

Department
of
APPLIED MATHEMATICS

Convergence of finite differences schemes for viscous and
inviscid conservation laws with rough coefficients.

by

Kenneth Hvistendahl Karlsen
and Nils Henrik Risebro

Report no. 149

September 2000



UNIVERSITY OF BERGEN
Bergen, Norway

NB Rana
Depotbiblioteket

Department of Mathematics
University of Bergen
5008 Bergen
Norway

ISSN 0084-778x

Convergence of finite differences schemes for viscous and
inviscid conservation laws with rough coefficients.

by

Kenneth Hvistendahl Karlsen
and Nils Henrik Risebro

Report no. 149

September 2000

CONVERGENCE OF FINITE DIFFERENCE SCHEMES FOR VISCOUS AND INVISCID CONSERVATION LAWS WITH ROUGH COEFFICIENTS

KENNETH HVISTENDAHL KARLSEN AND NILS HENRIK RISEBRO

ABSTRACT. We consider the initial value problem for degenerate viscous and inviscid scalar conservation laws where the flux function depends on the spatial location through a “rough” coefficient function $k(x)$. We show that the Engquist-Osher (and hence all monotone) finite difference approximations converge to the unique entropy solution of the governing equation if, among other demands, k' is in BV , thereby providing alternative (new) existence proofs for entropy solutions of degenerate convection-diffusion equations as well as new convergence results for their finite difference approximations. In the inviscid case, we also provide a rate of convergence. Our convergence proofs are based on deriving a series of a priori estimates and using a general L^p compactness criterion.

1. INTRODUCTION

The main subject of this paper is finite difference schemes for computing the entropy solution of scalar viscous and inviscid conservation laws where the transport term depends explicitly on the spatial location. Such equations are of the form

$$(1.1) \quad u_t + \operatorname{div} f(k, u) = \Delta A(u), \quad u(x, 0) = u_0(x), \quad (x, t) \in \Pi_T = \mathbb{R}^d \times (0, T),$$

where the flux function $f(k, u) = (f_1(k^1, u), \dots, f_d(k^d, u))$ depends on the spatial location through the coefficient $k = k(x)$,

$$k(x) = (k^1(x), \dots, k^d(x)).$$

For the initial value problem (1.1) to be well-posed, we must require that the nonlinear elliptic operator $u \mapsto \Delta A(u)$ satisfies the *degenerate ellipticity* condition

$$(1.2) \quad A(\cdot) \text{ nondecreasing with } A(0) = 0.$$

Note that (1.2) implies that many well known nonlinear partial differential equations are special cases of (1.1). In particular, (1.2) includes as special cases the inviscid conservation law, the heat equation, one-point degenerate porous medium type equations [43], two-point degenerate oil reservoir flow equations [15], and *strongly* degenerate convection-diffusion equations of the type arising in the theory of sedimentation-consolidation processes [4].

We recall that if (1.1) is allowed to degenerate at certain points, that is, $A'(s) = 0$ for some values of s , solutions are not necessarily smooth (but typically continuous) and weak solutions must be sought. On the other hand, if $A'(s)$ is zero on an interval $[\alpha, \beta]$, (weak) solutions may be discontinuous and they are not uniquely determined by their initial data. Consequently, an entropy condition must be imposed to single out the physically correct solution. Roughly speaking, we call a function $u \in L^1 \cap L^\infty$ an *entropy solution* of (1.1) if

$$(1.3) \quad \begin{cases} \text{(i)} & \partial_t |u - c| + \operatorname{div} [\operatorname{sign}(u - c) (f(k, u) - f(k, c))] \\ & + \operatorname{sign}(u - c) \operatorname{div} f(k, c) - \Delta |A(u) - A(c)| \leq 0 \text{ in } \mathcal{D}' \quad \forall c \in \mathbb{R}, \\ \text{(ii)} & \nabla A(u) \text{ belongs to } L^2. \end{cases}$$

Date: September 6, 2000.

1991 Mathematics Subject Classification. 65M06, 35L65, 35L45, 35K65.

Key words and phrases. conservation law, degenerate convection-diffusion equation, entropy solution, finite difference scheme, convergence, error estimate.

We refer to §2.1 for a more precise statement of the definition of an entropy solution as well as precise conditions on u_0, f, k, A ensuring that this definition makes sense. Relevant mathematical (existence and uniqueness) theory for entropy solutions can be found in [5, 28, 3, 42].

For the hyperbolic equation, the convergence analysis of numerical schemes have very long traditions and goes back to the 1950s. Being extremely selective, we mention only a *few* references related to finite difference and finite volume approximations. The case of finite difference schemes have been treated by Oleřnik [40], Harten, Hyman, and Lax [24], Kuznetsov [36], Crandall and Majda [12], Sanders [44], Lucier [37], Osher and Tadmor [41], Cockburn and Gremaud [10], and many others. The study of finite volume methods is more recent and have been conducted by Champier, Gallouët, and Herbin [7], Vila [48], Cockburn, Coquel, and LeFloch [8, 9], Kröner and Rokyta [32], Kröner, Noelle, and Rokyta [31], Noelle [38], Eymard, Gallouët, Ghilani, Herbin [21], and Chainais-Hillairet [6], as well as many others. Among the cited papers, only [40, 7, 21, 6] treat equations where the nonlinearity f depends on the spatial position x (and time t).

Although there seems to be an increasing interest in the (analysis of) numerical approximation of entropy solutions of degenerate parabolic equations, the amount of literature on the subject is at the moment modest. The (very recent) literature include papers by Evje and Karlsen [18], Holden, Karlsen, and Lie [25], and Holden, Karlsen, Lie, and Risebro [26] on operator splitting methods (see also the lecture notes by Espedal and Karlsen [15]); Evje and Karlsen [19, 17, 20, 16] on upwind difference schemes; Kurganov and Tadmor [35] on central difference schemes; Bouchut, Guarguaglini, and Natalini [2] on kinetic BGK schemes; Afif and Amaziane [1] and Ohlberger [39] on finite volume methods; and Cockburn and Shu [11] on the local discontinuous Galerkin method. Strictly speaking, the authors of [1, 11, 35] does analyze their numerical methods within an entropy solution framework.

It is somewhat surprising that there have been few attempts up to very recently (confer the list of references given above) to develop a systematic treatment of mixed hyperbolic-parabolic partial differential equations within a unified mathematical (entropy solution) framework. In fact, the construction and analysis of numerical methods for first order hyperbolic and second order parabolic equations are usually considered as separate subject areas. In this work we demonstrate that it is possible to give a coherent treatment of numerical methods for such large class of nonlinear partial differential equations. Our main long-term goal is indeed to develop a consistent (mathematical/numerical) framework which is the same whether we are working with the hyperbolic case ($A' \equiv 0$), the parabolic case ($A' > 0$), or with the mixed hyperbolic-parabolic case ($A' \geq 0$). In the present paper (see also [19, 17, 20, 16]), we are concerned with finite difference schemes and their convergence analysis. For related work on other numerical methods for strongly degenerate parabolic equations, see the list of references given above.

To illustrate the results of this paper, we now state them in the one dimensional case (i.e, $d = 1$). For the general results, we refer to sections 3 and 4. As a model difference scheme for (1.1), we consider the generalized upwind (Engquist-Osher) scheme

$$\begin{aligned} \frac{u_i^{n+1} - u_i^n}{\Delta t} + \frac{f^{\text{EO}}(k_{i+1/2}, u_i^n, u_{i+1}^n) - f^{\text{EO}}(k_{i-1/2}, u_{i-1}^n, u_i^n)}{h} \\ = \frac{A(u_{i+1}^n) - 2A(u_i^n) + A(u_{i-1}^n)}{h^2}, \end{aligned}$$

where the so-called Engquist-Osher numerical flux [14] takes the form

$$f^{\text{EO}}(k, u_1, u_2) = \int_0^{u_1} (f_u(k, s) \vee 0) ds + \int_0^{u_2} (f_u(k, s) \wedge 0) ds + f(k, 0).$$

Here and in the following, $a \vee b = \max\{a, b\}$ and $a \wedge b = \min\{a, b\}$. Note that k and u are discretized on grids that are staggered with respect to each other. Concretely, we set

$$\begin{aligned} u_{\Delta t}(x, t) &= \sum_{i, n} \chi_{[x_{i-1/2}, x_{i+1/2}] \times [t_n, t_{n+1})} u_i^n, \\ k_{\Delta t} &= \sum_i \chi_{[x_i, x_{i+1})} k_{i+1/2}, \end{aligned}$$

where $k_{i+1/2} = k(x_{i+1/2})$ and $x_i = ih$.

We have chosen to analyse the above scheme because of its simplicity. One can, however, adopt the method of proof developed in this paper and obtain similar results for other schemes (e.g., all monotone schemes) as well as more general equations. For example, under the assumption that $k \equiv 1$, Evje and Karlsen [20] have studied high order difference schemes (based on the MUSCL idea) for degenerate parabolic equations with source terms. One can easily combine the ideas in the present paper with those in [20] and obtain high order difference schemes for degenerate parabolic equations with source terms and $k = k(x)$ non-constant. Moreover, one can easily treat the case where k possesses also a temporal dependence, i.e., $k = k(x, t)$. Although we consider only explicit schemes in this paper, one can easily adopt the techniques used herein to analyse semi-implicit and implicit schemes (the details will be presented elsewhere).

Assuming that u_0 , k and k' are in BV , we are able to show that the approximate solutions $\{u_{\Delta t}\}_{\Delta t > 0}$ generated by our scheme converge strongly in L^1_{loc} as $\Delta t \downarrow 0$ to the unique entropy solution. Furthermore, in the hyperbolic case, we show that this convergence has a rate. More precisely, we prove

Theorem 1.1. *Let $u_{\Delta t}$ denote the function generated by the Engquist-Osher scheme. We assume that the time step Δt is related to the spatial step h through an appropriate CFL condition. If u_0 , k and k' are in $BV \cap L^1 \cap L^\infty$, then*

$$u = \lim_{\Delta t \downarrow 0} u_{\Delta t}$$

is the unique entropy solution to (1.1). Furthermore, if $A' \equiv 0$, then

$$\|u(\cdot, t) - u_{\Delta t}(\cdot, t)\|_{L^1(\mathbb{R})} = \mathcal{O}(\sqrt{\Delta t}).$$

We remark that Theorem 1.1 provides an existence result for entropy solutions of strongly degenerate parabolic equations which complements those in [50, 5]. We also remark that the question of a convergence rate for the difference approximations to degenerate parabolic equations will be addressed elsewhere.

We now relate our results to the ones obtained by Evje and Karlsen [19, 17], who analyse monotone difference approximations of (1.1) in the special case $k \equiv 1$. In this case, the authors gave a fairly complete analysis for the one-dimensional equation under certain smoothness assumptions on the initial function u_0 , in which case it actually holds that $A(u)$ belongs to the Hölder space $C^{1,1/2}(\mathbb{R} \times [0, T])$ and not merely $L^2(0, T; H^1(\mathbb{R}))$ as follows from our analysis. We mention also the work [16] which generalizes the analysis in [19, 17] to the more difficult case of *doubly* nonlinear degenerate parabolic equations. In the present paper, we dispense with most of the smoothness assumptions on u_0 used in [19, 17]. Moreover, in the multidimensional case, the authors of [19] do not prove that the limit u of their monotone difference approximations satisfies (ii) in (1.3), a result that can be easily established by adopting the techniques developed in the present paper.

We continue with a few words about the proof of Theorem 1.1. The proof of the first part of Theorem 1.1 is based on deriving uniform L^∞ , L^1 , and BV bounds on the approximate solution $u_{\Delta t}$. Equipped with the BV bound, we use the difference scheme itself and Kružkov's interpolation lemma [33] to show that $u_{\Delta t}$ is uniformly L^1 continuous in time. Kolmogorov's compactness criterion then immediately gives L^1_{loc} convergence (along a subsequence) of $\{u_{\Delta t}\}_{\Delta t > 0}$ to a function $u \in L^1 \cap L^\infty$. Uniqueness of the entropy solution [5, 28] (see also Theorem 2.1 herein) will imply that the whole sequence $\{u_{\Delta t}\}_{\Delta t > 0}$ converges and not just a subsequence.

To ensure that the limit u is the (unique) entropy solution in the sense of (1.3), we first prove that the difference scheme satisfies a so-called discrete (or cell) entropy inequality and hence it follows, by arguments analogous to the ones used to prove the Lax-Wendroff theorem, that the entropy condition (i) in (1.3) holds true for the limit u . In passing, we mention that the BV regularity and the cell entropy inequalities are used to derive the error estimate in the hyperbolic case. In doing so, we follow Kuznetsov [36] and Kružkov [34].

Finally, we show that the limit u satisfies (ii) in (1.3). The arguments needed to prove (ii) are rather involved and based on deriving a space estimate that is resemblant of the so-called *weak BV* estimates employed by Champier *et al.* [7] and Eymard *et al.* [21] to prove convergence of finite volume methods on unstructured grids for the hyperbolic equation, see also [1, 22] for the diffusion

equation. Equipped with our weak BV estimate and an appropriate time estimate, Kolmogorov's compactness criterion implies strong L^2_{loc} convergence (along a subsequence) of $\{A(u_{\Delta t})\}_{\Delta t > 0}$ to $A(u)$ and $\nabla A(u) \in L^2$.

