} \sum_{|z+z'|\lesssim 1} \|f_{z,\lambda_1}\| \|g_{z',\lambda_2}\| \\ &\lesssim (\mu\lambda_1)^{\frac{1}{2}} \left(\sum_{z\in\mathbb{Z}^3} \|f_{z,\lambda_1}\|^2\right)^{\frac{1}{2}} \left(\sum_{z'\in\mathbb{Z}^3} \|g_{z',\lambda_2}\|^2\right)^{\frac{1}{2}} \\ &\sim (\mu\lambda_1)^{\frac{1}{2}} \|f_{\lambda_1}\| \|g_{\lambda_2}\|. \end{aligned}$$

LEMMA 14 (refined bilinear estimates). Assume $\mu \ll \lambda_1 \sim \lambda_2$. For all $(z, z') \in \mathbb{Z}^3 \times \mathbb{Z}^3$ we have the following localized bilinear estimates:

(i) $(++)$ interaction:

$$(8.5) \quad \|P_\mu(S_m(t)f_{z,\lambda_1} \cdot S_m(t)g_{z',\lambda_2})\| \lesssim \mu \|f_{z,\lambda_1}\| \|g_{z',\lambda_2}\|.$$

(ii) $(+-)$ interaction:

$$(8.6) \quad \|P_\mu(S_m(t)f_{z,\lambda_1} \cdot S_m(-t)g_{z',\lambda_2})\| \lesssim (\mu\lambda_1)^{\frac{1}{2}} \|f_{z,\lambda_1}\| \|g_{z',\lambda_2}\|.$$

8.2.1. Proof of Lemma 14(i). Set $\rho_{z,\lambda}(|\xi|) = \mathbb{1}_{B_{2\mu}(\mu z)}(\xi) \cdot \rho_\lambda(|\xi|)$, where $B_{2\mu}(\mu z)$ denotes the ball of center μz and radius 2μ . Squaring (8.4) and using Cauchy–Schwarz we have

$$(8.7) \quad \begin{aligned} &|\mathcal{F}_{t,x} [P_\mu(S_m(t)f_{\lambda_1,z} \cdot S_m(t)g_{\lambda_2,z'})](\tau, \xi)|^2 \\ &\lesssim J_{z,z'}^+(\tau, \xi) \cdot \int_{\mathbb{R}^3} |\widehat{f_{z,\lambda_1}}(\eta)|^2 |\widehat{g_{z',\lambda_2}}(\xi - \eta)|^2 \delta(\tau - \langle \eta \rangle_m - \langle \xi - \eta \rangle_m) d\eta, \end{aligned}$$

where

$$J_{z,z'}^+(\tau, \xi) = \rho_\mu(|\xi|) \int_{\mathbb{R}^3} \rho_{z,\lambda_1}(|\eta|) \rho_{z',\lambda_2}(|\xi - \eta|) \delta(\tau - \langle \eta \rangle_m - \langle \xi - \eta \rangle_m) d\eta.$$

It suffices to show for all $(z, z') \in \mathbb{Z}^3 \times \mathbb{Z}^3$ that

$$(8.8) \quad \sup_{(\tau, \xi) \in \mathbb{R}^{1+3}} J_{z,z'}^+(\tau, \xi) \lesssim \mu^2 \quad \text{if } \mu \ll \lambda_1 \sim \lambda_2.$$

Integration of (8.7) in τ and ξ then yields Lemma 14(i).

We now prove (8.8). By (7.1) we have

$$J_{z,z'}^+(\tau, \xi) = \rho_\mu(|\xi|) \int_{\eta \in \mathcal{E}(\tau, \xi) \cap B_{2\mu}(\mu z)} \frac{\rho_{\lambda_1}(|\eta|) \rho_{z',\lambda_2}(|\xi - \eta|)}{|\nabla_\eta(\langle \eta \rangle_m + \langle \xi - \eta \rangle_m)|} dS\eta,$$

where the set $\mathcal{E}(\tau, \xi)$ is as in (7.3). Since $\angle(\eta, \xi - \eta) \sim 1$ we have

$$|\nabla_\eta(\langle \eta \rangle_m + \langle \xi - \eta \rangle_m)| = \left| \frac{\eta}{\langle \eta \rangle_m} - \frac{\xi - \eta}{\langle \xi - \eta \rangle_m} \right| \sim 1.$$

The domain of integration, $\mathcal{E}(\tau, \xi) \cap B_{2\mu}(\mu z)$, is a two dimensional surface with area $\lesssim \mu^2$. Thus for all $(z, z') \in \mathbb{Z}^3 \times \mathbb{Z}^3$ and $(\tau, \xi) \in \mathbb{R}^{1+3}$, we have

$$J_{z,z'}^+(\tau, \xi) \lesssim |\mathcal{E}(\tau, \xi) \cap B_{2\mu}(\mu z)| \lesssim \mu^2,$$

and this establishes (8.8).