Throughout this paper the coefficient $k(x)$ is not allowed to be discontinuous. In the one-dimensional hyperbolic case ($A' \equiv 0$) with $k(x)$ depending discontinuously on x , the equation (1.1) is often written as the following 2×2 system:

$$(1.4) \quad u_t + f(k, u)_x = 0, \quad k_t = 0.$$

If $\partial f / \partial u$ changes sign, then this system is non-strictly hyperbolic. This complicates the analysis, and in order to prove compactness of approximated solutions a singular transformation $\Psi(k, u)$ has been used by several authors [45, 23, 30, 29]. In these works convergence of the Glimm scheme and of front tracking was established in the case where k may be discontinuous. Under weaker conditions on k , e.g., $k' \in BV$, and for f convex in u , convergence of the one-dimensional Godunov method for (1.4) (not for (1.1)) was shown by Isaacson and Temple in [27]. Recently, convergence of the one-dimensional Engquist-Osher method for (1.1) was shown by Towers [46, 47] in the case where k is piecewise continuous. In this case, the Kruřkov entropy condition (1.3) no longer applies, and in [30] a wave entropy condition analogous to the Oleinik entropy condition introduced in [40] was used to obtain uniqueness. We intend to study the degenerate parabolic case (1.1) with a discontinuous $k(x)$ in future work.

The rest of this paper is organized as follows: In the next section we introduce (precisely) the notion of an entropy solution, and state the theorem regarding uniqueness and the L^1 contraction property of the solution operator to (1.1). We then proceed to show convergence and convergence rates of difference schemes for the hyperbolic equation. In the last section we show convergence of difference schemes for the degenerate parabolic equation.

Throughout this paper we denote by C a generic constant, not depending on our discretization parameter Δt . Note that the actual value of C may change from one line to the next during a calculation.

2. PRELIMINARIES

In this section we first give a precise definition of an entropy solution, and then present some technical tools that we shall use.

2.1. Definition of the entropy solution. Throughout this paper we let $f_i(k^i, u)$ be smooth functions $\mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, and set $f(k, u) = (f_1(k^1, u), \dots, f_d(k^d, u))$. We assume that $A : \mathbb{R} \rightarrow \mathbb{R}$ is a function that satisfies

$$(2.1) \quad A \in \text{Lip}_{\text{loc}}(\mathbb{R}) \text{ and } A(\cdot) \text{ is nondecreasing with } A(0) = 0.$$

Concerning the flux function $f : \mathbb{R}^d \times \mathbb{R} \rightarrow \mathbb{R}^d$, we assume that $f \in C^3(\mathbb{R}^d \times \mathbb{R}; \mathbb{R}^d)$ and that

$$(2.2) \quad f_i, \partial_u f_i, \partial_k f_i, \partial_{uk} f_i, \partial_{ukk} f_i \in \text{Lip}(\mathbb{R} \times \mathbb{R}; \mathbb{R}), \quad \text{for } i = 1, \dots, d.$$

Furthermore, we assume that the relevant Lipschitz constants are bounded by

$$|\partial_u f_i| \leq L_u, \quad |\partial_k f_i| \leq L_k, \quad |\partial_{uk} f_i| \leq L_{uk}, \quad \text{and so on,}$$

for all i and for some constants L_u, L_k, L_{uk} . Without explicitly mentioning this any more, we will always assume in this paper that $f(k, 0) = 0$ for all k . Note that we can do so without loss of generality.

Regarding the coefficient k we assume that

$$(2.3) \quad k^i \in C(\mathbb{R}^d) \cap BV(\mathbb{R}^d), \quad \partial_x k^i \in L^\infty(\mathbb{R}^d) \cap BV(\mathbb{R}^d) \text{ for all } i \text{ and } j.$$

Under the above assumptions we shall study difference approximations to (1.1). Following [28] (see also Carrillo [5]), an entropy solution is defined as follows:

Definition 2.1. *An entropy solution of (1.1) is a measurable function $u = u(x, t)$ satisfying:*

$$\text{D.1 } u \in L^1(\Pi_T) \cap L^\infty(\Pi_T) \cap C(0, T; L^1(\mathbb{R}^d)).$$

D.2 For all $c \in \mathbb{R}$, and all non-negative test functions φ in $C_0^\infty(\Pi_T)$ the following entropy inequality holds:

$$(2.4) \quad \iint_{\Pi_T} \left(|u - c| \varphi_t + \text{sign}(u - c) (f(k(x), u) - f(k(x), c)) \cdot \nabla \varphi + |A(u) - A(c)| \Delta \varphi - \text{sign}(u - c) \text{div} f(k(x), c) \varphi \right) dt dx \geq 0.$$

D.3 $A(u) \in L^2(0, T; H^1(\mathbb{R}^d))$.

D.4 Essentially as $t \rightarrow 0+$,

$$\int_{\mathbb{R}^d} |u(x, t) - u_0(x)| dx \rightarrow 0.$$

Remark 2.1. (i) Observe that when $A' \equiv 0$, (2.4) reduces to the well known entropy inequality for scalar conservation laws introduced by Kruřkov [34] and Vol'pert [49].

(ii) Condition (D.4), i.e., that the initial datum u_0 should be taken by continuity, motivates the requirement of continuity with respect to t in condition (D.1).

The following theorem from [28] shows that the initial value problem (1.1) is well posed:

Theorem 2.1. Assume that (2.1), (2.2) and (2.3) hold. Let $v, u \in L^\infty(0, T; BV(\mathbb{R}^d))$ be entropy solutions of (1.1) with initial data $v_0, u_0 \in L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d) \cap BV(\mathbb{R}^d)$, respectively. Then for almost all $t \in (0, T)$,

$$(2.5) \quad \|v(\cdot, t) - u(\cdot, t)\|_{L^1(\mathbb{R}^d)} \leq \|v_0 - u_0\|_{L^1(\mathbb{R}^d)}.$$

In particular, there exists at most one entropy solution of the initial value problem (1.1).

Remark 2.2. At the expense of losing (2.5), the assumption that $v, u \in L^\infty(0, T; BV(\mathbb{R}^d))$ can be removed and uniqueness still holds, see [28].

2.2. Some mathematical tools. In this section we present some mathematical tools that we shall use in the analysis.

Let $z : \mathbb{R}^d \times (0, T) \rightarrow \mathbb{R}$ be a function such that $z(\cdot, t) \in L^1(\mathbb{R}^d)$ for all $t \in (0, T)$. By a modulus of continuity, we mean a nondecreasing continuous function $\nu : \mathbb{R}_+^0 \rightarrow \mathbb{R}_+^0$ such that $\nu(0) = 0$. We say that u has a spatial modulus of continuity if

$$(2.6) \quad \sup_{|\varepsilon| \leq y} \int_{\mathbb{R}^d} |u(x + \varepsilon, t) - u(x, t)| dx \leq \nu(y; u),$$

(where ν may depend on t). We also say that u has a temporal modulus of continuity if there is a modulus of continuity $\omega(\cdot; u)$ such that for each $\tau \in (0, T)$,

$$(2.7) \quad \sup_{0 \leq \varepsilon \leq \tau} \int_{\mathbb{R}^d} |u(x, t + \varepsilon) - u(x, t)| dx \leq \omega(\tau; u), \quad \forall t \in (0, T - \tau).$$

Let $\theta(r)$ be a smooth non-negative function of a single variable r such that

$$\theta(r) = \theta(-r), \quad \theta(r) = 0, \quad \text{for } |r| \geq 1, \quad \text{and} \quad \int_{\mathbb{R}} \theta(r) dr = 1.$$

Let $\delta_\varepsilon(x) = (1/\varepsilon^d)\theta(|x|/\varepsilon)$, and, with a slight abuse of notation, $\delta_\varepsilon(t) = (1/\varepsilon)\theta(t/\varepsilon)$. Now define a test function $\varphi(x, y, t, s)$ by

$$\varphi(x, y, t, s) = \delta_\varepsilon(x - y)\delta_\varepsilon(t - s).$$

For a function $u = u(x, t)$, set

$$(2.8) \quad \lambda(u, c) = - \iint_{\Pi_T} \left(|u - c| \varphi_t + \text{sign}(u - c) (f(k, u) - f(k, c)) \varphi_x - \text{sign}(u - c) f(k, c)_{,x} \varphi \right) dt dx \\ + \int_{\mathbb{R}} |u - c| \varphi \Big|_{t=0}^{t=T} dx.$$

For two functions u and v we define the functional $\Lambda_\varepsilon(u, v)$ as

$$(2.9) \quad \Lambda_\varepsilon(u, v) = \iint_{\Pi_T} \lambda(u, v(y, s)) ds dy,$$

where $u = u(x, t)$ and $v = v(y, s)$. In passing, we note that if $A' \equiv 0$, and u is an entropy solution of (1.1), then

$$(2.10) \quad \Lambda_\varepsilon(u, v) \leq 0.$$

For two arbitrary functions u and v we have the following result:

Lemma 2.1 (Kuznetsov's lemma). *Assume that $k = (k^1, \dots, k^d)$ is in $C(\mathbb{R}^d)$ and k' is in $L^\infty(\mathbb{R}^d)$ and that both k and k_{x_i} have moduli of continuity for all $i = 1, \dots, d$. If u and v are in $L^1(\Pi_T)$ and have moduli of continuity in space and time, then*

$$(2.11) \quad \|u(\cdot, T) - v(\cdot, T)\|_{L^1(\mathbb{R}^d)} \leq \|u(\cdot, 0) - v(\cdot, 0)\|_{L^1(\mathbb{R}^d)} + \Lambda_\varepsilon(u, v) + \Lambda_\varepsilon(v, u) \\ + \frac{1}{2} [\nu(u(\cdot, 0); \varepsilon) + \nu(v(\cdot, 0); \varepsilon) + \nu(u(\cdot, T); \varepsilon) + \nu(v(\cdot, T); \varepsilon)] \\ + \frac{1}{2} [\omega(u(\cdot, T); \varepsilon) + \omega(v(\cdot, T); \varepsilon) + \omega(u(\cdot, 0); \varepsilon) + \omega(v(\cdot, 0); \varepsilon)] \\ + \|\text{div} k\|_{L^\infty} L_u T \sup_{0 \leq t \leq T} (\nu(u(\cdot, t); \varepsilon) + \omega(u(\cdot, t); \varepsilon)) \\ + CT \left(\|\text{div} k\|_{L^\infty} \nu(k; \varepsilon) + \max_i \nu(k_{x_i}; \varepsilon) \right),$$

where $\omega(\cdot; \cdot)$ denotes a temporal modulus of continuity, and $\nu(\cdot; \cdot)$ denotes a spatial modulus. The constant C depends on f_k and f_{kk} .

Proof. We shall prove this lemma for $d = 1$, the general proof is completely analogous. Remember that $\varphi_x = -\varphi_y$ and $\varphi_t = -\varphi_s$. By adding $\Lambda_\varepsilon(u, v)$ and $\Lambda_\varepsilon(v, u)$ we find that

$$(2.12) \quad \Lambda_\varepsilon(u, v) + \Lambda_\varepsilon(v, u) = - \iint_{\Pi_T} \iint_{\Pi_T} \text{sign}(u - v) \left[(f(k(x), u) - f(k(x), v)) \varphi_x - f(k(x), v)_{,x} \varphi \right. \\ \left. - (f(k(y), u) - f(k(y), v)) \varphi_x + f(k(y), u)_{,y} \varphi \right] dt dx ds dy \\ + \iint_{\Pi_T} \int_{\mathbb{R}} \varphi(x, y, T, s) |u(x, T) - v(y, s)| dx ds dy \\ + \iint_{\Pi_T} \int_{\mathbb{R}} \varphi(x, y, t, T) |u(x, t) - v(y, T)| dy dt dx \\ - \iint_{\Pi_T} \int_{\mathbb{R}} \varphi(x, y, 0, s) |u(x, 0) - v(y, s)| dx ds dy \\ - \iint_{\Pi_T} \int_{\mathbb{R}} \varphi(x, y, t, 0) |u(x, t) - v(y, 0)| dy dt dx.$$

Using standard arguments, the four last terms will give the $\|u - v\|_{L^1}$ terms and the terms starting with $\frac{1}{2}[\dots]$ in (2.11). Regarding the remaining term, we follow Kružkov [34]. Let

$$m(x, y, w) = f_k(k(x), w)k'(x) - f_k(k(y), w)k'(y).$$

Then we rewrite the square brackets in (2.12) as

$$\begin{aligned} & \left[(f(k(x), u) - f(k(x), v)) \varphi_x - f(k(x), v)_{,x} \varphi - (f(k(y), u) - f(k(y), v)) \varphi_x + f(k(y), u)_{,y} \varphi \right] \\ &= [(f(k(y), u) - f(k(x), u)) \varphi_y + f(k(y), u)_{,y} \varphi] \\ & \quad + [(f(k(y), v) - f(k(x), v)) \varphi_x - f(k(x), v)_{,x} \varphi] \\ &= f_k(k(y), u)k'(y) [(y-x)\varphi_y + \varphi] + m(\xi_1, y, u)(x-y)\varphi_y \\ & \quad + f_k(k(y), v)k'(y) [(y-x)\varphi_x - \varphi] \\ & \quad + m(y, x, v)\varphi + m(\xi_2, y, v)(y-x)\varphi_x \\ &= -f_k(k(y), u)k'(y) [(y-x)\varphi]_x + f_k(k(y), v)k'(y) [(y-x)\varphi]_x \\ & \quad + (m(\xi_1, y, u) + m(\xi_2, y, v)) \varphi_y + m(y, x, v)\varphi \\ &= [k'(y) (f_k(k(y), v) - f_k(k(y), u))] [(x-y)\varphi]_x \\ & \quad + (m(\xi_1, y, u) + m(\xi_2, y, v)) (x-y)\varphi_y + m(y, x, v)\varphi, \end{aligned}$$

where $|\xi_i - y| \leq |x - y|$ for $i = 1, 2$. Let now

$$F(u, v) = \text{sign}(u - v) [k'(y) (f_k(k(y), v) - f_k(k(y), u))],$$

and note that F is Lipschitz continuous, with Lipschitz constant given by $\|k'\|_{L^\infty} L_u$, in both arguments. Next, we obviously have that

$$\iint_{\Pi_T} \iint_{\Pi_T} F(u(y, s), v(y, s)) [(x-y)\varphi]_x dt dx ds dy = 0.$$

Thus, our troublesome term reads

(2.13)

$$\iint_{\Pi_T} \iint_{\Pi_T} [F(u(x, t), v(y, s)) - F(u(y, s), v(y, s))] [(x-y)\varphi]_x dt dx ds dy$$

$$(2.14) \quad + \iint_{\Pi_T} \iint_{\Pi_T} (\text{sign}(u - v) (m(\xi_1, y, u) + m(\xi_2, y, v)) (x-y)\varphi_y + m(y, x, v)\varphi) dt dx ds dy.$$

Now

$$|m(x, y, u)| \leq L_k |k'(x) - k'(y)| + \|k'\|_{L^\infty} L_{uk} |k(x) - k(y)|.$$

Hence, (2.14) is bounded by integrals of the form

$$(2.15) \quad \iint_{\Pi_T} \iint_{\Pi_T} |l(\xi) - l(y)| |(x-y)\delta'_\varepsilon(x-y)| \delta_\varepsilon(t-s) dt dx ds dy,$$

and

$$(2.16) \quad \iint_{\Pi_T} \iint_{\Pi_T} |l(\xi) - l(y)| \delta_\varepsilon(x-y) \delta_\varepsilon(t-s) dt dx ds dy$$

where $\xi = x, \xi_1$ or ξ_2 , and $l = k$ or $l = k'$. Since $|x - y| \leq \varepsilon$ we have that $|\xi - y| \leq \varepsilon$ in (2.15) and (2.16), so they are both easily seen to be bounded by $\nu(l; \varepsilon)$. The rest of (2.13) is bounded

as follows

$$\begin{aligned}
& \iint_{\Pi_T} \iint_{\Pi_T} \left| F(u(x, t), v(y, s)) - F(u(y, s), v(y, s)) \right| |((x - y)\varphi)_x| dt dx ds dy \\
& \leq \|k'\|_{L^\infty} L_u \iint \iint |u(x, t) - u(y, s)| |((x - y)\varphi)_x| dt dx ds dy \\
& \leq \frac{\|k'\|_{L^\infty} L_u}{\varepsilon} \left[\int_0^T \iint_{|x-y|\leq\varepsilon} |u(x, t) - u(y, t)| dx dy dt \right. \\
& \quad \left. + \iint \int_{|t-s|\leq\varepsilon} |u(y, t) - u(y, s)| dy dt ds \right] \\
& \leq \|k'\|_{L^\infty} L_u T \sup_{0\leq t\leq T} (\nu(u(\cdot, t); \varepsilon) + \omega(u(\cdot, t); \varepsilon)).
\end{aligned}$$

This concludes the proof of the lemma. \square

We need the following general L^1 and L^2 compactness criteria

Lemma 2.2 (L^1_{loc} compactness lemma). *Let $\{z_h\}_{h>0}$ be a sequence of functions defined on $\mathbb{R}^d \times (0, T)$ which satisfies:*

- (1) *There exists a constant $C_1 > 0$ which is independent of h such that*

$$\|z_h(\cdot, t)\|_{L^\infty(\mathbb{R}^d)} \text{ and } \|z_h(\cdot, t)\|_{L^\infty(\mathbb{R}^d)} \leq C_1, \quad \forall t \in (0, T);$$

- (2) *There exists a spatial modulus of continuity ν which is independent of h such that*

$$\|z_h(\cdot + y, t) - z_h(\cdot, t)\|_{L^1(\mathbb{R}^d)} \leq \nu(|y|; z_h) \text{ as } y \rightarrow 0, \quad \forall t \in (0, T);$$

- (3) *There exists a temporal modulus of continuity ω which is independent of h such that*

$$\|z_h(\cdot, t + \tau) - z_h(\cdot, t)\|_{L^1(\mathbb{R}^d)} \leq \omega(\tau; z_h), \quad \forall t \in (0, T - \tau) \text{ whenever } \tau \in (0, T).$$

Then $\{z_h\}_{h>0}$ is compact in the strong topology of $L^1_{\text{loc}}(\mathbb{R}^d \times (0, T))$. Moreover, any limit point of $\{z_h\}_{h>0}$ belongs to $L^1(\mathbb{R}^d \times (0, T)) \cap L^\infty(\mathbb{R}^d \times (0, T)) \cap C(0, T; L^1(\mathbb{R}^d))$.

Lemma 2.3 (L^2_{loc} compactness lemma). *Let $\{z_h\}_{h>0}$ be a sequence of functions defined on $\mathbb{R}^d \times (0, T)$ which satisfies:*

- (1) *There exists a constant $C_1 > 0$ which may depend on T , but not h , such that*

$$\|z_h\|_{L^2(\mathbb{R}^d \times (0, T))} \leq C_1;$$

- (2) *There exists a constant $C_2 > 0$ which may depend on T but not h such that*

$$\|z_h(\cdot + y, \cdot) - z_h(\cdot, \cdot)\|_{L^2(\mathbb{R}^d \times (0, T))} \leq C_2 (|y| + h) \text{ for all } y \text{ as } h \downarrow 0;$$

- (3) *There exists a constant $C_3 > 0$ which may depend on T but not h such that*

$$\|z_h(\cdot, \cdot + \tau) - z_h(\cdot, \cdot)\|_{L^2(\mathbb{R}^d \times (0, T - \tau))} \leq C_3 \sqrt{\tau + h} \text{ for all } \tau > 0 \text{ as } h \downarrow 0.$$

Then $\{z_h\}_{h>0}$ is compact in the strong topology of $L^2_{\text{loc}}(\mathbb{R}^d \times (0, T))$. Moreover, any limit point of $\{z_h\}_{h>0}$ belongs to $L^2(0, T; H^1(\mathbb{R}^d))$.

To prove that the difference approximations possess some L^1 time continuity, we shall use the following lemma due to Kruřkov [33].

Lemma 2.4 (Kruřkov's interpolation lemma [33]). *Let $z(x, t)$ be a bounded measurable function defined on $\mathbb{R}^d \times (0, T)$. For $t \in (0, T)$ assume that z possesses a spatial modulus of continuity*

$$(2.17) \quad \int_{\mathbb{R}^d} |z(x + \varepsilon, t) - z(x, t)| dx \leq \nu(|\varepsilon|; z),$$

where ν does not depend on t . Suppose that for any $\phi \in C_0^\infty(\mathbb{R}^d)$ and any $t_1, t_2 \in (0, T)$,

$$(2.18) \quad \left| \int_{\mathbb{R}^d} (z(x, t_2) - z(x, t_1)) \phi(x) dx \right| \leq \text{Const}_T \cdot \left(\sum_{|\alpha| \leq m} c_\alpha \|D^\alpha \phi\|_{L^\infty(\mathbb{R}^d)} \right) \cdot |t_2 - t_1|,$$

where α denotes a multi-index, and c_α are constants not depending on ϕ or t . Then for any $t_1, t_2 \in (0, T)$ and all $\varepsilon > 0$

$$(2.19) \quad \int_{\mathbb{R}^d} |z(x, t_2) - z(x, t_1)| dx \leq C \cdot \left(|t_2 - t_1| \sum_{|\alpha| \leq m} \frac{c_\alpha}{\varepsilon^{|\alpha|}} + \nu(z; \varepsilon) \right).$$

Proof. Let $\delta_\varepsilon(x)$ denote the usual mollifying kernel of radius ε , and let $d(x) = z(x, t_2) - z(x, t_1)$. For $r > \varepsilon$, set

$$\beta(x) = \begin{cases} \text{sign}(d(x)) & \text{for } |x| \leq r - \varepsilon, \\ 0 & \text{otherwise,} \end{cases}$$

and set $\beta_\varepsilon = \beta * \delta_\varepsilon$. Then β_ε is in $C_0^\infty(\mathbb{R}^n)$, has support inside the ball B_r , and we have the bound $|D^\alpha \beta_\varepsilon| \leq \text{Const}/\varepsilon^{|\alpha|}$. Also

$$\begin{aligned} \left| \int_{B_r} d(x) dx \right| &\leq \int_{B_r} |d(x) - \beta_\varepsilon(x)d(x)| dx + \left| \int_{B_r} \beta_\varepsilon(x)d(x) dx \right| \\ &\leq \iint_{\mathbb{R}^d} |d(x) - d(x-y)| \delta_\varepsilon(y) dx dy + C |t_2 - t_1| \sum_{|\alpha| \leq m} \frac{c_\alpha}{\varepsilon^{|\alpha|}} \\ &\leq C \left(\nu(\varepsilon; z) + |t_2 - t_1| \sum_{|\alpha| \leq m} \frac{c_\alpha}{\varepsilon^{|\alpha|}} \right). \end{aligned}$$

Letting $r \uparrow \infty$, we obtain (2.19). □

We shall also need the technical result:

Lemma 2.5 (Crandall and Tartar [13]). *Let (Ω, μ) be some measure space and let D be a subset of $L^1(\Omega)$. Assume that if u and v are in D , then also $u \vee v$ is in D . Let T be a map $D \rightarrow D$ such that*

$$\int_{\Omega} T(u) d\mu = \int_{\Omega} u d\mu, \quad \forall u \in D.$$

Then the following statements, valid for all u and v in D , are equivalent:

- (i) *If $u \leq v$, then $T(u) \leq T(v)$.*
- (ii) $\int_{\Omega} (T(u) - T(v)) \vee 0 d\mu \leq \int_{\Omega} (u - v) \vee 0 d\mu$.
- (iii) $\int_{\Omega} |T(u) - T(v)| d\mu \leq \int_{\Omega} |u - v| d\mu$.

3. DIFFERENCE APPROXIMATIONS: THE HYPERBOLIC EQUATION

In this section we analyze a difference approximation to the solution of the hyperbolic equation

$$(3.1) \quad u_t + \text{div} f(k, u) = 0, \quad u(x, 0) = u_0(x), \quad (x, t) \in \Pi_T,$$

where k and f satisfy (2.2) and (2.3) respectively. For simplicity, we shall assume that u_0 has compact support, which implies that all subsequent sums over I are finite. To obtain results in the general case, we can use the stability result in Theorem 2.1 (these standard details will not be written out). We have chosen to analyze the hyperbolic equation separately since the analysis parallels the general case but is simpler. In the next section, where we consider the general case, we shall use several of the estimates obtained in this section. Furthermore, we provide a convergence rate in the hyperbolic case.

As already mentioned in the introduction, we use the Engquist-Osher scheme to make the analysis more concrete, but our methods can easily be adapted to general monotone schemes. For a scalar flux function $f_i(k, u)$, the Engquist-Osher flux f_i^{EO} [14] can be written as

$$(3.2) \quad f_i^{\text{EO}}(k, u, v) = \frac{1}{2} \left(f_i(k, u) + f_i(k, v) - \int_u^v |\partial_u f_i(k, s)| ds \right).$$

To define the scheme, let I be a multi index $I = (i_1, \dots, i_d)$ and set e_i to be a multi-index with zeros everywhere except for a 1 at the i th place. Furthermore, we choose a time step Δt such that

$N\Delta t = T$ and a spatial discretization parameter $h > 0$. Letting $\lambda = \Delta t/h$, the Engquist-Osher scheme reads

$$(3.3) \quad \begin{aligned} u_I^{n+1} &= u_I^n - \lambda \sum_{i=1}^d \left[\bar{f}_{I+e_i/2}^{\text{EO}} - \bar{f}_{I-e_i/2}^{\text{EO}} \right] \\ &= u_I^n - \lambda \sum_{i=1}^d \frac{1}{2^{d-1}} \sum_{\substack{j \neq i \\ J=I \pm e_j/2}} \left[f_i^{\text{EO}} \left(k_{J+e_i/2}^j, u_I^n, u_{I+e_i}^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right], \end{aligned}$$

where

$$(3.4) \quad \bar{f}_{I+e_i/2}^{\text{EO}} = \frac{1}{2^{d-1}} \sum_{\substack{j \neq i \\ J=I \pm e_j/2}} f_i^{\text{EO}} \left(k_{J+e_i/2}^j, u_I^n, u_{I+e_i}^n \right).$$

The approximate solution $u_{\Delta t}$ is then defined as

$$(3.5) \quad u_{\Delta t}(x, t) = u_I^n, \quad \text{for } (x, t) \in \chi_I \times [t_n, t_{n+1}),$$

where χ_I denotes the set

$$\chi_I = \left\{ x \in \mathbb{R}^d \mid (x_{I-e_i/2})_i \leq x_i < (x_{I+e_i/2})_i, \quad i = 1, \dots, d \right\}$$

and $x_I = hI$. We initialize the scheme by setting

$$u_I^0 = \frac{1}{|\chi_I|} \int_{\chi_I} u_0(x) dx.$$

Note that $f_i^{\text{EO}}(k, u, v)$ is not continuously differentiable in the first variable but merely Lipschitz. Therefore we introduce the following auxiliary numerical flux

$$f_i^{\text{EO}, \varepsilon}(k, u, v) = \frac{1}{2} \left(f_i(k, u) + f_i(k, v) - \int_u^v |\partial_u f_i(k, s)|_\varepsilon ds \right),$$

where $|\cdot|_\varepsilon$ is a smooth approximation to the absolute value function $|\cdot|$ such that

$$||a| - |a|_\varepsilon| \leq \varepsilon \quad \text{and} \quad |a| = |a|_\varepsilon \quad \text{for } |a| > \varepsilon.$$

Note in particular that

$$(3.6) \quad \left| f_i^{\text{EO}}(k, u, v) - f_i^{\text{EO}, \varepsilon}(k, u, v) \right| \leq |u - v| \varepsilon, \quad \forall k, u, v.$$

This scheme can be analyzed as follows. Set

$$\widehat{\sum}_i = \frac{1}{2^{d-1}} \sum_{\substack{j \neq i \\ J=I \pm e_j/2}} \quad \text{and} \quad \psi_i(k, u, v) = \frac{\partial f_i^{\text{EO}, \varepsilon}}{\partial k}(k, u, v).$$