8.2.2. Proof of Lemma 14(ii). Here we follow Foschi and Klainerman for $m = 0$ [11, proof of Lemma 12.1, equation (66)]. To estimate the left-hand side of (8.6) first we square (8.4) (the $+$ case), write it as a double integral, and then integrate over τ and ξ . After applying the Fubini–Tonelli theorem and rearranging the integrand we obtain

$$\begin{aligned} & \|P_\mu(S_m(t)f_{z,\lambda_1} \cdot S_m(-t)g_{z',\lambda_2})\|^2 \\ &= \int_{\mathbb{R}^9} \widehat{f_{\lambda_1,z}}(\eta)\widehat{g_{\lambda_2,z'}}(\zeta) \cdot \widehat{f_{\lambda_1,z}}(\xi - \zeta)\widehat{g_{\lambda_2,z'}}(\xi - \eta) \, d\sigma(\xi, \eta, \zeta), \end{aligned}$$

where $d\sigma(\xi, \eta, \zeta)$ is the surface measure

$$d\sigma(\xi, \eta, \zeta) = \rho_\mu^2(|\xi|) \cdot \delta(\langle \eta \rangle_m + \langle \zeta \rangle_m - \langle \xi - \eta \rangle_m - \langle \xi - \zeta \rangle_m) \, d\xi d\eta d\zeta.$$

Applying Cauchy–Schwarz on the terms $\widehat{f_{\lambda_1,z}}(\eta)\widehat{g_{\lambda_2,z'}}(\zeta)$ and $\widehat{f_{\lambda_1,z}}(\xi - \zeta)\widehat{g_{\lambda_2,z'}}(\xi - \eta)$ with respect to the measure $d\sigma(\xi, \eta, \zeta)$, and then changing variables we obtain

$$\begin{aligned} \|P_\mu(S_m(t)f_{z,\lambda_1} \cdot S_m(-t)g_{z',\lambda_2})\|^2 &\leq \int_{\mathbb{R}^9} |\widehat{f_{\lambda_1,z}}(\xi - \eta)|^2 |\widehat{g_{\lambda_2,z'}}(\xi - \zeta)|^2 \, d\sigma(\xi, \eta, \zeta) \\ &\lesssim \int_{\mathbb{R}^6} J_{z,z'}^-(\eta, \zeta) \cdot |\widehat{f_{\lambda_1,z}}(\xi - \eta)|^2 |\widehat{g_{\lambda_2,z'}}(\xi - \zeta)|^2 \, d\eta d\zeta, \end{aligned}$$

where

$$\begin{aligned} J_{z,z'}^-(\eta, \zeta) &= \int_{\mathbb{R}^3} \rho_{z,\lambda_1}(|\xi - \eta|)\rho_{z',\lambda_2}(|\xi - \zeta|)\rho_\mu(|\xi|) \\ &\quad \times \delta(\langle \eta \rangle_m + \langle \zeta \rangle_m - \langle \xi - \eta \rangle_m - \langle \xi - \zeta \rangle_m) \, d\xi. \end{aligned}$$

So it suffices to show for all $(z, z') \in \mathbb{Z}^3 \times \mathbb{Z}^3$ that

$$(8.9) \quad \sup_{\eta \in C_z, \zeta \in C_{z'}} J_{z,z'}^-(\eta, \zeta) \lesssim \mu\lambda_1 \quad \text{for } \mu \ll \lambda_1 \sim \lambda_2.$$

By (7.1) we have

$$J_{z,z'}^-(\eta, \zeta) = \int_{\xi \in \mathcal{E}(\eta, \zeta)} \frac{\rho_{z,\lambda_1}(|\xi - \eta|)\rho_{z',\lambda_2}(|\xi - \zeta|)\rho_\mu(|\xi|)}{|\nabla_\xi(\langle \xi - \eta \rangle_m + \langle \xi - \zeta \rangle_m)|} \, dS_\xi,$$

where

$$\mathcal{E}(\eta, \zeta) = \{ \xi \in \mathbb{R}^3 : \langle \xi - \eta \rangle_m + \langle \xi - \zeta \rangle_m = \langle \eta \rangle_m + \langle \zeta \rangle_m \}.$$

Now we compute

$$\begin{aligned} & |\nabla_\xi(\langle \xi - \eta \rangle_m + \langle \xi - \zeta \rangle_m)|^2 \\ &= \left| \frac{\xi - \eta}{\langle \xi - \eta \rangle_m} + \frac{\xi - \zeta}{\langle \xi - \zeta \rangle_m} \right|^2 \\ &= \left| \frac{|\xi - \eta|}{\langle \xi - \eta \rangle_m} - \frac{|\xi - \zeta|}{\langle \xi - \zeta \rangle_m} \right|^2 + \frac{2[|\xi - \eta||\xi - \zeta| + (\xi - \eta) \cdot (\xi - \zeta)]}{\langle \xi - \eta \rangle_m \langle \xi - \zeta \rangle_m} \\ &\gtrsim \theta^2, \end{aligned}$$

where $\theta = \angle(\xi - \eta, -(\xi - \zeta))$. Observe that since $\xi - \eta \in C_z$ and $\xi - \zeta \in C_{z'}$, where $|z + z'| \lesssim 1$ (see the comments under (8.4)), we conclude that

$$\theta \sim \mu/\lambda_1.$$

Thus $|\nabla_\xi(\langle \xi - \eta \rangle_m + \langle \xi - \zeta \rangle_m)| \gtrsim \mu/\lambda_1$ and, hence,

$$J_{z,z'}^-(\eta, \zeta) \lesssim \frac{\lambda_1}{\mu} \int_{\xi \in \mathcal{E}(\eta, \zeta) \cap B_{2\mu}(0)} dS_\xi = \frac{\lambda_1}{\mu} |\mathcal{E}(\eta, \zeta) \cap B_{2\mu}(0)| \lesssim \mu\lambda_1$$

since $\mathcal{E}(\tau, \xi) \cap B_{2\mu}(\mu z)$ is a two dimensional surface with area $\lesssim \mu^2$. This establishes (8.9).

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