Note that

$$|\psi_i(k, u, v)| \leq L_k + \frac{1}{2} |u - v| L_{uk}.$$

Then we define F_I as the right hand side in (3.3), i.e.,

$$(3.7) \quad u_I^{n+1} = F_I(u^n).$$

Assuming the CFL condition

$$(3.8) \quad 2\lambda \sum_{i=1}^d \max_{k, u} |\partial_u f_i(k, u)| \leq 1,$$

it is easy to show that $\frac{\partial F_I}{\partial u_J^n} \geq 0$ for all J . In other words, the Engquist-Osher scheme is monotone. Let $U^n = \max_I |u_I^n|$, then

$$\begin{aligned} |u_I^{n+1}| &= |F_I(u^n)| \leq F_I(U^n) \\ &= U^n + \lambda \sum_{i=1}^d \widehat{\sum}_i \left[f_i(k_{J+e_i/2}^i, U^n) - f_i(k_{J-e_i/2}^i, U^n) \right] \\ &\leq U^n + L_k \Delta t \sum_{i=1}^d \widehat{\sum}_i \left| k_{J+e_i/2}^i - k_{J-e_i/2}^i \right| \frac{1}{h} \leq U^n + L_k \Delta t \sum_{i=1}^d \|k_{x_i}^i\|_{L^\infty(\mathbb{R}^d)}. \end{aligned}$$

From this it follows that

$$(3.9) \quad \|u_{\Delta t}(\cdot, T)\|_{L^\infty(\mathbb{R}^d)} \leq \|u_0\|_{L^\infty(\mathbb{R}^d)} + T L_k d \max_i \|k_{x_i}^i\|_{L^\infty(\mathbb{R}^d)}.$$

Next, by the Crandall and Tartar lemma (see Lemma 2.5) and the monotonicity of F_I ,

$$\sum_I |F_I(u^n) - F_I(0)| \leq \sum_I |u_I^n|.$$

Hence

$$\begin{aligned} h^d \sum_I |u_I^{n+1}| &\leq h^d \sum_I |u_I^n| + h^d \lambda \sum_{i=1}^d \widehat{\sum}_i \left| f^i(k_{J+e_i/2}^i, 0) - f^i(k_{J-e_i/2}^i, 0) \right| \\ &\leq h^d \sum_I |u_I^n| + K \Delta t |k|_{BV(\mathbb{R}^d)}. \end{aligned}$$

This means that

$$(3.10) \quad \|u_{\Delta t}(\cdot, T)\|_{L^1(\mathbb{R}^d)} \leq \|u_0\|_{L^1(\mathbb{R}^d)} + K T |k|_{BV(\mathbb{R}^d)}.$$

For any quantity X_I defined on our grid let $D_\ell X_I$ denote the upward difference

$$(3.11) \quad D_\ell X_I = X_{I+e_\ell} - X_I.$$

To bound the total variation of $u_{\Delta t}$ we again use the Crandall-Tartar lemma, which in this case gives

$$\sum_I |F_{I+e_\ell}(u_{+e_\ell}^n) - F_{I+e_\ell}(u^n)| \leq \sum_I |u_{I+e_\ell}^n - u_I^n|.$$

Note that we have

$$u_{I+e_\ell}^{n+1} = F_{I+e_\ell}(u_{+e_\ell}^n)$$

and

$$(3.12) \quad \sum_I |D_\ell u_I^{n+1}| \leq \sum_I |D_\ell u_I^n| + \left| \sum_I [F_{I+e_\ell}(u^n) - F_I(u^n)] \right|.$$

Before we start to estimate the difference on the right-hand side of (3.12), note that

$$\begin{aligned} &\left| \psi_i(k_1, u, v) - \psi_i(k_2, u, v) \right| \\ &= \frac{1}{2} \left| (\partial_{kk} f_i(\eta, u) + \partial_{kk} f_i(\nu, v)) (k_1 - k_2) \right. \\ &\quad \left. - \int_u^v \left([\text{sign}_\varepsilon(\partial_u f_i(k_1, s)) - \text{sign}_\varepsilon(\partial_u f_i(k_2, s))] \partial_{uk} f_i(k_1, s) \right. \right. \\ &\quad \left. \left. + \text{sign}_\varepsilon(\partial_u f_i(k_2, s)) \partial_{ukk} f_i(\gamma, s) \right) ds \right| \\ &\leq \max_{k,u} |\partial_{kk} f_i(k, u)| |k_1 - k_2| + \max_{k,u} |\partial_{uk} f_i(k, u)| |u - v| \\ &\quad + \frac{1}{2} \max_{k,u} |\partial_{ukk} f_i(k, u)| |u - v| |k_1 - k_2|, \end{aligned}$$

where $\text{sign}_\varepsilon(\cdot)$ denotes the derivative of $|\cdot|_\varepsilon$. Furthermore, we have

$$\begin{aligned} |\psi_i(k, u_1, v) - \psi_i(k, u_2, v)| &\leq \max_{k, u} |\partial_{ku} f_i(k, u)| |u_1 - u_2|, \\ |\psi_i(k, u, v_1) - \psi_i(k, u, v_2)| &\leq \max_{k, u} |\partial_{ku} f_i(k, u)| |v_1 - v_2|. \end{aligned}$$

Using the above estimates on ψ_i and (3.6), there exist numbers $\xi_{J+e_\ell/2 \pm e_i/2}$ between $k_{J \pm e_i/2}^i$ and $k_{J+e_\ell \pm e_i/2}^i$ such that

$$\begin{aligned} &F_{J+e_\ell}(u^n) - F_I(u^n) \\ &= -\lambda \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^{\text{EO}} \left(k_{J+e_\ell+e_i/2}^i, u_I^n, u_{J+e_i}^n \right) - f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n, u_{J+e_i}^n \right) \right) \right. \\ &\quad \left. - \left(f_i^{\text{EO}} \left(k_{J+e_\ell-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right) \right] \\ &= \mathcal{O}(\varepsilon) - \lambda \sum_{i=1}^d \widehat{\sum}_i \left[\psi_i \left(\xi_{J+e_\ell/2+e_i/2}, u_I^n, u_{J+e_i}^n \right) D_\ell k_{J+e_i/2}^i \right. \\ &\quad \left. - \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_{I-e_i}^n, u_I^n \right) D_\ell k_{J-e_i/2}^i \right] \\ &= \mathcal{O}(\varepsilon) - \lambda \sum_{i=1}^d \widehat{\sum}_i \left[\psi_i \left(\xi_{J+e_\ell/2+e_i/2}, u_I^n, u_{J+e_i}^n \right) D_i D_\ell k_{J+e_i/2}^i \right. \\ &\quad \left. - D_i \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_{I-e_i}^n, u_I^n \right) D_\ell k_{J-e_i/2}^i \right] \\ &= \mathcal{O}(\varepsilon) - \lambda \sum_{i=1}^d \widehat{\sum}_i \left[\psi_i \left(\xi_{J+e_\ell/2+e_i/2}, u_I^n, u_{J+e_i}^n \right) D_i D_\ell k_{J+e_i/2}^i \right. \\ &\quad \left. - \left\{ \psi_i \left(\xi_{J+e_\ell/2+e_i/2}, u_I^n, u_{J+e_i}^n \right) - \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_I^n, u_{J+e_i}^n \right) \right. \right. \\ &\quad \left. \left. + \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_I^n, u_{J+e_i}^n \right) - \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_I^n, u_I^n \right) \right. \right. \\ &\quad \left. \left. + \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_I^n, u_I^n \right) - \psi_i \left(\xi_{J+e_\ell/2-e_i/2}, u_{I-e_i}^n, u_I^n \right) \right\} D_\ell k_{J-e_i/2}^i \right] \\ &\leq \mathcal{O}(\varepsilon) + \lambda \sum_{i=1}^d \widehat{\sum}_i \left[\left| \psi_i \left(\xi_{J+e_\ell/2+e_i/2}, u_I^n, u_{J+e_i}^n \right) D_i D_\ell k_{J+e_i/2}^i \right| \right. \\ &\quad \left. - \left\{ L_{kk} |D_i \xi_{J+e_\ell/2-e_i/2}| + L_{uk} |D_i u_I^n| + \frac{L_{ukk}}{2} |D_i u_I^n D_i \xi_{J+e_\ell/2-e_i/2}| \right. \right. \\ &\quad \left. \left. + L_{ku} (|D_i u_I^n| + |D_i u_{I-e_i}^n|) \right\} |D_\ell k_{J-e_i/2}^i| \right]. \end{aligned}$$

As the above inequality holds for any $\varepsilon > 0$, we can let $\varepsilon \downarrow 0$ and obtain

$$\begin{aligned} &|F_{J+e_\ell}(u^n) - F_I(u^n)| \\ &\leq \lambda \sum_{i=1}^d \widehat{\sum}_i \left[\left| \psi_i \left(\xi_{J+e_\ell/2+e_i/2}, u_I^n, u_{J+e_i}^n \right) D_i D_\ell k_{J+e_i/2}^i \right| \right. \\ &\quad \left. - \left\{ L_{kk} |D_i \xi_{J+e_\ell/2-e_i/2}| + L_{uk} |D_i u_I^n| + \frac{L_{ukk}}{2} |D_i u_I^n D_i \xi_{J+e_\ell/2-e_i/2}| \right. \right. \\ &\quad \left. \left. + L_{ku} (|D_i u_I^n| + |D_i u_{I-e_i}^n|) \right\} |D_\ell k_{J-e_i/2}^i| \right]. \end{aligned}$$

Since we have that ψ_i is bounded, we find that

$$\begin{aligned} \sum_I |D_\ell u_I^{n+1}| h^{d-1} &\leq \sum_I |D_\ell u_I^n| h^{d-1} \\ &+ C\Delta t \left\{ h^{d-2} \sum_I \sum_{i=1}^d \widehat{\sum}_i |D_\ell D_i k_{J+e_i/2}^i| \right. \\ &\quad \left. + h^{d-1} \max_{i,j} \|k_{x_j}^i\|_{L^\infty(\mathbb{R}^d)} \sum_I \sum_{i=1}^d \widehat{\sum}_i |D_\ell k_{J-e_i/2}^i| \right. \\ &\quad \left. + h^{d-1} \max_{i,j} \|k_{x_j}^i\|_{L^\infty(\mathbb{R}^d)} \sum_I \sum_{i=1}^d |D_i u_I^n| \right\} \end{aligned}$$

for some constant C independent of Δt . The first and second sums inside $\{\dots\}$ are bounded since we assume that k^i and $k_{x_j}^i$ are in $BV(\mathbb{R}^d)$. By summing the above over $\ell = 1, \dots, d$, we find that

$$\begin{aligned} |u_{\Delta t}(\cdot, t_{n+1})|_{BV(\mathbb{R}^d)} &= h^{d-1} \sum_{\ell=1}^d \sum_I |D_\ell u_I^{n+1}| \\ &\leq (1 + C\Delta t) |u_{\Delta t}(\cdot, t_n)|_{BV(\mathbb{R}^d)} + C\Delta t \left(|k|_{BV(\mathbb{R}^d)} + \max_{i,j} \|k_{x_j}^i\|_{BV(\mathbb{R}^d)} \right). \end{aligned}$$

Consequently,

$$(3.13) \quad |u_{\Delta t}(\cdot, t)|_{BV(\mathbb{R}^d)} \leq C \left(|u_0|_{BV(\mathbb{R}^d)} + t \right), \quad \forall t \in (0, T),$$

where C does not depend on Δt .

Next, we shall use the scheme to show that $u_{\Delta t} \in C(0, T; L^1(\mathbb{R}^d))$ uniformly in Δt . This is done as follows

$$\begin{aligned} h^d \sum_I |u_I^{n+1} - u_I^n| &\leq \Delta t h^{d-1} \sum_I \widehat{\sum}_i \sum_{i=1}^d \left[\left| f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n, u_{I+e_i}^n \right) - f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right| \right. \\ &\quad \left. + \max \left| \frac{\partial f_i^{\text{EO}}}{\partial k} \right| \left| D_i k_{J-e_i/2}^i \right| \right] \\ &\leq C\Delta t \left(|u_{\Delta t}|_{BV(\mathbb{R}^d)} + |k|_{BV(\mathbb{R}^d)} \right), \end{aligned}$$

from which we obtain

$$(3.14) \quad \|u_{\Delta t}(\cdot, t + \tau) - u_{\Delta t}(\cdot, t)\|_{L^1(\mathbb{R}^d)} \leq C\tau, \quad \forall t \in [0, T - \tau].$$

By Lemma 2.2, we have that the sequence $\{u_{\Delta t}\}_{\Delta t > 0}$ is compact in $L^1(\Pi_T)$. Moreover, any limit point of this sequence satisfies **(D.1)** and **(D.4)**.

Next, we shall prove a cell entropy inequality which ensures that any subsequence of $\{u_{\Delta t}\}_{\Delta t > 0}$ converges to the unique entropy solution. Let

$$w_I^n = u_I^n \vee c, \quad v_I^n = u_I^n \wedge c, \quad w_I^{n+1} = F_I(w_I^n), \quad v_I^{n+1} = F_I(v_I^n), \quad c_I^{n+1} = F_I(c),$$

where F_I is defined in (3.7). Then we have that

$$w_I^{n+1} \geq u_I^{n+1} \geq v_I^{n+1}, \quad v_I^{n+1} \leq c_I^{n+1} \leq w_I^{n+1}.$$

This implies that

$$|u_I^{n+1} - c_I^{n+1}| \leq w_I^{n+1} - v_I^{n+1}.$$

Now

$$\begin{aligned} & w_I^{n+1} - v_I^{n+1} \\ &= |u_I^n - c| - \lambda \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n \vee c, u_{I+e_i}^n \vee c \right) - f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n \wedge c, u_{I+e_i}^n \wedge c \right) \right) \right. \\ & \quad \left. - \left(f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n \vee c, u_I^n \vee c \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n \wedge c, u_I^n \wedge c \right) \right) \right]. \end{aligned}$$

Denoting the numerical entropy flux by

$$q_i^{\text{EO}}(k, u, v) = f_i^{\text{EO}}(k, u \vee c, v \vee c) - f_i^{\text{EO}}(k, u \wedge c, v \wedge c)$$

and noting that

$$\begin{aligned} |u_I^{n+1} - c| &= \left| u_I^{n+1} - c + \lambda \sum_{i=1}^d \widehat{\sum}_i \left[f_i \left(k_{J+e_i/2}^i, c \right) - f_i \left(k_{J-e_i/2}^i, c \right) \right] \right| \\ &\geq \text{sign}(u_I^{n+1} - c) \left(u_I^{n+1} - c + \lambda \sum_{i=1}^d \widehat{\sum}_i \left[f_i \left(k_{J+e_i/2}^i, c \right) - f_i \left(k_{J-e_i/2}^i, c \right) \right] \right) \\ &\geq |u_I^{n+1} - c| + \text{sign}(u_I^{n+1} - c) \lambda \sum_{i=1}^d \widehat{\sum}_i \left[f_i \left(k_{J+e_i/2}^i, c \right) - f_i \left(k_{J-e_i/2}^i, c \right) \right], \end{aligned}$$

we find that

$$\begin{aligned} (3.15) \quad |u_I^{n+1} - c| &\leq |u_I^n - c| - \lambda \sum_{i=1}^d \widehat{\sum}_i \left[q_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n, u_{I+e_i}^n \right) - q_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right] \\ &\quad - \lambda \sum_{i=1}^d \widehat{\sum}_i \text{sign}(u_I^{n+1} - c) D_i f_i \left(k_{J-e_i/2}^i, c \right). \end{aligned}$$

We now multiply (3.15) by a nonnegative test function, do summation by parts, and then subsequently send $\Delta t \rightarrow 0$. To take the limit $\Delta t \rightarrow 0$ in the expression involving the last term in (3.15), we need the following elementary lemma (whose easy proof is omitted):

Lemma 3.1. *Let $\Omega \subset \mathbb{R}^N$ and $g_j(x) \rightarrow g(x)$ a.e. in Ω . Then there exists a set F , which is at most countable, such that for any $c \in \mathbb{R} \setminus F$*

$$\text{sign}(g_j(x) - c) \rightarrow \text{sign}(g(x) - c) \quad \text{a.e. in } \Omega.$$

Equipped with this lemma, we conclude that a limit point u of $\{u_{\Delta t}\}_{\Delta t > 0}$ satisfies the entropy condition (2.4) (with $A' \equiv 0$) for almost all $c \in \mathbb{R}$. An approximation argument will then reveal that (2.4) actually holds true for all $c \in \mathbb{R}$. Hence, by the uniqueness of the entropy solutions, the whole sequence $\{u_{\Delta t}\}_{\Delta t > 0}$ converges to the unique entropy solution.

Now we shall use the cell entropy estimate and Kuznetsov's lemma (Lemma 2.1) to show that $u_{\Delta t}$ converges to the unique entropy solution at a rate of $\Delta t^{1/2}$. For simplicity we shall restrict our proof to the case of one space dimension, i.e., $d = 1$. However, with some effort, the calculations given below can be generalized to the multi-dimensional case $d > 1$.

Let $u(x, t)$ be the unique entropy solution to

$$(3.16) \quad u_t + f(k, u)_x = 0, \quad u(x, 0) = u_0(x)$$

where u_0 and k' is of bounded variation, and let $u_{\Delta t}(x, t)$ and $k_{\Delta t}$ be as before. Now $\Lambda_\varepsilon(u, u_{\Delta t}) \leq 0$, and all the continuity moduli in Kuznetsov's lemma are linear in ε , therefore (2.11) reads

$$(3.17) \quad \|u(\cdot, T) - u_{\Delta t}(\cdot, T)\|_{L^1(\mathbb{R})} \leq \|u_0 - u_{\Delta t}(\cdot, 0)\|_{L^1(\mathbb{R})} + \Lambda_\varepsilon(u_{\Delta t}, u) + C\varepsilon,$$

where the constant C does not depend on Δt . We must estimate $\Lambda_\varepsilon(u_{\Delta t}, u)$. Set

$$\eta = |u - c|, \quad q(k, u) = \text{sign}(u - c) (f(k, u) - f(k, c)).$$

Multiplying the cell entropy inequality (3.15) by positive numbers $h\varphi_i^n$ with $\varphi_i^n = 0$ for $|i|$ large, and summing over i and $n = 0, \dots, N-1$ where $N\Delta t = T$, we find that

$$\begin{aligned}
 (3.18) \quad l(u_{\Delta t}, c) &:= \sum_{i,n} \left[(\eta_i^{n+1} - \eta_i^n) \varphi_i^n h \right. \\
 &\quad + (q^{\text{EO}}(k_{i+1/2}, u_i^n, u_{i+1}^n) - q^{\text{EO}}(k_{i-1/2}, u_{i-1}^n, u_i^n)) \varphi_i^n \Delta t \\
 &\quad \left. + \text{sign}(u_i^{n+1} - c) (f(k_{i+1/2}, c) - f(k_{i-1/2}, c)) \varphi_i^n \Delta t \right] \\
 &= l_1 + l_2 + l_3 \leq 0.
 \end{aligned}$$

We also find that

$$(3.19) \quad \lambda_\varepsilon(u_{\Delta t}, c) = \sum_{i,n} \left[(\eta_i^{n+1} - \eta_i^n) \int_{x_{i-1/2}}^{x_{i+1/2}} \varphi(x, t_n) dx \right.$$

$$(3.20) \quad \left. + (q(k_{i+1/2}, u_{i+1}^n) - q(k_{i-1/2}, u_i^n)) \int_{t_n}^{t_{n+1}} \varphi(x_i, t) dt \right.$$

$$(3.21) \quad \left. + (q(k_{i+1/2}, u_{i+1}^n) - q(k_{i+1/2}, u_i^n)) \int_{t_n}^{t_{n+1}} (\varphi(x_{i+1/2}, t) - \varphi(x_i, t)) dt \right.$$

$$\begin{aligned}
 (3.22) \quad &\left. + \text{sign}(u_i^n - c) (f(k_{i+1/2}, c) - f(k_{i-1/2}, c)) \int_{t_n}^{t_{n+1}} \varphi(x_i, t) dt \right] \\
 &=: \lambda_1 + \lambda_{2,1} + \lambda_{2,2} + \lambda_3.
 \end{aligned}$$

Since $l(u_{\Delta t}, c) \leq 0$,

$$\lambda_\varepsilon(u_{\Delta t}, u) \leq |\lambda_\varepsilon(u_{\Delta t}, u) - l(u_{\Delta t}, u)| \leq |\lambda_1 - l_1| + |\lambda_{2,1} - l_2| + |\lambda_3 - l_3| + |\lambda_{2,2}|.$$

First we note that

$$|\lambda_{2,2}| \leq L_u \sum_{i,n} \int_{x_i}^{x_{i+1/2}} \int_{t_n}^{t_{n+1}} |\delta'_\varepsilon(x-y)| \delta_\varepsilon(t-s) dt dx |u_{i+1}^n - u_i^n|$$

and

$$(3.23) \quad \iint_{\Pi_T} |\lambda_{2,2}| ds dy \leq \frac{L_u T h}{\varepsilon} |u_{\Delta t}|_{BV(\mathbb{R})}.$$

We choose the numbers φ_i^n as

$$\varphi_i^n = \frac{1}{\Delta t h} \int_{x_{i-1/2}}^{x_{i+1/2}} \int_{t_n}^{t_{n+1}} \varphi(x, t) dt dx.$$

Using this we find that

$$\begin{aligned}
 |\lambda_1 - l_1| &\leq \sum_{i,n} |\eta_i^{n+1} - \eta_i^n| \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} |\varphi(x, t) - \varphi(x, t_n)| dx dt \\
 &\leq \sum_{i,n} |\eta_i^{n+1} - \eta_i^n| \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} |\varphi_t| dx dt
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 (3.24) \quad \iint_{\Pi_T} |\lambda_1 - l_1| ds dy &\leq \sum_{i,n} |\eta_i^{n+1} - \eta_i^n| \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} \iint |\delta'_\varepsilon(t-s)| \delta_\varepsilon(x-y) ds dy dx dt \\
 &\leq \sum_{i,n} |\eta_i^{n+1} - \eta_i^n| C \frac{\Delta t h}{\varepsilon} \\
 &\leq C \frac{\Delta t}{\varepsilon}.
 \end{aligned}$$

We continue with

$$\begin{aligned}
|\lambda_{2,1} - l_2| &\leq \sum_{i,n} \left[\int_{t_n}^{t_{n+1}} \varphi(x_i, t) dt \times \left| \left(q(k_{i+1/2}, u_{i+1}^n) - q^{\text{EO}}(k_{i+1/2}, u_i^n, u_{i+1}^n) \right) \right. \right. \\
&\quad \left. \left. - \left(q(k_{i-1/2}, u_i^n) - q^{\text{EO}}(k_{i-1/2}, u_{i-1}^n, u_i^n) \right) \right| \right. \\
&\quad \left. + \left| \int_{t_n}^{t_{n+1}} \varphi(x_i, t) dt - \varphi_i^n \Delta t \right| \left| q^{\text{EO}}(k_{i+1/2}, u_i^n, u_{i+1}^n) - q^{\text{EO}}(k_{i-1/2}, u_{i-1}^n, u_i^n) \right| \right] \\
&+ \sum_{i,n} \left[\left| q(k_{i+1/2}, u_{i+1}^n) - q^{\text{EO}}(k_{i+1/2}, u_i^n, u_{i+1}^n) \right| \int_{t_n}^{t_{n+1}} \int_{x_i}^{x_{i+1}} |\varphi_x| dx dt \right. \\
&\quad \left. + \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} |\varphi_x| dx dt \left| q^{\text{EO}}(k_{i+1/2}, u_i^n, u_{i+1}^n) - q^{\text{EO}}(k_{i-1/2}, u_{i-1}^n, u_i^n) \right| \right] \\
&\leq \sum_{i,n} \left[L_u \int_{t_n}^{t_{n+1}} \int_{x_i}^{x_{i+1}} |\varphi_x| dx dt |u_{i+1}^n - u_i^n| \right. \\
&\quad \left. + C \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} |\varphi_x| dx dt \left\{ |k_{i+1/2} - k_{i-1/2}| + |u_i^n - u_{i-1}^n| + |u_{i+1}^n - u_i^n| \right\} \right].
\end{aligned}$$

Consequently

$$(3.25) \quad \iint_{\Pi_T} |\lambda_{2,1} - l_2| dy ds \leq C \left(|u_{\Delta t}|_{BV(\mathbb{R})} + |k|_{BV(\mathbb{R})} \right) \frac{h}{\varepsilon} \leq C \frac{h}{\varepsilon}.$$

Finally we estimate

$$\begin{aligned}
|\lambda_3 - l_3| &\leq \sum_{i,n} \left[\left| f(k_{i+1/2}, c) - f(k_{i-1/2}, c) \right| \times \right. \\
&\quad \left. \frac{1}{h} \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} |\varphi(x_i, t) - \varphi(x, t) + \varphi(x, t) - \varphi(x, t - \Delta t)| dx dt \right. \\
&\quad \left. + \sum_i \left| f(k_{i+1/2}, c) - f(k_{i-1/2}, c) \right| \left\{ \int_0^{\Delta t} \varphi(x_i, t) dt + \Delta t \varphi_i^{N-1} \right\} \right] \\
&\leq L_k \sum_{i,n} \left[\left| k_{i+1/2} - k_{i-1/2} \right| \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} h |\varphi_x| + \Delta t |\varphi_t| dx dt \right. \\
&\quad \left. + L_k \sum_i \left| k_{i+1/2} - k_{i-1/2} \right| \left\{ \int_0^{\Delta t} \varphi(x_i, t) dt + \Delta t \varphi_i^{N-1} \right\} \right].
\end{aligned}$$

Therefore

$$\begin{aligned}
\iint_{\Pi_T} |\lambda_3 - l_3| ds dy &\leq L_k \sum_{i,n} \left| k_{i+1/2} - k_{i-1/2} \right| \frac{h^2 \Delta t + h \Delta t^2}{\varepsilon} \\
&\quad + \sum_i \left| k_{i+1/2} - k_{i-1/2} \right| C \Delta t \\
(3.26) \quad &\leq C |k|_{BV(\mathbb{R})} \left(\frac{h^2 + h \Delta t}{\varepsilon} + \Delta t \right).
\end{aligned}$$

Collecting the bounds (3.23), (3.24), (3.25) and (3.26) we find that

$$(3.27) \quad \Lambda_\varepsilon(u_{\Delta t}, u) \leq C \left(\Delta t + \frac{h + \Delta t + h^2 + h \Delta t}{\varepsilon} \right),$$

for some constant C not depending on Δt or h . Since we assume that u_0 has bounded variation,

$$\|u(\cdot, 0) - u_{\Delta t}(\cdot, 0)\|_{L^1(\mathbb{R})} \leq Ch,$$

and using this in (3.17), and using $h = \Delta t/\lambda$ we arrive at the inequality

$$(3.28) \quad \|u(\cdot, T) - u_{\Delta t}(\cdot, T)\|_{L^1(\mathbb{R})} \leq C \left(\varepsilon + \frac{\Delta t}{\varepsilon} \right),$$

which is minimized by setting $\varepsilon = \sqrt{\Delta t}$.

The main result of this section is summed up in the following theorem, which is stated for multi-dimensional equations:

Theorem 3.1. *Assume that f and k satisfy (2.2) and (2.3), respectively. Moreover, assume that u_0 is a function in $L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d) \cap BV(\mathbb{R}^d)$. Let u be the unique entropy solution of (3.1). If the CFL condition (4.15) holds, then there exists a constant C , depending on k , k_{x_i} , u_0 , f and T , but not on Δt , such that*

$$(3.29) \quad \|u_{\Delta t}(\cdot, T) - u(\cdot, T)\|_{L^1(\mathbb{R}^d)} \leq C\sqrt{\Delta t},$$

where the Engquist-Osher approximate solution $u_{\Delta t}$ is build from (3.3) and (3.5).

Remark 3.1. The assumptions on $k = (k^1, \dots, k^d)$ in Theorem 3.1 are (slightly) less restrictive than those used in [1, 7, 6, 21] for finite volume methods.

4. DIFFERENCE APPROXIMATIONS: THE DEGENERATE PARABOLIC EQUATION

In this section we analyse the Engquist-Osher scheme for the degenerate parabolic equation (1.1). Again, we shall assume that u_0 has compact support so that all subsequent sums over I are finite. To obtain results for the general case, we can use the stability result in Theorem 2.1.

Let $\lambda = \Delta t/h$ (as usual) and $\mu = \Delta t/h^2$, then this the scheme reads

$$(4.1) \quad \begin{aligned} u_I^{n+1} &= u_I^n - \lambda \sum_{i=1}^d \widehat{\sum}_i D_i f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}, u_I \right) + \mu \sum_{i=1}^d D_i^2 A(u_{I-e_i}^n) \\ &=: G_I(u^n), \end{aligned}$$

where D_i denotes the usual upwind difference operator, see (3.11). Let $u_{\Delta t}$ be the piecewise constant function defined by (4.1) and (3.5).

As a starting point we assume that the following CFL condition holds

$$(4.2) \quad \text{CFL} = \lambda \sum_{i=1}^d \sup_{k, u} |\partial_u f_i(k, u)| + 2\mu d \sup_u A'(u) \leq 1.$$

Remark 4.1. The CFL condition (4.2) will be sufficient to establish the convergence of the sequence $\{u_{\Delta t}\}_{\Delta t > 0}$ and moreover that a limit point u of this sequence satisfies (D.1), (D.2), and (D.4). However, to prove that u obeys (D.3), we shall later need a slightly stronger CFL condition (see (4.15) below).

Now it is easy to see that the CFL condition (4.2) implies that $\frac{\partial G_I}{\partial u_J^2} \geq 0$ for all J and the scheme (4.1) is monotone. In the same manner as the bounds (3.9), (3.10), and (3.13), we show that

$$(4.3) \quad \|u_{\Delta t}(\cdot, t)\|_{L^\infty(\mathbb{R}^d)} \leq C, \quad \|u_{\Delta t}(\cdot, t)\|_{L^1(\mathbb{R}^d)} \leq C, \quad |u_{\Delta t}(\cdot, t)|_{BV(\mathbb{R}^d)} \leq C, \quad \forall t \in (0, T).$$

for some constant C not depending on Δt . To show compactness of the scheme, we must also show that $u_{\Delta t} \in C(0, T; L^1(\mathbb{R}^d))$ uniformly in Δt . In order to do this, we use the Kruřkov interpolation lemma (Lemma 2.4). Let $\varphi(x)$ be a test function and set $\varphi_I = \varphi(x_I)$. Let $D_t X_I^n = X_I^{n+1} - X_I^n$

for any X_I^n . From (4.1) we find that

$$\begin{aligned} \sum_I D_t u_I^n \varphi_I h^d &= \sum_I \lambda \sum_{i=1}^d \widehat{\sum}_i f_i^{\text{EO}}(k_{J-e_i/2}, u_{I-e_i}^n, u_I^n) D_i \varphi_{I-e_i} h^d + \mu \sum_{i=1}^d D_i A(u_I^n) D_i \varphi_{I-e_i} h^d \\ &\leq C \Delta t \|\nabla \varphi\|_{L^\infty(\mathbb{R}^d)} \left(\sum_I \widehat{\sum}_i \sum_{i=1}^d |f_i^{\text{EO}}(k_{J-e_i/2}, u_{I-e_i}^n, u_I^n)| h^d \right. \\ &\quad \left. + \sum_I \sum_{i=1}^d |D_i A(u_I^n)| h^{d-1} \right) \end{aligned}$$

In view of the uniform L^1 and BV bounds in (4.3), an application of Lemma 2.4 gives

$$(4.4) \quad \|u_{\Delta t}(\cdot, t_1) - u_{\Delta t}(\cdot, t_2)\|_{L^1(\mathbb{R}^d)} \leq C \sqrt{|t_1 - t_2|},$$

for some constant C not depending on Δt . By Lemma 2.2, the sequence $\{u_{\Delta t}\}_{\Delta t > 0}$ is compact in $L^1(\Pi_T)$ and any limit point will satisfy **(D.1)** and **(D.4)**.

We establish an cell entropy inequality for the scheme (4.1) in the same way as in the hyperbolic case. A straightforward modification of the arguments leading to equation (3.15) yields

$$\begin{aligned} |u_I^{n+1} - c| &\leq |u_I^n - c| - \lambda \sum_{i=1}^d \widehat{\sum}_i \left[q_i^{\text{EO}}(k_{J+e_i/2}^i, u_I^n, u_{I+e_i}) - q_i^{\text{EO}}(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I) \right] \\ (4.5) \quad &\quad - \lambda \sum_{i=1}^d \widehat{\sum}_i \text{sign}(u_I^{n+1} - c) D_i f_i(k_{J-e_i/2}^i, c) \\ &\quad + \mu \sum_{i=1}^d D_i^2 |A(u_{I-e_i}^n) - A(c)|. \end{aligned}$$

Consequently, any limit point of $\{u_{\Delta t}\}_{\Delta t > 0}$ will satisfy the entropy condition **(D.2)**.

It remains to show that a limit u of $\{u_{\Delta t}\}_{\Delta t > 0}$ satisfies **(D.3)**. This will be done by deriving a so-called weak BV estimate [7, 21, 1, 22].

Multiplying (4.1) by $u_I^n h^d$, and summing over I , we find that

$$\begin{aligned} \sum_I u_I^n D_t u_I^n h^d + \Delta t \sum_{i=1}^d \widehat{\sum}_i u_I^n \left(f_i^{\text{EO}}(k_{J+e_i/2}^i, u_I^n, u_{I+e_i}^n) - f_i^{\text{EO}}(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n) \right) h^{d-1} \\ + \mu \sum_{i=1}^d D_i A(u_{I-e_i}^n) D_i u_{I-e_i}^n \\ = -\Delta t \sum_I \sum_{i=1}^d \widehat{\sum}_i u_I^n \left(f_i^{\text{EO}}(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n) - f_i^{\text{EO}}(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n) \right) h^{d-1}. \end{aligned}$$

We can write

$$u_I^n D_t u_I^n = \frac{1}{2} \left(D_t (u_I^n)^2 - (D_t u_I^n)^2 \right),$$

and we also have that

$$D_i A(u_{I-e_i}^n) D_i u_{I-e_i}^n \geq \frac{(D_i A(u_{I-e_i}^n))^2}{\max_u A'(u)}$$

since $A'(u) \geq 0$. Using these observations, we find that

$$\begin{aligned}
 (4.6) \quad & \frac{\Delta t h^d}{\max_u A'(u)} \sum_I \sum_{i=1}^d \left(\frac{D_i A(u_{I-e_i}^n)}{h} \right)^2 \\
 & + \Delta t \sum_I \sum_{i=1}^d \widehat{\sum}_i u_I^n \left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n, u_{I+e_i}^n \right) - f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right) h^{d-1} \\
 & \leq \frac{-h^d}{2} \sum_I \left[D_t (u_I^n)^2 - (D_t u_I^n)^2 \right] \\
 & \quad - \Delta t \sum_I \sum_{i=1}^d \widehat{\sum}_i u_I^n \left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right) h^{d-1}.
 \end{aligned}$$

Before we proceed, we note that

$$f_i^{\text{EO}}(k, v, w) - f_i^{\text{EO}}(k, u, v) = (f_i^-(k, w) - f_i^-(k, v)) + (f_i^+(k, v) - f_i^+(k, u)),$$

where

$$f_i^-(k, u) = \int_0^u \left(\partial_u f_i(k, s) \wedge 0 \right) ds, \quad \text{and} \quad f_i^+(k, u) = \int_0^u \left(\partial_u f_i(k, s) \vee 0 \right) ds.$$

Thus we can write inequality (4.6) as

$$\begin{aligned}
 (4.7) \quad & \frac{\Delta t h^d}{\max_u A'(u)} \sum_I \sum_{i=1}^d \left(\frac{D_i A(u_{I-e_i}^n)}{h} \right)^2 \\
 (4.8) \quad & + \Delta t h^{d-1} \sum_I \widehat{\sum}_i \sum_{i=1}^d \left[u_I^n \left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right) \right. \\
 & \quad \left. + u_I^n \left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right) \right] \\
 (4.9) \quad & \leq \frac{-h^d}{2} \sum_I \left[D_t (u_I^n)^2 - (D_t u_I^n)^2 \right] + C \Delta t \sum_I \sum_{i=1}^d \left| D_i k_{I-e_i}^i \right| h^{d-1},
 \end{aligned}$$

for some constant C . The sum in (4.8) can be analyzed further by introducing the functions

$$\mathcal{F}_i^\pm(k, u) = \int_0^u s \partial_u f^\pm(k, s) ds.$$

Then an integration by parts reveals that

$$\mathcal{F}_i^\pm(k, b) - \mathcal{F}_i^\pm(k, a) = b \left(f_i^\pm(k, b) - f_i^\pm(k, a) \right) - \int_a^b \left(f_i^\pm(k, s) - f_i^\pm(k, a) \right) ds.$$

Therefore

$$\begin{aligned}
(4.10) \quad & u_I^n \left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right) \\
&= \mathcal{F}_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - \mathcal{F}_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \\
&\quad + \int_{u_{I-e_i}^n}^{u_I^n} \left(f_i^+ \left(k_{J+e_i/2}^i, s \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right) ds,
\end{aligned}$$

$$\begin{aligned}
(4.11) \quad & u_I^n \left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right) \\
&= \mathcal{F}_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - \mathcal{F}_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \\
&\quad - \int_{u_{I+e_i}^n}^{u_I^n} \left(f_i^- \left(k_{J+e_i/2}^i, s \right) - f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) \right) ds.
\end{aligned}$$

Consequently (4.8) can be written

$$\begin{aligned}
& \Delta t h^{d-1} \sum_I \sum_{i=1}^d \widehat{\sum}_i \left[\mathcal{F}_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - \mathcal{F}_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right. \\
& \quad + \int_{u_{I-e_i}^n}^{u_I^n} \left(f_i^+ \left(k_{J+e_i/2}^i, s \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right) ds, \\
& \quad + \mathcal{F}_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - \mathcal{F}_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \\
& \quad \left. - \int_{u_{I+e_i}^n}^{u_I^n} \left(f_i^- \left(k_{J+e_i/2}^i, s \right) - f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) \right) ds \right].
\end{aligned}$$

We also have that \mathcal{F}_i^\pm is locally Lipschitz continuous in k as

$$\left| \mathcal{F}_i^\pm(k_1, u) - \mathcal{F}_i^\pm(k_2, u) \right| = \left| \int_0^u s \partial_u (f_i^\pm(k_1, s) - f_i^\pm(k_2, s)) ds \right| \leq \max_{k, u} |\partial_{uk} f_i| |u| |k_1 - k_2|.$$

we obtain

$$\begin{aligned}
(4.12) \quad & \left| \sum_I \sum_{i=1}^d \widehat{\sum}_i \left[\mathcal{F}_i^\pm \left(k_{J+e_i/2}^i, u_I^n \right) - \mathcal{F}_i^\pm \left(k_{J-e_i/2}^i, u_I^n \right) \right] h^{d-1} \right| \\
& \leq L_{uk} \max_t \|u_{\Delta t}(\cdot, t)\|_{L^\infty(\mathbb{R}^d)} \sum_I \sum_{i=1}^d |D_i k_{J-e_i}^i| h^{d-1},
\end{aligned}$$

which is bounded uniformly in Δt . To bound the terms involving integrals, we need the following technical lemma (whose easy proof can be found in [22]):

Lemma 4.1. *Let $h : \mathbb{R} \rightarrow \mathbb{R}$ be a monotone, Lipschitz continuous function, with a Lipschitz constant L_h . Then we have*

$$\left| \int_a^b (h(\xi) - h(a)) d\xi \right| \geq \frac{1}{2L_h} (h(b) - h(a))^2, \quad \forall a, b \in \mathbb{R}.$$

Applying this to f_i^\pm we find that

$$\begin{aligned} & \int_{u_{I-e_i}^n}^{u_I^n} \left(f_i^+ \left(k_{J+e_i/2}^i, s \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right) ds \\ & \geq \frac{1}{2 \max_u |\partial_u f(k, u)|} \left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right)^2 \\ & - \int_{u_{I+e_i}^n}^{u_I^n} \left(f_i^- \left(k_{J+e_i/2}^i, s \right) - f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) \right) ds \\ & \geq \frac{1}{2 \max_u |\partial_u f(k, u)|} \left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right)^2. \end{aligned}$$

The above and (4.6) imply that

(4.13)

$$\begin{aligned} & \frac{\Delta t h^d}{\max_u A'(u)} \sum_I \sum_{i=1}^d \left(\frac{D_i A(u_{I-e_i}^n)}{h} \right)^2 \\ & + \frac{\Delta t h^{d-1}}{2 \max_{u,k} |\partial_u f(k, u)|} \sum_I \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right)^2 \right. \\ & \quad \left. + \left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right)^2 \right] \\ & \leq \frac{-h^d}{2} \sum_I \left[D_t (u_I^n)^2 - (D_t u_I^n)^2 \right] + C \Delta t, \end{aligned}$$

where the constant C does not depend on Δt . Furthermore, using the definition of the scheme, (4.1), and the inequality $(a+b)^2 \leq 2(a^2+b^2)$, we find that

$$\begin{aligned} & \frac{1}{2} (D_t u_I^n)^2 \leq 2\lambda^2 \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_I^n, u_{I+e_i}^n \right) - f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right)^2 \right. \\ & \quad \left. + \left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right)^2 \right] \\ & \quad + 2\mu^2 \sum_{i=1}^d \left[(D_i A(u_I^n))^2 + (D_i A(u_{I-e_i}^n))^2 \right] \\ (4.14) \quad & \leq 4\lambda^2 \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right)^2 \right. \\ & \quad \left. + \left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right)^2 \right] \\ & \quad + 2\lambda^2 \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right)^2 \right. \\ & \quad \left. + 2\mu^2 \sum_{i=1}^d \left[(D_i A(u_I^n))^2 + (D_i A(u_{I-e_i}^n))^2 \right] \right] \end{aligned}$$

In what follows, we assume the following strengthened CFL condition

$$(4.15) \quad \text{CFL}_\varepsilon := 8\lambda \max_{i,k,u} |\partial_u f_i(k, u)| + 4\mu \max_u A'(u) \leq 1 - \varepsilon,$$

where $\varepsilon \in (0, 1)$ is given a real number. Note that if $A' \equiv 0$, i.e., in the hyperbolic case, (4.15) implies $\text{CFL}_\varepsilon \in (0, \frac{1}{8})$, which should be compared with the usual $\text{CFL} \in (0, 1)$, see (4.2). The new

CFL condition implies in particular that

$$4\lambda^2 = 4\lambda \frac{\Delta t}{h} = 8\lambda \max_{k,u,i} |\partial_u f_i(k,u)| \frac{\Delta t}{2h \max_{k,u,i} |\partial_u f_i(k,u)|} \leq \frac{\Delta t(1-\varepsilon)}{2h \max_{k,u,i} |\partial_u f_i(k,u)|},$$

$$2\mu^2 = 2\mu \frac{\Delta t}{h^2} = 4 \max_u A'(u) \frac{\Delta t}{2h^2 \max_u A'(u)} \leq \frac{\Delta t(1-\varepsilon)}{2h^2 \max_u A'(u)},$$

and therefore

$$(4.16) \quad \frac{1}{2} (D_t u_I^n)^2 \leq \frac{\Delta t(1-\varepsilon)}{2h \max_{k,u,i} |\partial_u f_i(k,u)|} \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right)^2 \right. \\ \left. + \left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right)^2 \right] \\ + \frac{\Delta t(1-\varepsilon)}{2h \max_{k,u,i} |\partial_u f_i(k,u)|} \sum_{i=1}^d \widehat{\sum}_i \left(\psi_i \left(\xi_J, u_{I-e_i}^n, u_I^n \right) D_i k_{J-e_i}^i \right)^2 \\ + \frac{\Delta t(1-\varepsilon)}{2h^2 \max_u A'(u)} \sum_{i=1}^d \left[(D_i A(u_I^n))^2 + (D_i A(u_{I-e_i}^n))^2 \right].$$

Now we multiply the above inequality (4.16) by h^d and sum over I and $n = 0, \dots, N$, and sum (4.13) over n , and add the results to find that

$$(4.17) \quad \frac{\Delta t \varepsilon h^d}{\max_u A'(u)} \sum_{n,I} \sum_{i=1}^d \left(\frac{D_i A(u_{I-e_i}^n)}{h} \right)^2 \\ + \frac{\Delta t h^{d-1} \varepsilon}{2 \max_{i,k,u} |\partial_u f_i(k,u)|} \sum_{n,I} \sum_{i=1}^d \widehat{\sum}_i \left[\left(f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right)^2 \right. \\ \left. + \left(f_i^- \left(k_{J+e_i/2}^i, u_{I+e_i}^n \right) - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) \right)^2 \right] \\ \leq \frac{h^d}{2} \sum_I (u_I^0)^2 + CT \leq \frac{1}{2} \|u_0\|_{L^\infty(\mathbb{R}^d)} \|u_0\|_{L^1(\mathbb{R}^d)} + CT \leq C,$$

for some constant C not depending on Δt . we have the following bound

$$(4.18) \quad \Delta t h^d \sum_{n,I} \sum_{i=1}^d \left(\frac{D_i A(u_I^n)}{h} \right)^2 \leq C$$

for some constant C not depending on Δt .

Next let $I(x)$ be the multi-index such that $x \in \chi_I$. Then we have that $I(x+y) - I(x) =: J = (J_1, \dots, J_d)$, and $|Jh| \leq |y| + h$. Set $K_i = I + (J_1, \dots, J_{i-1}, 0, \dots, 0)$. Using this notation we can write

$$A(u_{\Delta t}(x+y, t)) - A(u_{\Delta t}(x, t)) = A(u_{I(x+y)}^n) - A(u_{I(x)}^n) = \sum_{i=1}^d \sum_{j=1}^{J_i} D_j A(u_{K_i - (j-1)e_j}^n).$$

By the Cauchy-Schwartz inequality

$$\left(A(u_{\Delta t}(x+y, t)) - A(u_{\Delta t}(x, t)) \right)^2 \leq \sum_{i=1}^d |J_i| \sum_{j=1}^{J_i} \left(D_j A(u_{K_i - (j-1)e_j}^n) \right)^2.$$

Hence using (4.18),

$$\begin{aligned}
 & \iint_{\Pi_T} \left(A(u_{\Delta t}(x+y, t)) - A(u_{\Delta t}(x, t)) \right)^2 dt dx \\
 & \leq \Delta t h^d \sum_{n, I} \left(A(u_I^n(x_{I+y})) - A(u_I^n(x_I)) \right)^2 \\
 & \leq \Delta t h^d \sum_{n, I} \sum_{i=1}^d |J_i| \sum_{j=1}^{J_i} \left(D_j A(u_{K_{i-(j-1)e_j}}^n) \right)^2 \\
 & \leq \max_i |J_i| \Delta t h^d \sum_{n, I} \sum_{i=1}^d \sum_{j=1}^{J_i} \sum_{\ell=1}^d \left(D_\ell A(u_{K_{i-(j-1)e_j}}^n) \right)^2 \\
 & \leq \left(\max_i |J_i| \right)^2 d \Delta t h^d \sum_{n, I} \sum_{i=1}^d D_i A(u_I^n) \leq C \left(\max_i |J_i| h \right)^2,
 \end{aligned}$$

where the constant C does not depend on y or h . Noting that $\max_i |J_i| h \leq C(|y| + h)$, we find that

$$(4.19) \quad \|A(u_{\Delta t}(\cdot + y, \cdot)) - A(u_{\Delta t}(\cdot, \cdot))\|_{L^2(\Pi_T)} \leq C(|y| + h).$$

Next, we will use the weak space estimate (4.18) and the difference scheme itself to show that $A(u_{\Delta t})$ is also L^2 continuous in time. Let $n(t)$ denote the integer such that $t \in [t_n, t_{n+1})$. Then we have

$$\begin{aligned}
 & \iint_{\Pi_{T-\tau}} \left(A(u_{\Delta t}(x, t+\tau)) - A(u_{\Delta t}(x, t)) \right)^2 dt dx \\
 & \leq \max_u A'(u) \iint_{\Pi_{T-\tau}} \left(A(u_{\Delta t}(x, t+\tau)) - A(u_{\Delta t}(x, t)) \right) (u_{\Delta t}(x, t+\tau) - u_{\Delta t}(x, t)) dt dx \\
 & = \max_u A'(u) \int_0^{T-\tau} h^d \sum_I \left(A(u_I^{n(t+\tau)}) - A(u_I^{n(t)}) \right) \left(u_I^{n(t+\tau)} - u_I^{n(t)} \right) dt.
 \end{aligned}$$

We denote the above integrand by $B(t)$ and write

$$B(t) = h^d \sum_I \left(A(u_I^{n(t+\tau)}) - A(u_I^{n(t)}) \right) \sum_{n=n(t)}^{n(t+\tau)-1} D_t u_I^n.$$

Then each term in the sum over n above equals

$$\begin{aligned}
 & h^d \sum_I \left(A(u_I^{n(t+\tau)}) - A(u_I^{n(t)}) \right) D_t u_I^n \\
 & = -\Delta t h^{d-1} \sum_I \sum_{i=1}^d \widehat{\sum}_i \left[\left(A(u_I^{n(t+\tau)}) - A(u_I^{n(t)}) \right) \times \left\{ f_i^- \left(k_{J+e_i/2}^i, u_{J+e_i}^n \right) \right. \right. \\
 & \quad \left. \left. - f_i^- \left(k_{J+e_i/2}^i, u_I^n \right) + f_i^+ \left(k_{J+e_i/2}^i, u_I^n \right) - f_i^+ \left(k_{J+e_i/2}^i, u_{I-e_i}^n \right) \right\} \right. \\
 & \quad \left. + \left(A(u_I^{n(t+\tau)}) - A(u_I^{n(t)}) \right) \right. \\
 & \quad \left. \times \left\{ f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right\} \right]
 \end{aligned} \tag{4.20}$$

$$(4.21) \quad \times \left\{ f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) - f_i^{\text{EO}} \left(k_{J-e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right\}$$

$$(4.22) \quad + \Delta t h^{d-2} \sum_I \left(A(u_I^{n(t+\tau)}) - A(u_I^{n(t)}) \right) \sum_{i=1}^d D_i^2 A(u_{I-e_i}^n)$$

We can do a partial summation in (4.20), to find that

$$\begin{aligned}
|(4.20)| &= \Delta t h^{d-1} \left| \sum_{i=1}^d \widehat{\sum}_i D_i \left(A \left(u_{I-e_i}^{n(t+\tau)} \right) - A \left(u_{I-e_i}^{n(t)} \right) \right) f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right| \\
(4.23) \quad &\leq \Delta t h^d \sum_{i=1}^d \widehat{\sum}_i \left(f_i^{\text{EO}} \left(k_{J+e_i/2}^i, u_{I-e_i}^n, u_I^n \right) \right)^2 \\
&\quad \times \left(\left(\frac{D_i A \left(u_{I-e_i}^{n(t+\tau)} \right)}{h} \right)^2 + \left(\frac{D_i A \left(u_{I-e_i}^{n(t)} \right)}{h} \right)^2 \right) \leq C \Delta t,
\end{aligned}$$

since we have uniform control over the L^2 norm of the discrete gradient of $A(u_{\Delta t})$, see (4.18). Since k is of bounded variation,

$$(4.24) \quad |(4.21)| \leq \Delta t C \|k\|_{BV(\mathbb{R}^d)},$$

where C does not depend on Δt . Regarding (4.22) we have that

$$\begin{aligned}
|(4.22)| &= \Delta t h^{d-2} \left| \sum_I \sum_{i=1}^d -D_i A \left(u_{I-e_i}^{n(t+\tau)} \right) D_i A \left(u_{I-e_i}^n \right) + D_i A \left(u_{I-e_i}^{n(t)} \right) A \left(u_{I-e_i}^n \right) \right| \\
(4.25) \quad &\leq \Delta t^2 h^{d-2} \left[\sum_I \sum_{i=1}^d \frac{1}{2} \left(D_i A \left(u_{I-e_i}^{n(t+\tau)} \right) \right)^2 + \frac{1}{2} \left(D_i A \left(u_{I-e_i}^{n(t)} \right) \right)^2 + \left(D_i A \left(u_{I-e_i}^n \right) \right)^2 \right].
\end{aligned}$$

We can write

$$\int_0^{T-\tau} B(t) dt \leq (T-\tau) C n(\tau) \Delta t + \int_0^{T-\tau} \left(\frac{1}{2} B_1(t) + \frac{1}{2} B_2(t) + B_3(t) \right) dt,$$

where C does not depend on Δt , and B_1 , B_2 and B_3 are given by (4.25). Now

$$\begin{aligned}
\int_0^{T-\tau} B_1(t) dt &= \int_0^{T-\tau} \Delta t h^{d-2} \sum_I \sum_{i=1}^d \sum_{n=n(t)}^{n(t)+n(\tau)-1} \left(D_i A \left(u_I^{n(t+\tau)} \right) \right)^2 dt \\
&= \sum_{m=0}^{N-n(\tau)} \Delta t h^{d-2} \sum_I \sum_{i=1}^d \sum_{n=n(t_m)}^{n(t_m)+n(\tau)-1} \left(D_i A \left(u_I^{n(t_m+\tau)} \right) \right)^2 \Delta t \\
&\leq (n(\tau) + 1) \Delta t \Delta t h^{d-2} \sum_n \sum_I \sum_{i=1}^d \left(D_i A \left(u_I^n \right) \right)^2 \\
(4.26) \quad &\leq C(\tau + \Delta t)
\end{aligned}$$

Similarly

$$(4.27) \quad \int_0^{T-\tau} B_2(t) dt \leq C(\tau + \Delta t).$$

Finally

$$\begin{aligned}
\int_0^{T-\tau} B_3(t) dt &\leq \sum_{m=0}^{N-n(\tau)} \Delta t h^{d-2} \sum_{n=m}^{m+n(\tau)-1} \sum_I \sum_{i=1}^d \left(D_i A \left(u_I^n \right) \right)^2 \Delta t \\
&= \Delta t \sum_{k=0}^{n(\tau)-1} \Delta t h^{d-2} \sum_{n=0}^{N-n(\tau)} \sum_I \sum_{i=1}^d \left(D_i A \left(u_I^{n+k} \right) \right)^2 \\
(4.28) \quad &\leq C(\tau + \Delta t),
\end{aligned}$$

where C does not depend on Δt . Using the bounds (4.26)-(4.28), we find that

$$(4.29) \quad \|A(u_{\Delta t}(\cdot, \cdot + \tau)) - A(u_{\Delta t}(\cdot, \cdot))\|_{L^2(\mathbb{R}^d \times (0, T-\tau))} \leq C \sqrt{\Delta t + \tau}.$$

In view Lemma 2.3, we conclude that

$$A(u_{\Delta t}) \rightarrow \bar{A} \text{ strongly in } L^2_{\text{loc}}(\mathbb{R} \times (0, T)) \text{ as } \Delta t \downarrow 0 \text{ and } \bar{A} \in L^2(0, T; H^1(\mathbb{R})).$$

Equipped with the strong convergence $u_{\Delta t} \rightarrow u$ a.e., we conclude immediately that $\bar{A} = A(u)$ and thus (D.3) holds.

We sum up our results in the following theorem:

Theorem 4.1. *Assume that A , f , and k satisfy (2.1), (2.2), and (2.3), respectively. Furthermore, assume that u_0 is a function in $L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d) \cap BV(\mathbb{R}^d)$. If the CFL condition (4.15) holds, then the piecewise constant approximate solutions (3.5) generated by the Engquist-Osher scheme (4.1) converge to the unique entropy solution of (1.1).*

In the special case without coefficients, i.e., $k = 1$, we can use our techniques to prove existence of an entropy solution without necessarily having initial data in $BV(\mathbb{R}^d)$. This can be done as follows. Assuming that $u_0 \in L^\infty(\mathbb{R}^d) \cap L^1(\mathbb{R}^d)$, we study the problem

$$(4.30) \quad u_t + \operatorname{div} f(u) = \Delta A(u), \quad u(x, 0) = u_0(x),$$

where f and A are as before. We obtain the two first bounds in (4.3) as before. Fixing $\varepsilon \in \mathbb{R}^d$, we have

$$\|u_{\Delta t}(\cdot + \varepsilon, t) - u_{\Delta t}(\cdot, t)\|_{L^1(\mathbb{R}^d)} \leq \|u_0(\cdot + \varepsilon) - u_0(\cdot)\|_{L^1(\mathbb{R}^d)} \leq \nu(|\varepsilon|; u_0),$$

since any function in $L^\infty(\mathbb{R}^d) \cap L^1(\mathbb{R}^d)$ has some modulus of continuity and the scheme is now translation invariant. Then we use Kruřkov's interpolation lemma (Lemma 2.4) to show that $u_{\Delta t}$ also has a modulus of continuity in time. Next, we use the L^1 compactness lemma (Lemma 2.2) to show that $\{u_{\Delta t}\}_{\Delta t > 0}$ has a subsequence that converges strongly in L^1 to a function that satisfies (D.1), (D.4), and the entropy condition (D.3). To finally show that the limit satisfies (D.3), note that to obtain the crucial estimates (4.19) and (4.29) we did not use a BV bound on $u_{\Delta t}$. Thus we have shown the following theorem:

Theorem 4.2. *Assume that the function u_0 is in $L^\infty(\mathbb{R}^d) \cap L^1(\mathbb{R}^d)$. If the CFL condition (4.15) holds, then the piecewise constant approximate solutions (3.5) generated by the Engquist-Osher scheme (4.1) converge to the unique entropy solution of (4.30).*

REFERENCES

- [1] M. Afif and B. Amaziane. Convergence of finite volume schemes for a degenerate convection-diffusion equation arising in two-phase flow in porous media. Preprint, 1999.
- [2] F. Bouchut, F. R. Guarguaglini, and R. Natalini. Diffusive BGK approximations for nonlinear multidimensional parabolic equations. *Indiana Univ. Math. J.* To appear.
- [3] R. Bürger, S. Evje, and K. H. Karlsen. On strongly degenerate convection-diffusion problems modeling sedimentation-consolidation processes. *J. Math. Anal. Appl.*, 247(2):517–556, 2000.
- [4] M. C. Bustos, F. Concha, R. Bürger, and E. M. Tory. *Sedimentation and Thickening: Phenomenological Foundation and Mathematical Theory*. Kluwer Academic Publishers, Dordrecht, The Netherlands, 1999.
- [5] J. Carrillo. Entropy solutions for nonlinear degenerate problems. *Arch. Rational Mech. Anal.*, 147(4):269–361, 1999.
- [6] C. Chainais-Hillairet. Finite volume schemes for a nonlinear hyperbolic equation. Convergence towards the entropy solution and error estimate. *M2AN Math. Model. Numer. Anal.*, 33(1):129–156, 1999.
- [7] S. Champier, T. Gallouët, and R. Herbin. Convergence of an upstream finite volume scheme for a nonlinear hyperbolic equation on a triangular mesh. *Numer. Math.*, 66(2):139–157, 1993.
- [8] B. Cockburn, F. Coquel, and P. Le Floch. An error estimate for finite volume methods for multidimensional conservation laws. *Math. Comp.*, 63(207):77–103, 1994.
- [9] B. Cockburn, F. Coquel, and P. G. LeFloch. Convergence of the finite volume method for multidimensional conservation laws. *SIAM J. Numer. Anal.*, 32(3):687–705, 1995.
- [10] B. Cockburn and P.-A. Gremaud. A priori error estimates for numerical methods for scalar conservation laws. I. The general approach. *Math. Comp.*, 65(214):533–573, 1996.
- [11] B. Cockburn and C.-W. Shu. The local discontinuous Galerkin method for time-dependent convection-diffusion systems. *SIAM J. Numer. Anal.*, 35(6):2440–2463 (electronic), 1998.
- [12] M. G. Crandall and A. Majda. Monotone difference approximations for scalar conservation laws. *Math. Comp.*, 34(149):1–21, 1980.
- [13] M. G. Crandall and L. Tartar. Some relations between nonexpansive and order preserving mappings. *Proc. Amer. Math. Soc.*, 78(3):385–390, 1980.
- [14] B. Engquist and S. Osher. One-sided difference approximations for nonlinear conservation laws. *Math. Comp.*, 36(154):321–351, 1981.

- [15] M. S. Espedal and K. H. Karlsen. Numerical solution of reservoir flow models based on large time step operator splitting algorithms. In A. Fasano and H. van Duijn, editors, *Filtration in Porous Media and Industrial Applications*, Lecture Notes in Mathematics. Springer. To appear.
- [16] S. Evje and K. H. Karlsen. Discrete approximations of BV solutions to doubly nonlinear degenerate parabolic equations. *Numer. Math.* To appear.
- [17] S. Evje and K. H. Karlsen. Degenerate convection-diffusion equations and implicit monotone difference schemes. In *Hyperbolic problems: theory, numerics, applications, Vol. I (Zürich, 1998)*, pages 285–294. Birkhäuser, Basel, 1999.
- [18] S. Evje and K. H. Karlsen. Viscous splitting approximation of mixed hyperbolic-parabolic convection-diffusion equations. *Numer. Math.*, 83(1):107–137, 1999.
- [19] S. Evje and K. H. Karlsen. Monotone difference approximations of BV solutions to degenerate convection-diffusion equations. *SIAM J. Numer. Anal.*, 37(6):1838–1860 (electronic), 2000.
- [20] S. Evje and K. H. Karlsen. Second order difference schemes for degenerate convection-diffusion equations. Preprint, Department of Mathematics, University of Bergen, 2000.
- [21] R. Eymard, T. Gallouët, M. Ghilani, and R. Herbin. Error estimates for the approximate solutions of a nonlinear hyperbolic equation given by finite volume schemes. *IMA J. Numer. Anal.*, 18(4):563–594, 1998.
- [22] R. Eymard, T. Gallouët, D. Hilhorst, and Y. Naït Slimane. Finite volumes and nonlinear diffusion equations. *RAIRO Modél. Math. Anal. Numér.*, 32(6):747–761, 1998.
- [23] T. Gimse and N. H. Risebro. Solution of the Cauchy problem for a conservation law with a discontinuous flux function. *SIAM J. Math. Anal.*, 23(3):635–648, 1992.
- [24] A. Harten, J. M. Hyman, and P. D. Lax. On finite-difference approximations and entropy conditions for shocks. *Comm. Pure Appl. Math.*, XXIX:297–322, 1976.
- [25] H. Holden, K. H. Karlsen, and K.-A. Lie. Operator splitting methods for degenerate convection-diffusion equations I: convergence and entropy estimates. In *Stochastic Processes, Physics and Geometry: New Interplays. A Volume in Honor of Sergio Albeverio*. Amer. Math. Soc. To appear.
- [26] H. Holden, K. H. Karlsen, K.-A. Lie, and N. H. Risebro. Operator splitting for nonlinear partial differential equations: An L^1 convergence theory. Preprint (in preparation).
- [27] E. Isaacson and B. Temple. Convergence of the 2×2 Godunov method for a general resonant nonlinear balance law. *SIAM J. Appl. Math.*, 55(3):625–640, 1995.
- [28] K. H. Karlsen and N. H. Risebro. On the uniqueness and stability of entropy solutions of nonlinear degenerate parabolic equations with rough coefficients. Preprint, Department of Mathematics, University of Bergen, 2000.
- [29] C. Klingenberg and N. H. Risebro. Stability of a resonant system of conservation laws modeling polymer flow with gravitation. *J. Differential Equations*. To appear.
- [30] C. Klingenberg and N. H. Risebro. Convex conservation laws with discontinuous coefficients. Existence, uniqueness and asymptotic behavior. *Comm. Partial Differential Equations*, 20(11-12):1959–1990, 1995.
- [31] D. Kröner, S. Noelle, and M. Rokyta. Convergence of higher order upwind finite volume schemes on unstructured grids for scalar conservation laws in several space dimensions. *Numer. Math.*, 71(4):527–560, 1995.
- [32] D. Kröner and M. Rokyta. Convergence of upwind finite volume schemes for scalar conservation laws in two dimensions. *SIAM J. Numer. Anal.*, 31(2):324–343, 1994.
- [33] S. N. Kružkov. Results on the nature of the continuity of solutions of parabolic equations, and certain applications thereof. *Mat. Zametki*, 6:97–108, 1969.
- [34] S. N. Kružkov. First order quasi-linear equations in several independent variables. *Math. USSR Sbornik*, 10(2):217–243, 1970.
- [35] A. Kurganov and E. Tadmor. New high-resolution central schemes for nonlinear conservation laws and convection-diffusion equations. *J. Comput. Phys.*, 160:241–282, 2000.
- [36] N. N. Kuznetsov. Accuracy of some approximative methods for computing the weak solutions of a first-order quasi-linear equation. *USSR Comput. Math. and Math. Phys. Dokl.*, 16(6):105–119, 1976.
- [37] B. J. Lucier. Error bounds for the methods of Glimm, Godunov and LeVeque. *SIAM J. Numer. Anal.*, 22:1074–1081, 1985.
- [38] S. Noelle. Convergence of higher order finite volume schemes on irregular grids. *Adv. Comput. Math.*, 3(3):197–218, 1995.
- [39] M. Oehlberger. A posteriori error estimates for vertex centered finite volume approximations of convection-diffusion-reaction equations. Preprint, Mathematische Fakultät, Albert-Ludwigs-Universität Freiburg, 2000.
- [40] O. A. Oleĭnik. Discontinuous solutions of non-linear differential equations. *Amer. Math. Soc. Transl. Ser. 2*, 26:95–172, 1963.
- [41] S. Osher and E. Tadmor. On the convergence of difference approximations to scalar conservation laws. *Math. Comp.*, 50(181):19–51, 1988.
- [42] É. Rouvre and G. Gagneux. Solution forte entropique de lois scalaires hyperboliques-paraboliques dégénérées. *C. R. Acad. Sci. Paris Sér. I Math.*, 329(7):599–602, 1999.
- [43] A. A. Samarskii, V. A. Galaktionov, S. P. Kurdyumov, and A. P. Mikhailov. *Blow-up in quasilinear parabolic equations*. Walter de Gruyter & Co., Berlin, 1995. Translated from the 1987 Russian original by Michael Grinfeld and revised by the authors.
- [44] R. Sanders. On convergence of monotone finite difference schemes with variable spatial differencing. *Math. Comp.*, 40(161):91–106, 1983.

- [45] B. Temple. Global solution of the Cauchy problem for a class of 2×2 nonstrictly hyperbolic conservation laws. *Adv. in Appl. Math.*, 3(3):335–375, 1982.
- [46] J. Towers. Convergence of a difference scheme for conservation laws with a discontinuous flux. Preprint, Available at the URL <http://www.math.ntnu.no/conservation/>.
- [47] J. Towers. A difference scheme for conservation laws with a discontinuous flux - the nonconvex case. Preprint, Available at the URL <http://www.math.ntnu.no/conservation/>.
- [48] J.-P. Vila. Convergence and error estimates in finite volume schemes for general multidimensional scalar conservation laws. I. Explicit monotone schemes. *RAIRO Modél. Math. Anal. Numér.*, 28(3):267–295, 1994.
- [49] A. I. Vol'pert. The spaces BV and quasi-linear equations. *Math. USSR Sbornik*, 2(2):225–267, 1967.
- [50] A. I. Vol'pert and S. I. Hudjaev. Cauchy's problem for degenerate second order quasilinear parabolic equations. *Math. USSR Sbornik*, 7(3):365–387, 1969.

(Karlsen)

DEPARTMENT OF MATHEMATICS

UNIVERSITY OF BERGEN

JOHS. BRUUNSGT. 12

N-5008 BERGEN, NORWAY

E-mail address: kennethk@math.uib.no

URL: <http://www.mi.uib.no/~kennethk/>

(Risebro)

DEPARTMENT OF MATHEMATICS

UNIVERSITY OF OSLO

P.O. BOX 1053, BLINDERN

N-0316 OSLO, NORWAY

E-mail address: nilshr@math.uio.no

URL: <http://www.math.uio.no/~nilshr/>



Depotbiblioteket



01sd 05 816

